

# Dealing with uncertainty in a real-time knowledge process

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# Outline

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- Knowledge Discovery in Disaster Management
- Real Time and Uncertainty
- Our Approach
- Results

# Knowledge Discovery in Environmental Sciences

## Approaches, tools, environment and facilities for

- Exploring anomalies in geophysical data,
- Scaling up the current analysis techniques.

Behnke et al. 1999

# Knowledge Discovery in Disaster Management

- How to predict storm tracks?
- How to detect fires for a rapid dissemination of warnings?
- How to predict changes in intensity as a storm approaches land?



# Knowledge Discovery in Disaster Management

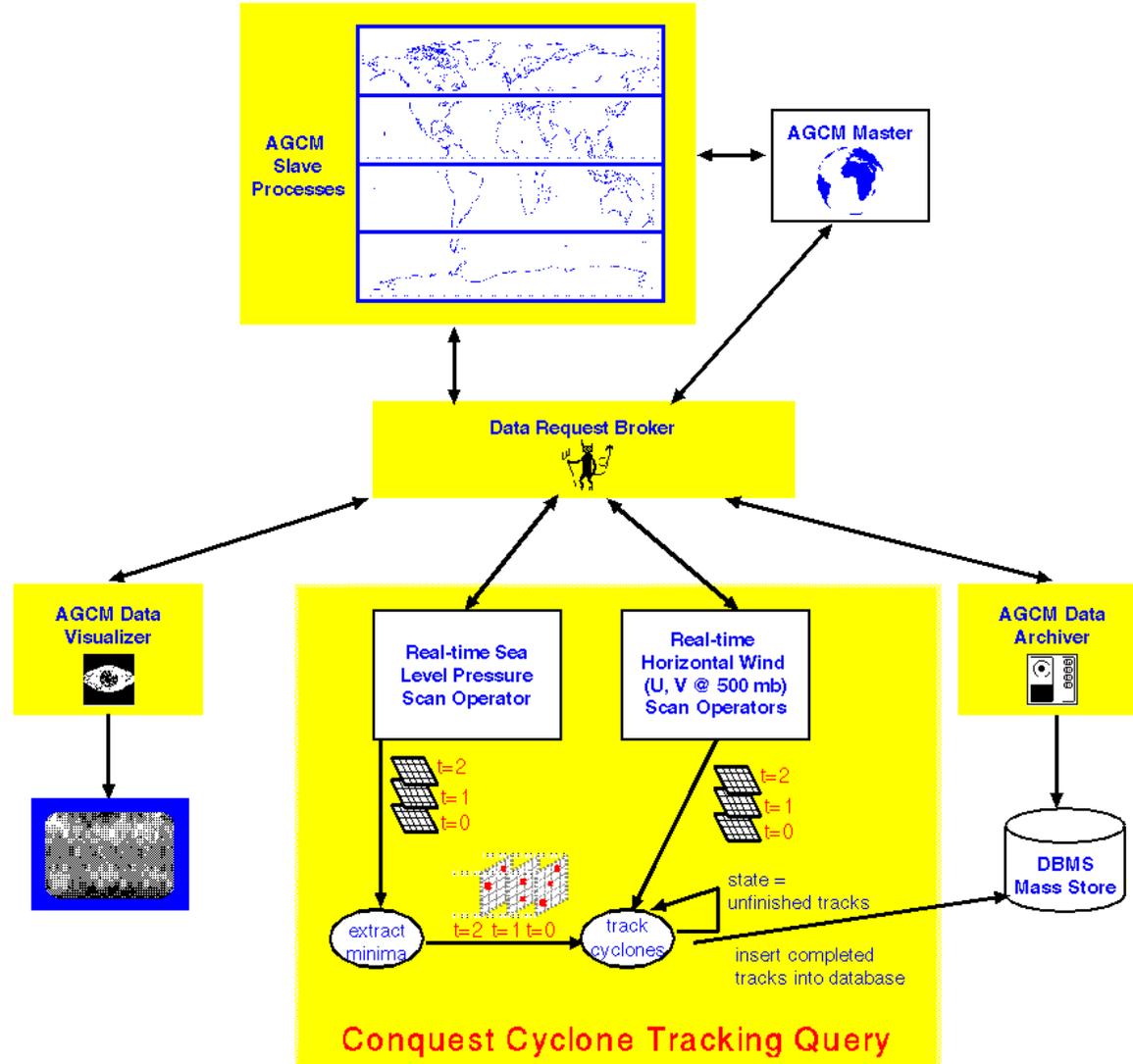
## Real-Time

Everything on line – rapid access

Rapid systematic dissemination of results

# Real Time Data Mining

- Super computing
- GRID



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# Knowledge Discovery in Disaster Management

## Uncertainty

False alarm problems are a major issue for natural hazard warnings due to cost and trust

# Our Approach

## Real-Time

- Assembling the data
- Pre-processing the data
- Data Mining Task
- Interpreting the results



## Uncertainty

- Accuracy
- Efficiency
- Usability

# Accuracy

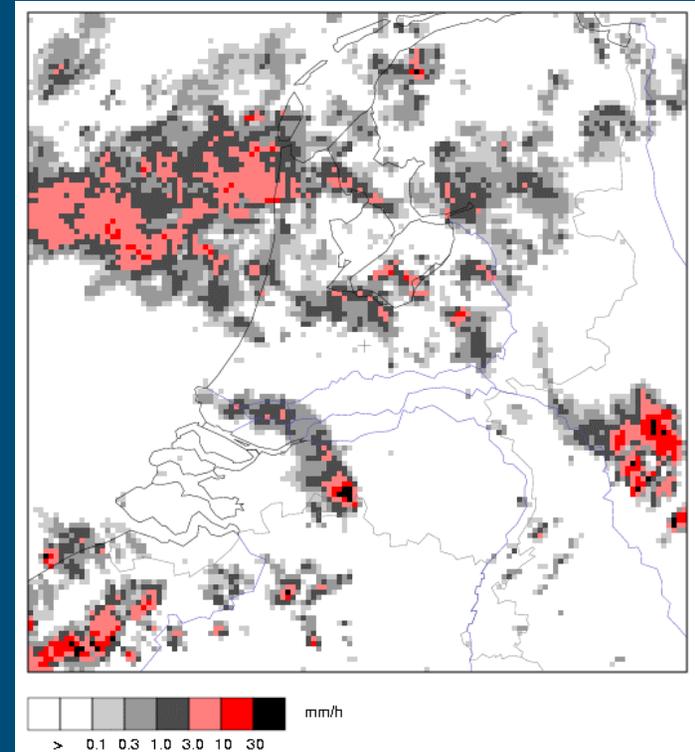
## ■ Pre-Processing:

The observations were clustered using the density based algorithm (Ester et al. 1996, Ester et al. 1998).

- Clusters (patterns) → C,S (confidence, support)
- Consistent patterns (high levels of support) separated from unique patterns (low levels of support - anomaly)

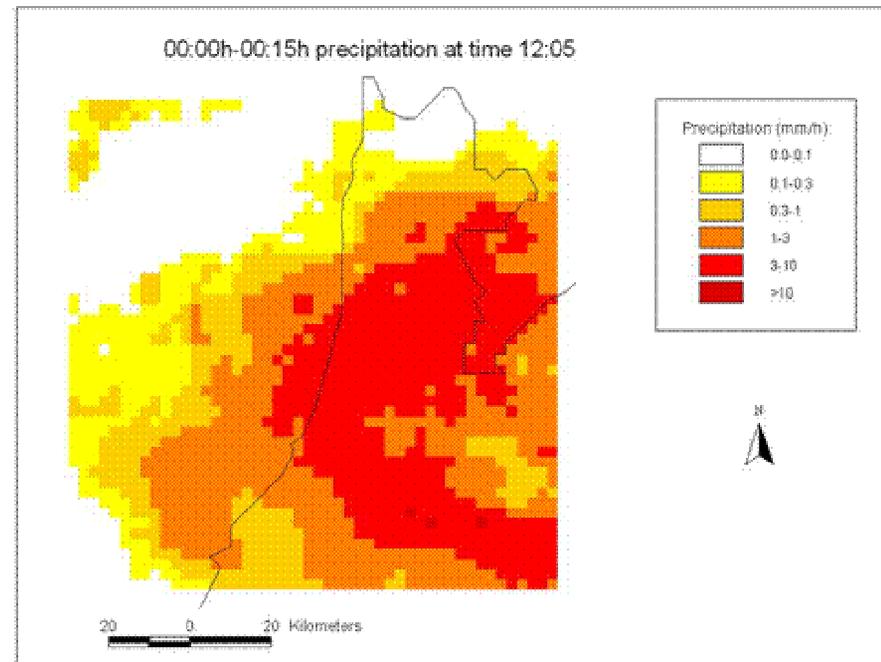
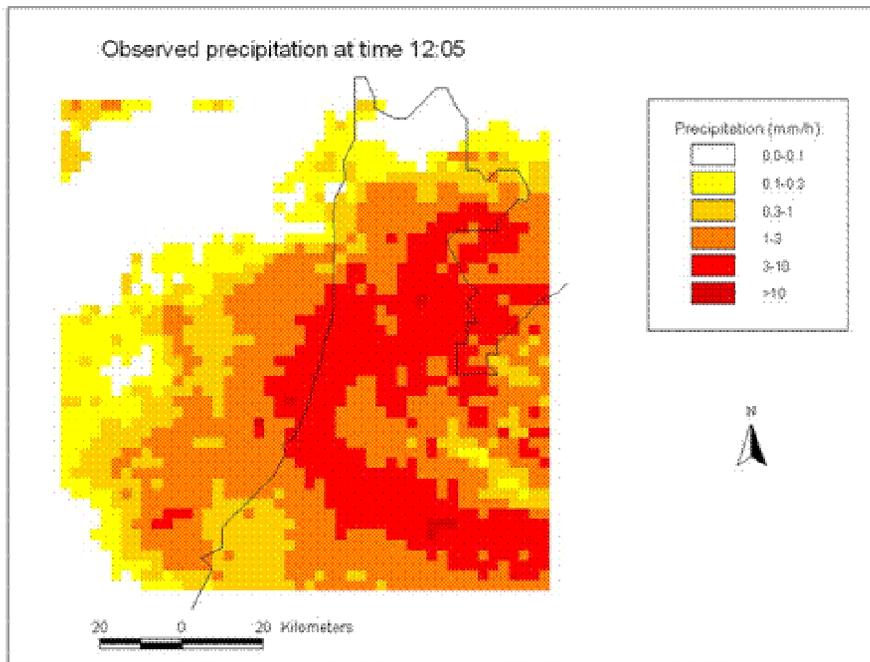
# Target Data Set

- Pseudo – Constant Altitude Plan Position Indicator
- every 5 minutes
- 19 September 2001
- Rainfall of 110 mm



- pCAPPi image of the Netherlands and surrounding area (source: KNMI, 2004)

# Finding the clusters in time



Observed rainfall

Clustered

19 September 2001

# Accuracy

## ■ Data Mining Task:

Prediction of changes in the precipitation clusters using the supervised inductive learning method

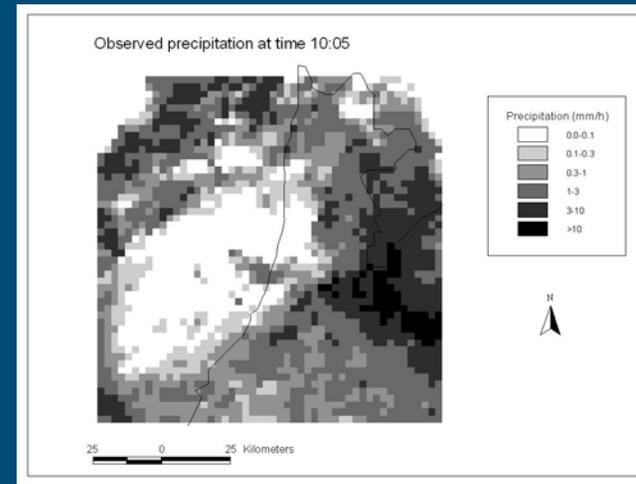
(Rao and Rao 1993).

- Misuse rules
- Anomaly detection rules
- Normal behaviour rules

# Data Mining

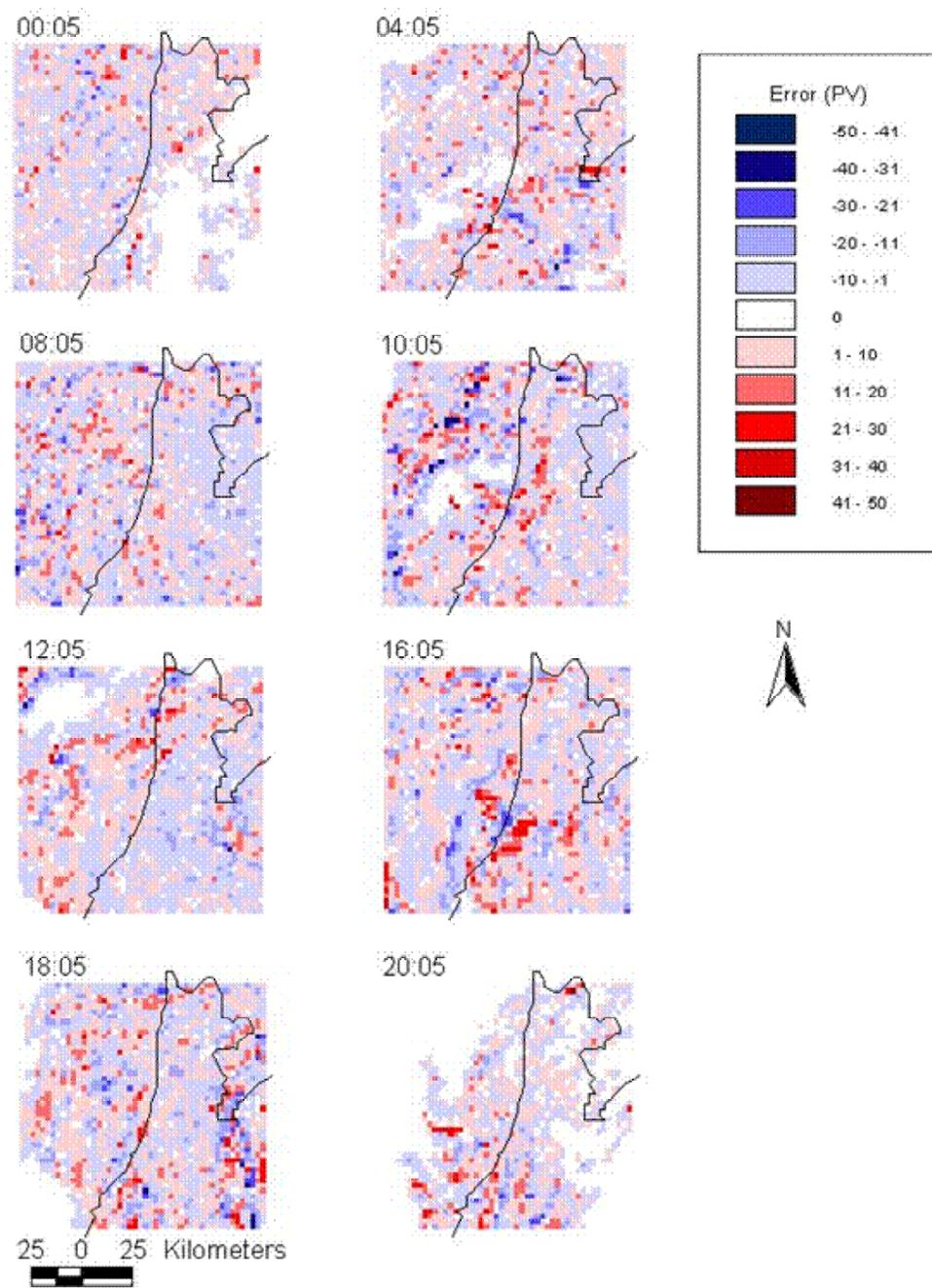
## ■ Within a cluster:

- Observed pixel values – 00:00, 00:15, 00:30 until 11:45
- Predicted pixel values – 00:05, 00:10, 00:20 until 11:40
- Validation – 12:00h until 23:45h



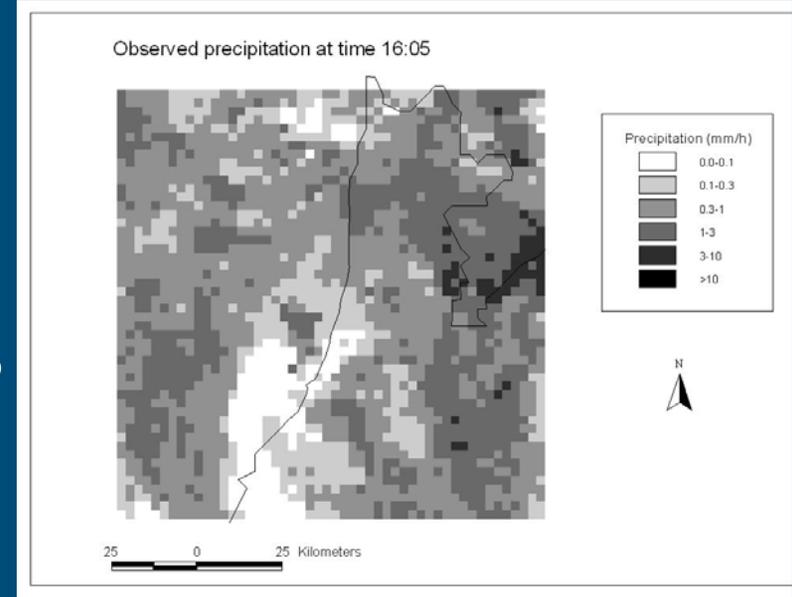
# Results

Error maps obtained from observations between 00:00h-00:15h



# Efficiency

- Computational Costs (time)
- How much does a rule cost?



# Efficiency

- Rules can be computed:
  - From the first observation ..... **Level 1**
  - During the capture of observations ..... **Level 2**
  - At the end of the observations ..... **Level 3**
  - At the end, but requires access to data from potentially many other prior observations ... **Level 4**

# Efficiency

- Cost Model : assigning weights to the levels
  - Level 1 : 1
  - Level 2 : 5
  - Level 3 : 10
  - Level 4 : 100

# Efficiency

- Cost Model : defining multiple rules to generate the training sets.
  - Multiple training sets
  - Precision measures
  - Threshold values

# Results

- This approach can reduce the computational cost by as much as 80% without compromising predictive accuracy.

# Conclusions

- We were capable of correctly estimating the precipitation rates up to 12 hours ahead.
- We achieved an accuracy of 72% within the time interval 12:00h – 12:15h.
- The approach was suitable for mining the temporal dimension, but further studies are required for mining the spatial dimension.
- More research is needed for investigating usability issues.