

Lunchmeeting GIS Technology

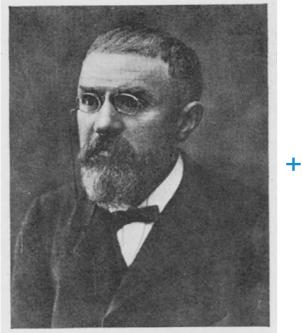
Friday September 1st 12.00-14.00h

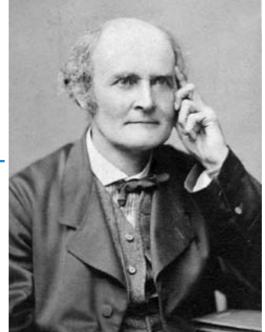
RGI project 3D Topography

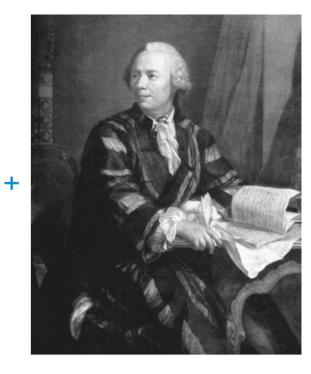
2 PhD's, 2 presentations:

- Friso Penninga (focus: data structure)
- Sander Oude Elberink (focus: data collection)

Check www.gdmc.nl/3dtopo !



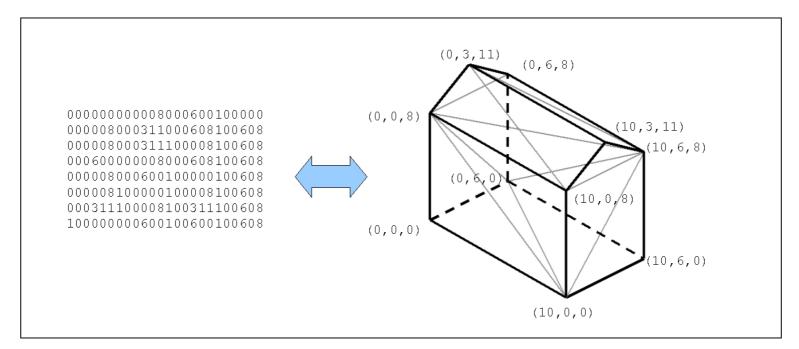




= 3D GIS?



Poincaré simplicial homology for 3D volume modeling



Friso Penninga Delft University of Technology, section GIS Technology



Outline

- Introduction
- PhD project history in a nutshell
- Basics of modelling approach
- Poincaré's formalism of simplicial homology
- Concept of Poincaré-based TEN structure
- Implementation —> illustration of concept
- Conclusions & future research
- Discussion



Introduction: Need for 3D Topography

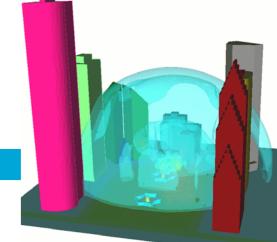
- Real world consists of 3D objects
- Objects + object representations get more complex due to multiple land use

Applications in:

- Sustainable development (planning, analysis)
- Support disaster management

3D Topography: more than visualization!





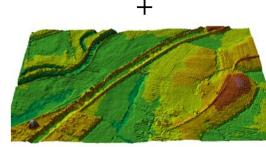
Introduction: Research Goal

Develop a new topographic model to be realized within a robust data structure and filled with existing 2D, 2.5D and 3D data

Data structure:

design / develop / implement a data structure that supports 3D analyses and maintains data-integrity









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History in a nutshell: First ideas

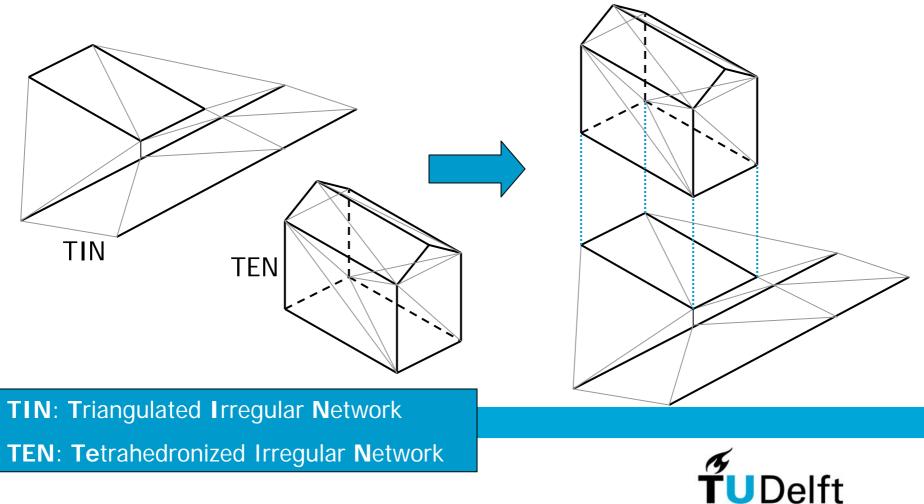
• July 2004: *"Realization of a three dimensional topographic terrain representation in an integrated TIN/TEN model"* (Agile 2005)



Proposed data model: 2.5D TIN + 3D TEN

Model terrain in 2.5D, 'glue' 3D models on top or below 2.5D terrain

Presentation Agile



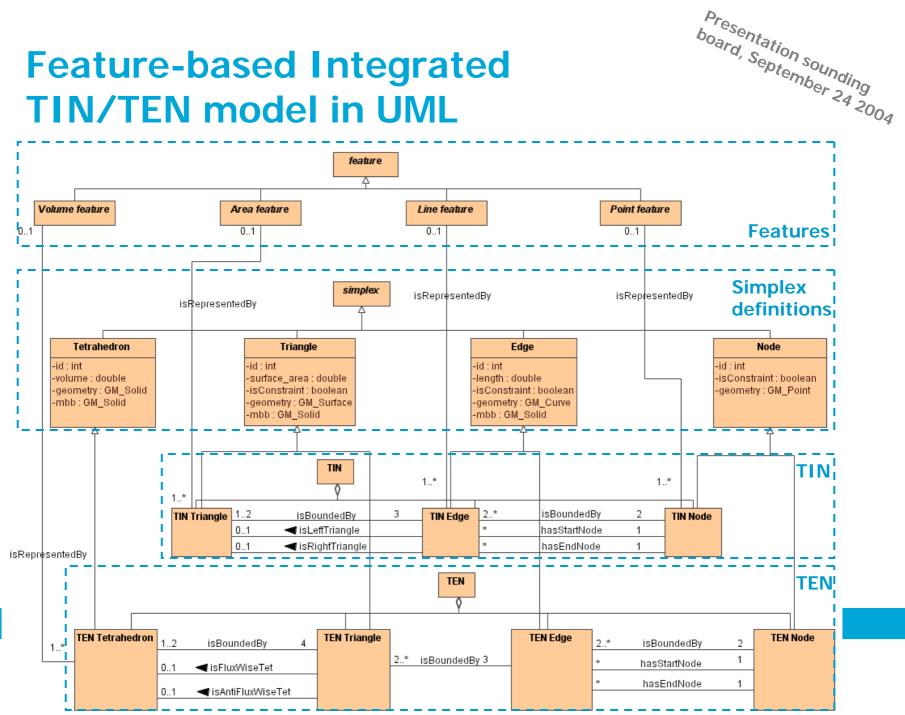
Basic principles (3/3)



User works with features Internal representation Interface: translate object model into set of constraints



Feature-based Integrated TIN/TEN model in UML



History in a nutshell: Continuation on hybrid approach

- July 2004: *"Realization of a three dimensional topographic terrain representation in an integrated TIN/TEN model"* (Agile 2005)
- September 2004: Linking TIN and TEN model (glue, stitch & nail)

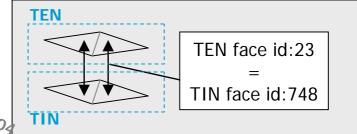


Connecting TIN+TENs

Problems



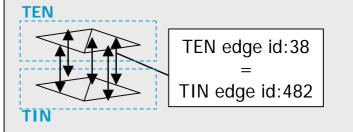
Linking faces: 'glueing'



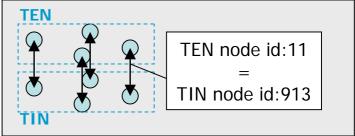
How to ensure identical faces or edges in TIN surface and TEN bottom? Might be problematic due to addition of Steiner points in triangulation / tetrahedronization (iterating process?)

Possible solution: addition of Steiner points in interior (common in mesh refinement, but rather unusual in GIS (nodes represent point measurents))

Linking edges: 'stitching'

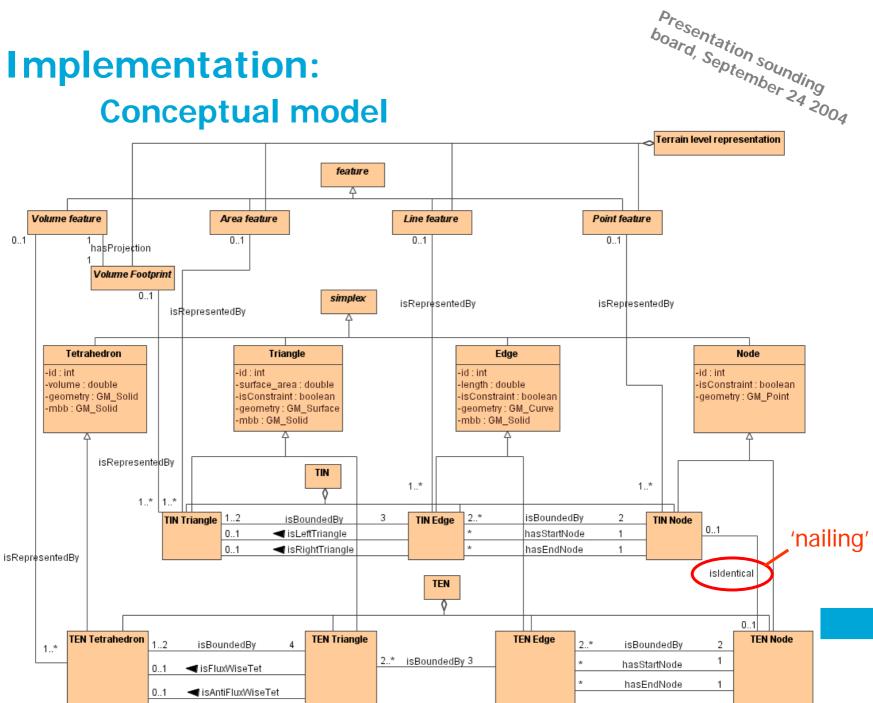


Linking nodes: 'nailing'





Implementation: **Conceptual model**



History in a nutshell: Switch to full 3D approach

- July 2004: *"Realization of a three dimensional topographic terrain representation in an integrated TIN/TEN model"* (Agile 2005)
- September 2004: Linking TIN and TEN model (glue, stitch & nail)
- Spring 2005: *"3D Topographic data modelling: why rigidity is preferable to pragmatism"* (Cosit '05)



Proposed new approach Full 3D TEN model



Two fundamental observations:

- ISO19101: a feature is an 'abstraction of real world phenomena'. These real world phenomena have by definition a volume
- Real world can be considered to be a volume partition (analogous to a planar partition: a set of non-overlapping volumes that form a closed modelled space)



Proposed new approach Why a full 3D approach?



'Abstraction of real world phenomena' (ISO19101):

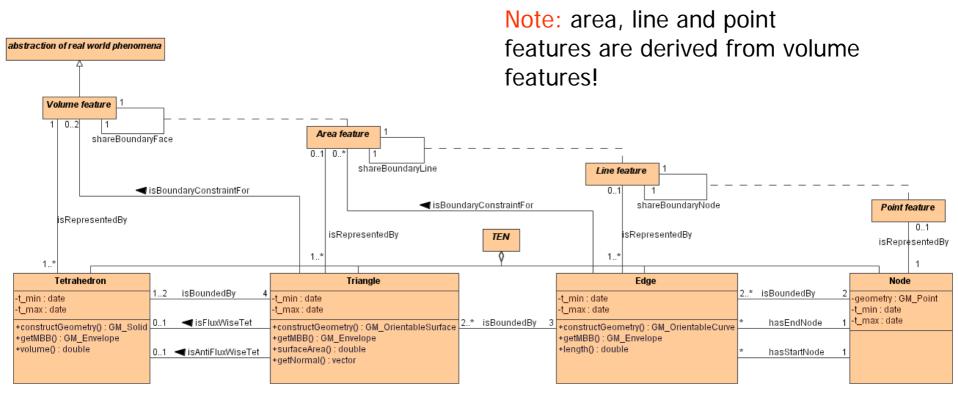
- until now: abstraction (simplification) —> less dimensional representation
- when using meshes: simplification is in subdivision into easy-to-handle parts (analogously to Finite Element Method for solving Partial Differential Equations)

As a result: model only volume features in a volume partition (but handle polygon features as association class, derived from volume features, as faces mark transition between two volumes: for instance wall, earth surface)





Further research UML model

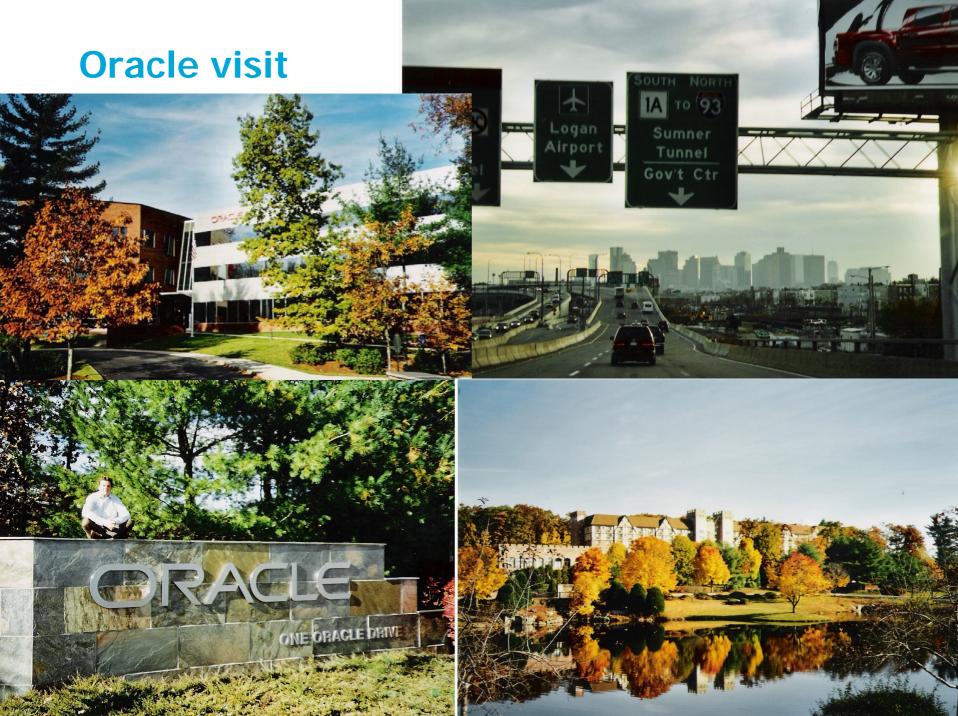




History in a nutshell: Introduced to Poincaré

- July 2004: *"Realization of a three dimensional topographic terrain representation in an integrated TIN/TEN model"* (Agile 2005)
- September 2004: Linking TIN and TEN model (glue, stitch & nail)
- September 2005: *"3D Topographic data modelling: why rigidity is preferable to pragmatism"* (Cosit '05)
- November 2005: one week visit to Oracle Spatial Development Centre





Oracle visit

- Discussions on 3D
- First experiences 'toy' dataset:
 56 tetrahedrons, 120 triangles,
 83 edges, 20 nodes
- John Herring suggests Poincaré
- 'Hands-on' session
- Visualisation: Oracle MapViewer + function rotateGeom

Simple Geometry Visualizer - Microsoft Internet Explorer	- 2
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MapViewer Simple Spatial Query Visualizer 108	Se .
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select rotate_geom(rotate_geom(edge_geometry, -60, Iine 0),25,1) from full_edge where isconstraint1 Iransho	Fat []







History in a nutshell: Poincaré-based approach

- July 2004: "Realization of a three dimensional topographic terrain representation in an integrated TIN/TEN model" (Agile 2005)
- September 2004: Linking TIN and TEN model (glue, stitch & nail)
- September 2005: *"3D Topographic data modelling: why rigidity is preferable to pragmatism"* (Cosit '05)
- November 2005: one week visit to Oracle Spatial Development Centre
- July 2006: *"A Tetrahedronized Irregular Network Based DBMS approach for 3D Topographic Data Modelling"* (SDH'06)
- September 2006: *"Updating Features in a TEN-based DBMS approach for 3D Topographic Data Modelling"* (GIScience'06)



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Basics of modelling approach: Fundamental concept (1/2)

- Physical world objects have by definition a volumetric shape: there are no such things as point, line or area features! (*only point, line and area representations at a certain level of generalization*)
- The real world can be considered as a volume partition: a set of non-overlapping volumes that form a closed modeled space. As a consequence, objects like 'earth' or 'air' are explicitly part of the real world and thus have to be modeled.



Basics of modelling approach Fundamental concept (2/2)

No area features at all?

yes, but as derived features: area features (e.g. 'wall', 'roof') mark transition between volume features

Doorrijhoogte

410 - MT

For instance:

- 'Earth surface' is transition between 'earth' and 'air'
- 'Wall/roof' is transition between 'house' and 'air'

But how to model for instance a road?

 Road is a volume (in which cars can drive without hitting something: 'tunnel in the sky'). Transition between 'earth' and 'road' can be drawn with 'road' colors

Basics of modelling approach TEN approach (1/2)

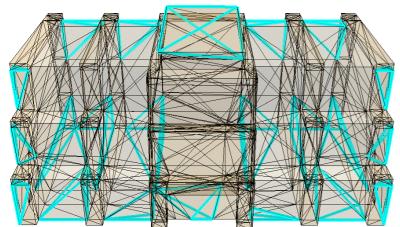
Important: data consistency and data analysis

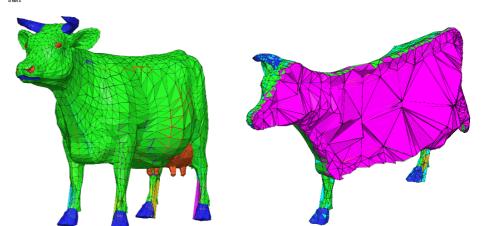
TEN structure well-suited:

well-defined, only convex volumes, flat faces

In 3D (complex) shapes \longrightarrow subdivide in (many) tetrahedrons:

TEN is based on points, line segments, triangles and tetrahedrons: simplexes ('simplest shape in a given dimension')





Basics of modelling approach TEN approach (2/2)

Drawbacks:

- Complexity (but hide it from user...)
- Storage requirements:



Building as polyhedron	Building as TEN
(1 volume)	8 tetrahedrons
7 polygons	24 triangles
(15 edges)	25 edges
(10 points)	10 nodes

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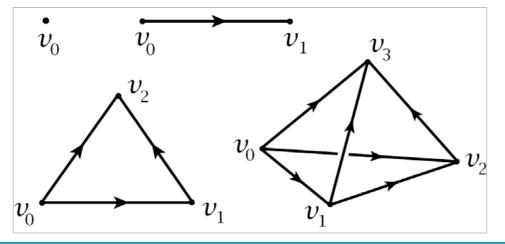
Poincaré simplicial homology (1/5) Definition simplex

Solid mathematical foundation:

A *n*-simplex S_n is defined as smallest convex set in Euclidian space \mathbb{R}^m of n+1 points $V_0, ..., V_n$ (which do not lie in a hyper plane of dimension less than *n*)



Jules Henri Poincaré (1854-1912)





Poincaré simplicial homology (2/5) Boundary operator

The boundary ∂ of simplex S_n is defined as sum of *(n-1)* dimensional simplexes (note that 'hat' means skip the node):

$$\partial S_{n} = \sum_{i=0}^{n} (-1)^{i} < v_{0}, ..., \hat{v}_{i}, ..., v_{n} >$$

remark: sum has n+1 terms

PUBLIÉ AVEC LA COLLABORATION DE

RENÉ GARNIER ET JEAN LERAY MEMBRE DE L'INSTITUT FERSER à LA AFOCTÉR DES SERVICES DE PARIS



 $S_{1} = \langle v_{0}, v_{1} \rangle$ $S_{2} = \langle v_{0}, v_{1}, v_{2} \rangle$ $S_{3} = \langle v_{0}, v_{1}, v_{2}, v_{3} \rangle$

$$\partial S_{1} = \langle v_{1} \rangle - \langle v_{0} \rangle$$

$$\partial S_{2} = \langle v_{1}, v_{2} \rangle - \langle v_{0}, v_{2} \rangle + \langle v_{0}, v_{1} \rangle$$

$$\partial S_{3} = \langle v_{1}, v_{2}, v_{3} \rangle - \langle v_{0}, v_{2}, v_{3} \rangle + \langle v_{0}, v_{1}, v_{3} \rangle - \langle v_{0}, v_{1}, v_{2} \rangle$$



Poincaré simplicial homology (3/5) Simplex construction

$$S_n has \binom{n+1}{p+1}$$
 faces of dimension p with $(0 \le p < n)$

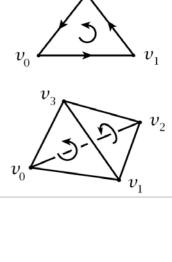
- 2D: this means that triangle (S_2) has 3 edges (S_1) and 3 nodes (S_0)
- 3D: this means that tetrahedron (S₃) has
 4 triangles (S₂), 6 edges (S₁) and 4 nodes (S₀)



Poincaré simplicial homology (4/5) Orientation of boundaries

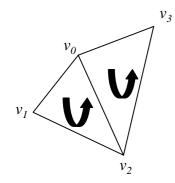
With (n+1) points, there are (n+1)! permutations of these points. In 3D for the 4 simplexes this means 1, 2, 6 and 24 options (S_0 obvious):

- For S₁ the two permutations are <v₀, v₁> and <v₁, v₀> (one positive and one negative <v₀, v₁> = <v₁, v₀>)
- For S_2 there are 6: $\langle v_0, v_1, v_2 \rangle$, $\langle v_1, v_2, v_0 \rangle$, $\langle v_2, v_0, v_1 \rangle$, $\langle v_2, v_1, v_0 \rangle$, $\langle v_0, v_2, v_1 \rangle$, and $\langle v_1, v_0, v_2 \rangle$. First 3 opposite orientation from last 3, e.g. $\langle v_0, v_1, v_2 \rangle = - \langle v_2, v_1, v_0 \rangle$. counter clockwise (+) and the negative orientation is clockwise (-)
- For S₃ there are 24, of which 12 with all normal vectors outside
 (+) and 12 others with all normal vectors inside (-)!

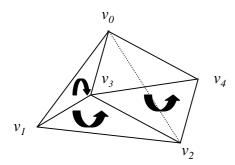




Poincaré simplicial homology (5/5) Simplicial complexes



$$\begin{split} S_{21} = &< v_0, v_1, v_2 > \text{and } S_{22} = < v_0, v_2, v_3 > \\ C_2 = &< v_1, v_2 > - < v_0, v_2 > + < v_0, v_1 > \\ + &< v_2, v_3 > - < v_0, v_3 > + < v_0, v_2 > \\ = &< v_1, v_2 > + < v_0, v_1 > + < v_2, v_3 > + < v_3, v_0 > \end{split}$$



$$\begin{split} S_{31} = &< v_0, v_1, v_2, v_3 > \text{and } S_{32} = < v_0, v_2, v_4, v_3 > \\ C_3 = &< v_1, v_2, v_3 > - < v_0, v_2, v_3 > + < v_0, v_1, v_3 > \\ - &< v_0, v_1, v_2 > + < v_2, v_4, v_3 > - < v_0, v_4, v_3 > \\ + &< v_0, v_2, v_3 > - < v_0, v_2, v_4 > \\ = &< v_1, v_2, v_3 > + < v_0, v_1, v_3 > - < v_0, v_1, v_2 > \\ + &< v_2, v_4, v_3 > - < v_0, v_4, v_3 > - < v_0, v_2, v_4 > \end{split}$$



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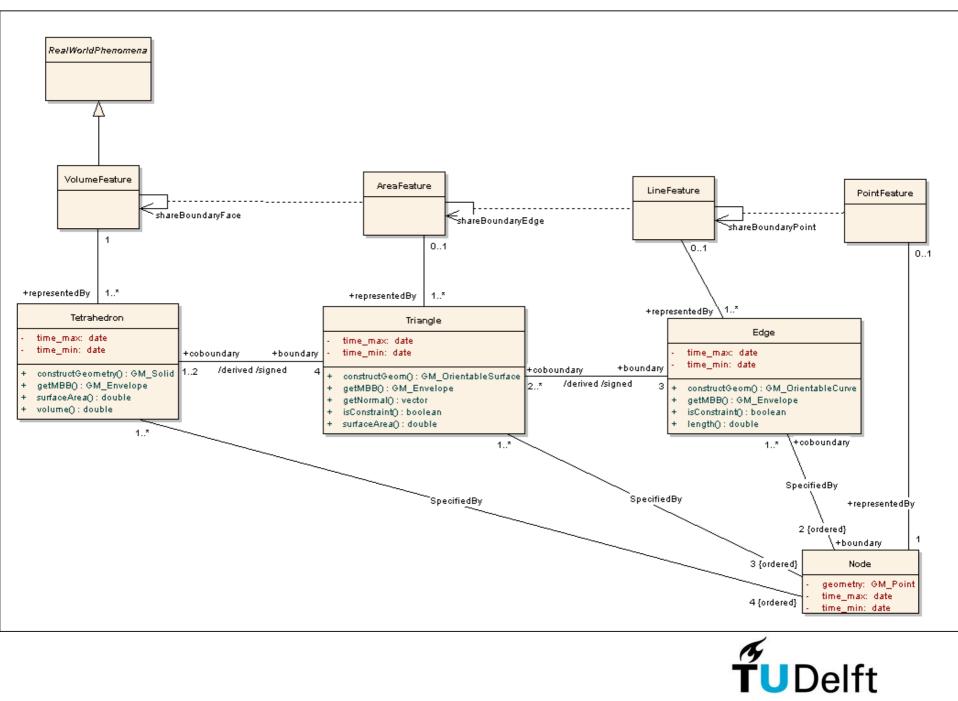


TEN approach using simplicial homology First ideas

- Describe all simplexes by their vertices
- Store tetrahedrons and vertices in table
- Derive triangles and edges (views) using the boundary operator
- Use signed and oriented simplexes

In UML this looks like...

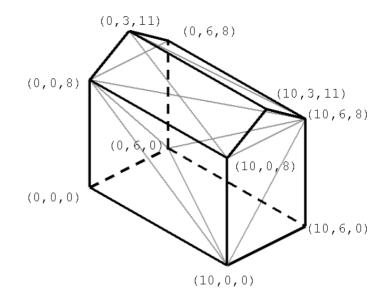




TEN approach using simplicial homology Current ideas

- Encode vertex coordinates
- Describe all simplexes by their coded vertices
- Store tetrahedrons in table
- Derive triangles, edges and nodes (views) using the boundary operator
- Use signed and oriented simplexes

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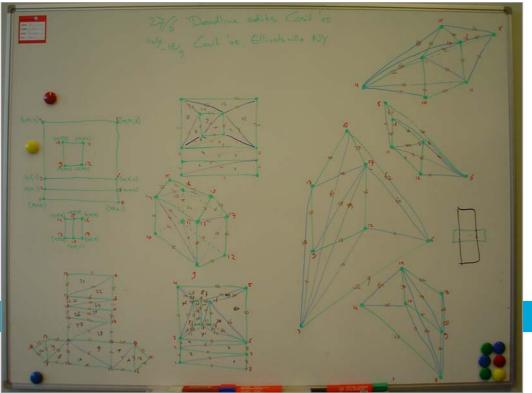
Outline

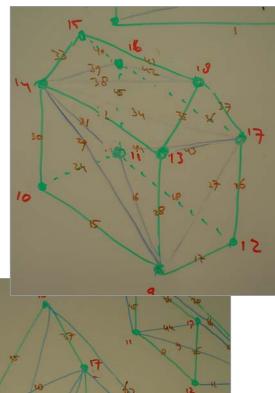
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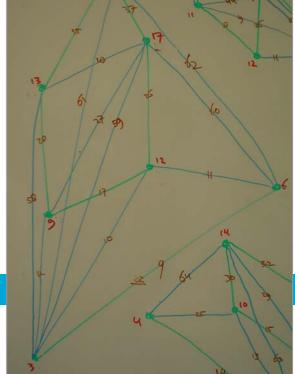


Implementation Tetrahedronization

At this moment: tetrahedronization by hand 'Toy' dataset: 56 tetrahedrons, 120 triangles, 83 edges, 20 nodes







Implementation Loading data in tetrahedron table

CREATE TABLE tetrahedron(tetcode NVARCHAR2(100));

LOAD DATA INFILE 'data/miniset.data' APPEND INTO TABLE tetrahedron fields terminated by ' ' (tetcode)

Result: table with tetrahedrons

Implementation Fixing orientation tetrahedrons

Objective: all tetrahedrons oriented outwards

each boundary triangle appears two times: 1x pos., 1x neg.

```
CREATE OR REPLACE PROCEDURE tettableoutwards
(...)
checkorientation(codelength,currenttetcode,bool);
IF (bool = 0) THEN
    permutation12(codelength,currenttetcode,newtetcode);
    UPDATE tetrahedron SET tetcode=newtetcode WHERE CURRENT OF tetcur;
(...)
END;
```

checkorientation : angle normal vector and vector to opposite point permutation12 : $(V_0, V_1, V_2, V_3) \longrightarrow (V_1, V_0, V_2, V_3)$

 \mathcal{V}_{c}

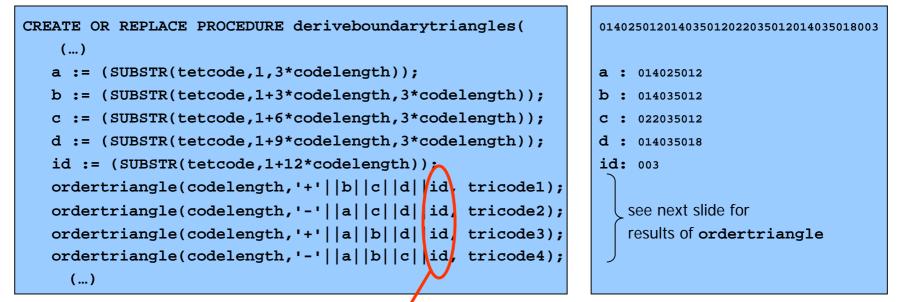
Implementation Deriving boundary triangles

Applying boundary operator:

$$\mathcal{O} S_n = \sum_{i=0}^n (-1)^i < v_0, ..., \hat{v}_i, ..., v_n >$$

Procedure:

Example:



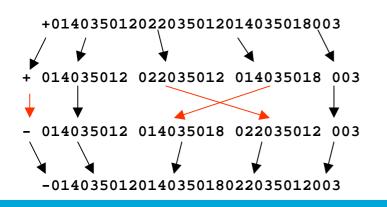
Note: triangles inherit ID of object which is represented by the tetrahedron of which they are a boundary!



Implementation Ordering triangles

Objective: gain control over which permutation is used

ordertriangle rewrites in form
<a,b,c> such that a<b<c</pre>



< <i>v</i> ₀ , <i>v</i> ₁ , <i>v</i> ₂ >	-
< <i>v</i> ₀ , <i>v</i> ₂ , <i>v</i> ₁ >	+
< <i>v</i> ₂ , <i>v</i> ₀ , <i>v</i> ₁ >	-
< <i>v</i> ₂ , <i>v</i> ₁ , <i>v</i> ₀ >	+
< <i>v</i> ₁ , <i>v</i> ₂ , <i>v</i> ₀ >	-
< <i>v</i> ₁ , <i>v</i> ₀ , <i>v</i> ₂ >	+



Implementation Creating view triangle

```
CREATE OR REPLACE VIEW triangle AS

SELECT deriveboundarytriangle1(3,tetcode) tricode FROM tetrahedron

UNION ALL

SELECT deriveboundarytriangle2(3,tetcode) tricode FROM tetrahedron

UNION ALL

SELECT deriveboundarytriangle3(3,tetcode) tricode FROM tetrahedron

UNION ALL

SELECT deriveboundarytriangle4(3,tetcode) tricode FROM tetrahedron;
```

Four functions: first gives first boundary, etc.

Result: #triangles = 4 * #tetrahedrons

Every triangle appears two times: once with sign +, once with sign – (and NOT in a permutated form \longrightarrow due to ordertriangle!)



Implementation Creating view constrainedtriangle

```
CREATE OR REPLACE VIEW constrainedtriangle AS
SELECT t1.tricode tricode FROM triangle t1
WHERE NOT EXISTS (SELECT t2.tricode FROM triangle t2 WHERE t1.tricode = t2.tricode*-1);
```

Well, not every triangle appears two times:

A constrained triangle is a boundary between two objects two different id's
two different triangle codes!

Example: in -1,7,2,-7,-3,1 the constrained triangles are 2 and -3



Implementation Creating views edge, constrainededge

In current implementation edges are undirected en do not inherit object id's (as no application for this is identified at the moment)

CREATE OR REPLACE VIEW edge AS		
SELECT DISTINCT deriveabsboundaryedge1(3,tricode) edcode FROM triangle		
UNION		
SELECT DISTINCT deriveabsboundaryedge2(3,tricode) edcode FROM triangle		
UNION		
SELECT DISTINCT deriveabsboundaryedge3(3,tricode) edcode FROM triangle;		

All boundary edges from constrained triangles are constrained edges:

```
CREATE OR REPLACE VIEW constrainedtriangle AS
SELECT t1.tricode tricode FROM triangle t1
WHERE NOT EXISTS (SELECT t2.tricode FROM triangle t2 WHERE t1.tricode =
t2.tricode*-1);
```



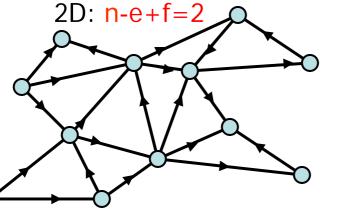
Implementation Validating the structure (1/3)

After creating node view the structure can be validated:

3D Euler-Poincaré

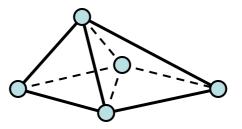
$$N-E+F-V=0$$

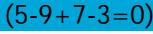
Leonard Euler, 1707-1783



(12-21+11=2)

3D: n-e+f-v=0









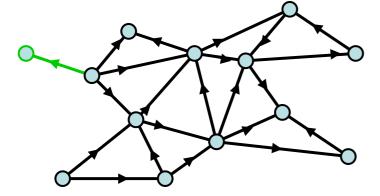
Implementation Validating the structure (2/3)

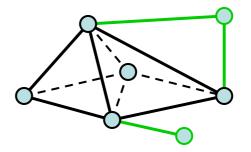
Limitations:

3D Euler-Poincaré holds for all simplicial complexes, including complexes build up of simplexes of different dimension (i.e. dangling edges and faces are allowed)



Leonard Euler, 1707-1783





(7-12+8-3=0)

(13-22+11=2)

Implementation Validating the structure (3/3)

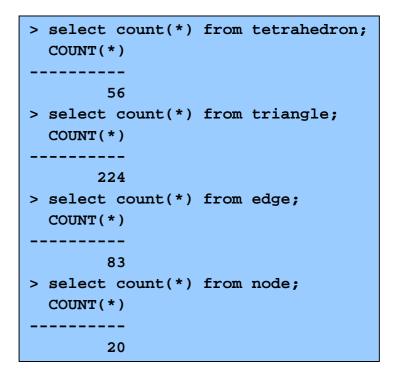
3D Euler-Poincaré for current dataset:

N - E + F - V = O

20 - 83 + 224 - 57 <> 0 !

View triangle contains duals, need to be excluded from count:

SELECT COUNT(DISTINCT ABS(removeobjectid(3,tricode)))
INTO numtri FROM triangle;





Implementation Query and analysis (1/2)

Query: boundary triangulation of building (object ID = 3)

SQL> select tricode from constrainedtriangle where getobjectid(3,tricode)=3; TRICODE -014025012014025018022025018003-014025018018025021022025018003-018025021018035021022035018003+014025012022025012022025018003-014025012014035012014035018003+018025021022025018022035018003-014025012022025012022035012003+014025012014025018014035018003+014025012014035012022035012003-014035018022035012022035018003+01403501201403501802203501200310 +014035018018025021018035021003+022025018022035012022035018003+014035018018035021022035018003-022025012022025018022035012003-014025018014035018018025021003

16 rows selected. Elapsed: 00:00:00.09

Implementation Query and analysis (2/2)

Volume of house, surface of boundary of house:



simplexvolume() implements Cayley-Menger determinant

Arthur Cayley, 1821-1895

Cayley-Menger determinant gives the volume of a simplex in *j* dimensions.

$$j=2: -16 \Delta^{2} = \begin{vmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & c^{2} & b^{2} \\ 1 & c^{2} & 0 & a^{2} \\ 1 & b^{2} & a^{2} & 0 \end{vmatrix} \qquad \qquad j=3: 288 V^{2} = \begin{vmatrix} 0 & 1 & 1 & 1 & 1 \\ 1 & 0 & d_{12}^{2} & d_{13}^{2} & d_{14}^{2} \\ 1 & d_{21}^{2} & 0 & d_{23}^{2} & d_{24}^{2} \\ 1 & d_{31}^{2} & d_{32}^{2} & 0 & d_{34}^{2} \\ 1 & d_{41}^{2} & d_{42}^{2} & d_{43}^{2} & 0 \end{vmatrix}$$

(with $a_i b_i c$ and d_{ij} length of simplex edges)



Implementation Performance

Indexing:

- Primary index: sort coded simplexes
- Secondary index: R-tree on tetrahedrons, using gettetrahedronmbb(), gettrianglembb() etC.

Coding:

• More work on encoding coordinates: bitwise interleaving, ...

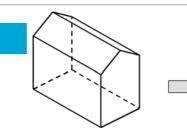


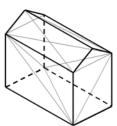
Implementation Final thougth

Polyhedron vs. TEN:

does a TEN really require that much more storage space than polyhedrons?

Building as polyhedron	Building as TEN
(1 volume)	8 tetrahedrons
7 faces	(24 triangles)
(15 edges)	(25 edges)
(10 points)	(10 nodes)





Conclusions & future research

Result:

- Topological 3D (TEN) data structure, stored in one single-column table (!)
- with advantages of TEN, but not its drawbacks (?)
- based on a solid theoretical foundation (100 years old math)

Future research ideas:

- Inclusion of incremental constrained Delaunay tetrahedronization
- Test with real data (Den Bosch case?)
- Compare to Calin/Oracle11 polyhedron approach
- History (?)



Discussion (with the living...)



