Generalisation via tGAP structure

MobiMaps project (RGI-233)

Guest lecture at LBS/Geomatics

Arta Dilo

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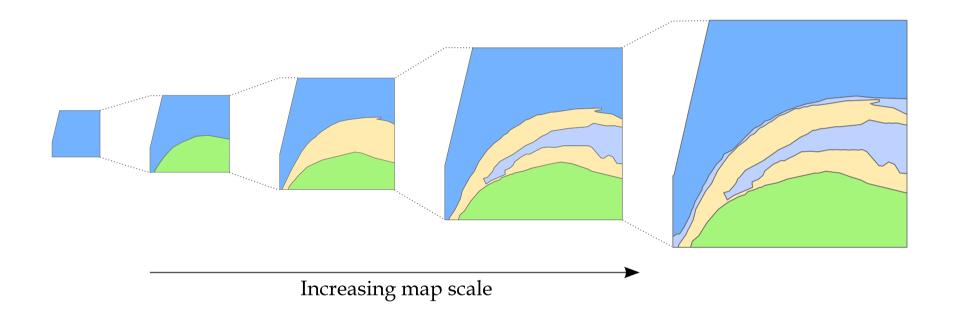


Content

- Few words on generalisation
- Theory of tGAP (topological Generalised Area Partitioning)
 - How tGAP is filled (off-line)
 - How tGAP is used for (online) feature selection
- Implementation of tGAP in Oracle Spatial
 - New data types
 - Tables storing the structure
- Further research



Why generalisation?

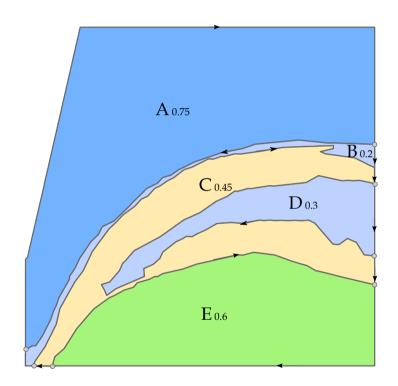




Generalisation methods & operators

- Generalisation methods:
 - Multiple representation databases
 - On-the-fly generalisation
 - tGAP structure
 - Off-line generalisation
 - On-the-fly feature selection
- Generalisation operators: reclassification, elimination, collapse, simplification, ...









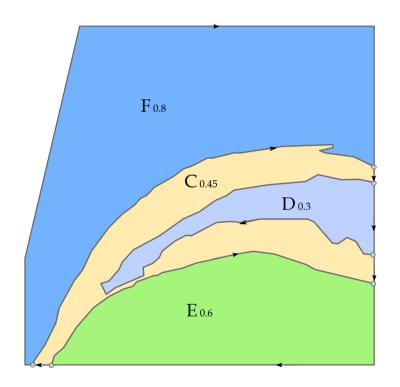






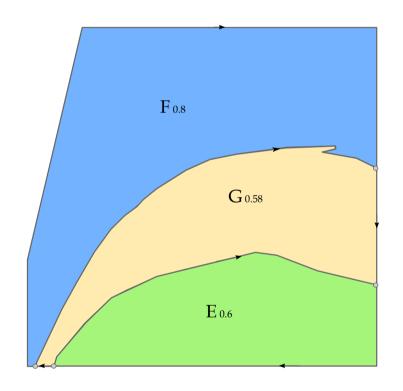
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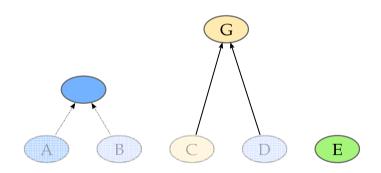




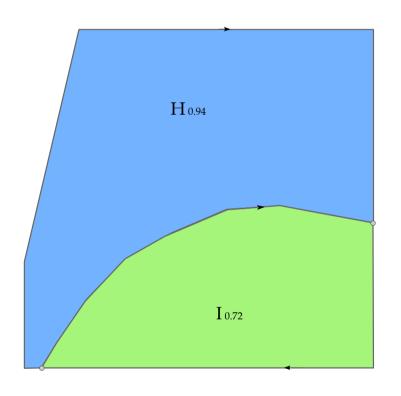


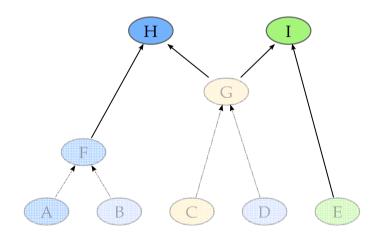






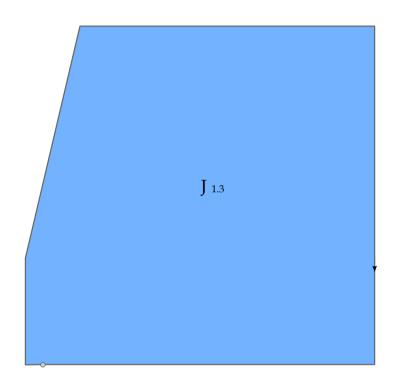


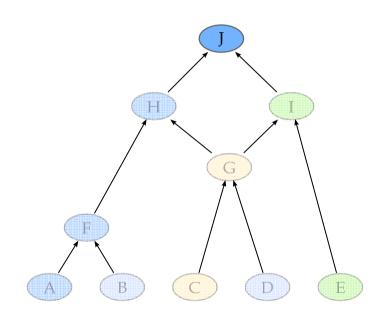




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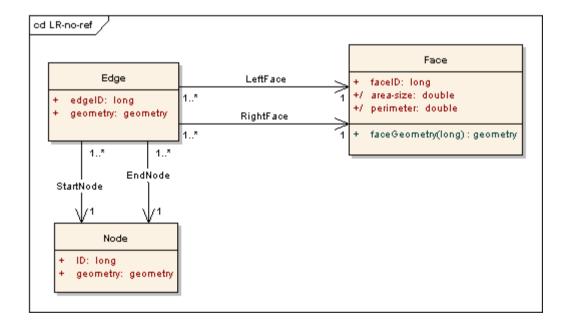






Topological model for data storage

Left-Right topology without edge references



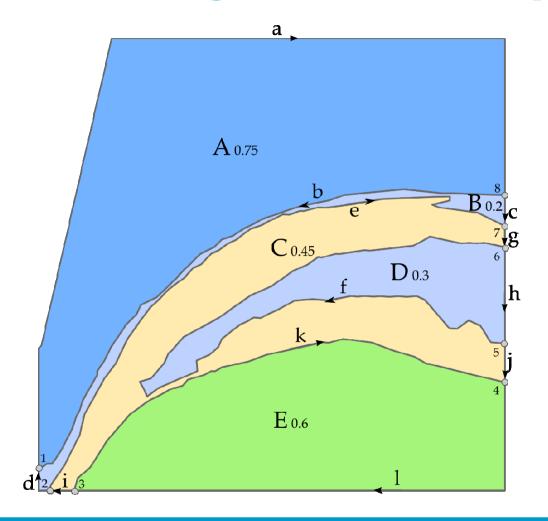


tGAP structure composition

- tGAP structure is composed of
 - Hierarchy of faces: DAG (Directed Acyclic Graph)
 - Hierarchy of edges: edge forest
 - BLG (Binary Line Generalisation) trees for edge simplification; one BLG for each edge



Building DAG hierarchy of faces: step 0



Calculate importance values:

Importance(F) = Area(F)*Class-Weight(F)



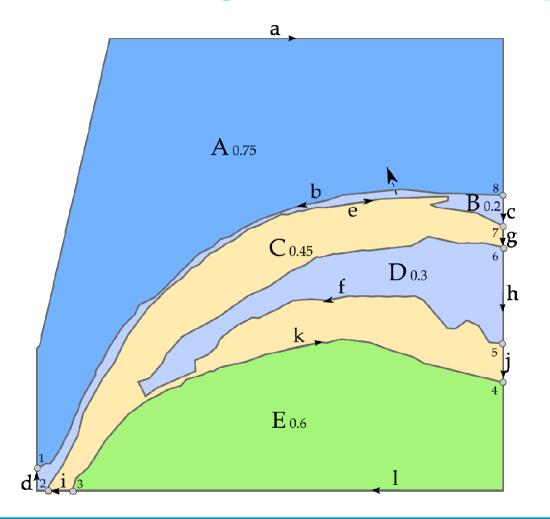












Find least important face; Find its most compatible neighbour:

Comp(F,G) = Len(Bnd(F,G)) * Class-Similarity(F,G)



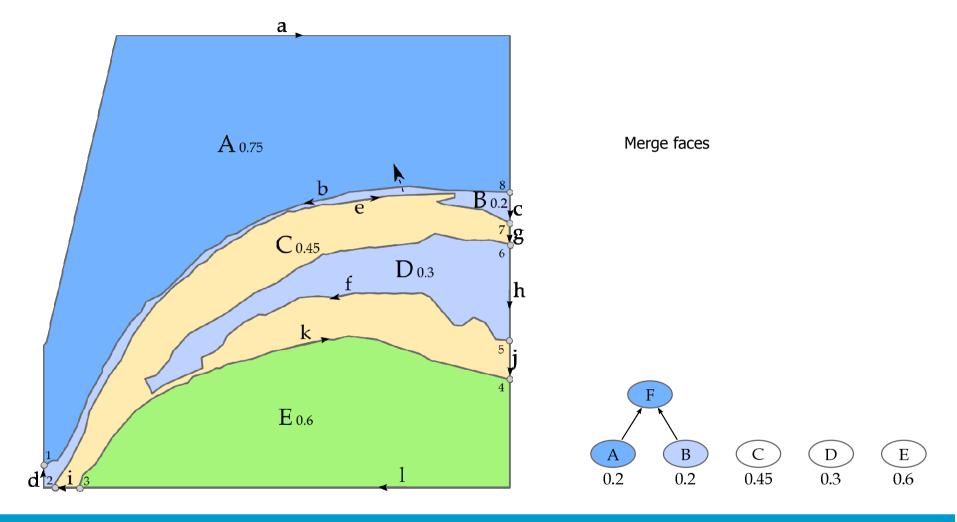




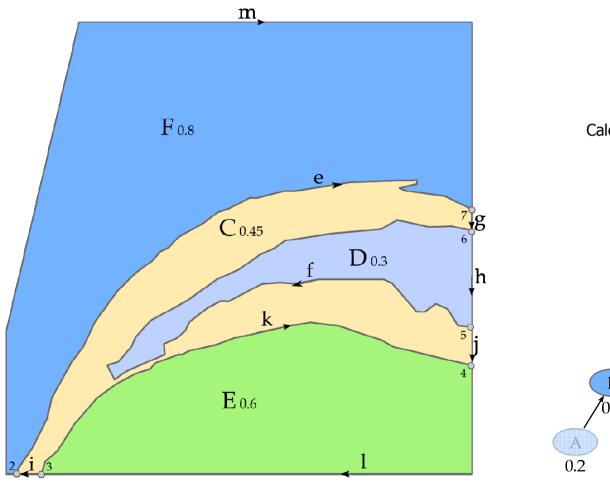




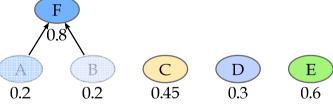




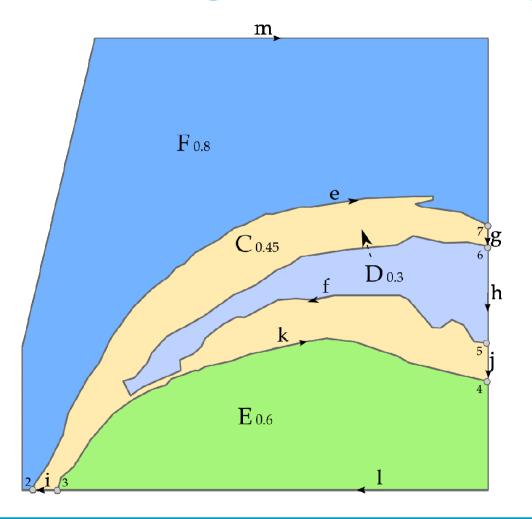




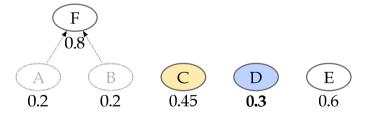
Calculate importance of the new face



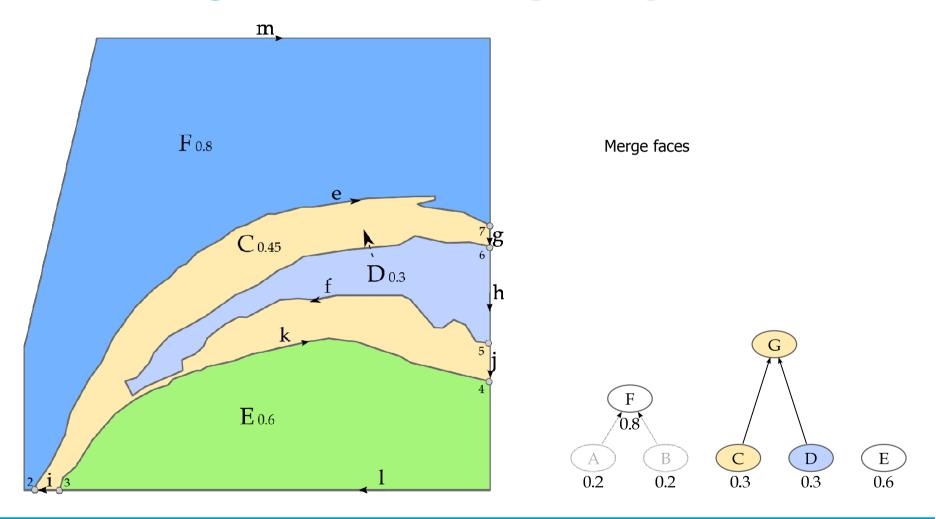




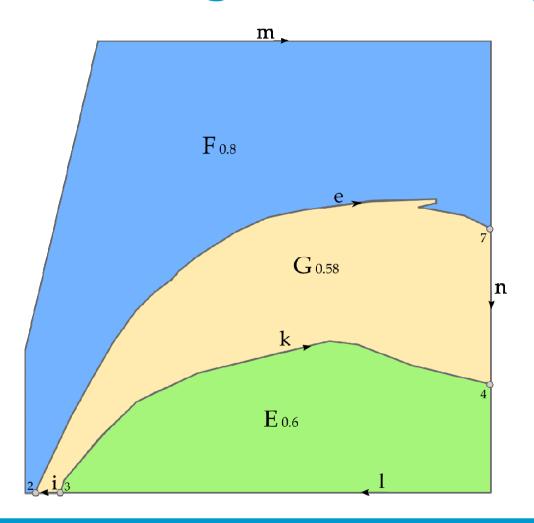
Find least important face; Find its most compatible neighbour



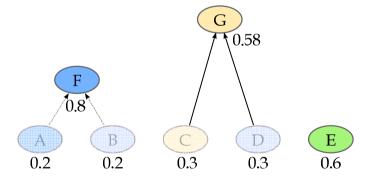




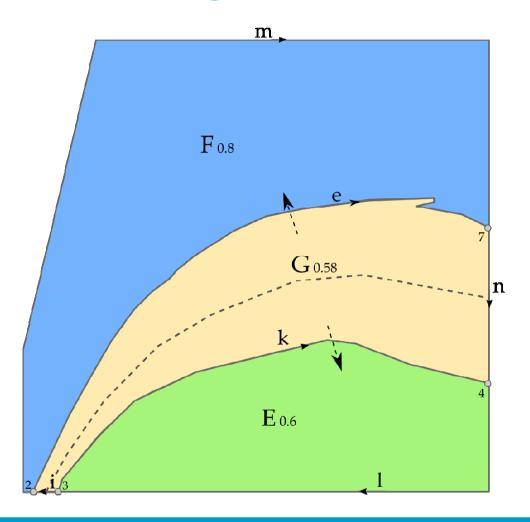




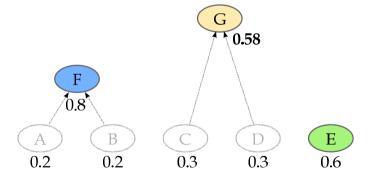
Calculate importance of the new face



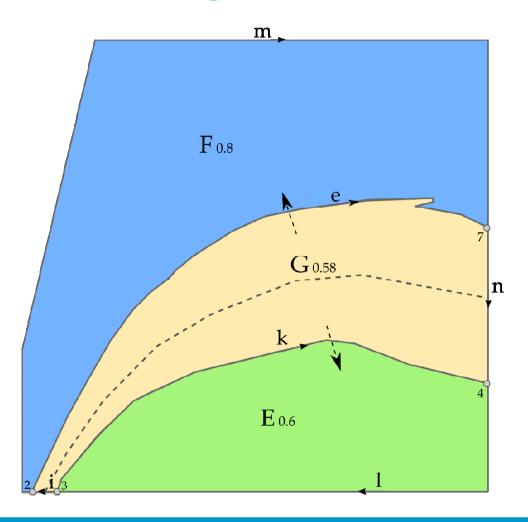




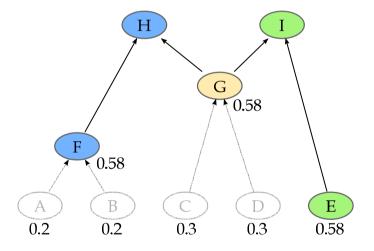
Find least important face; Find most compatible neighbours



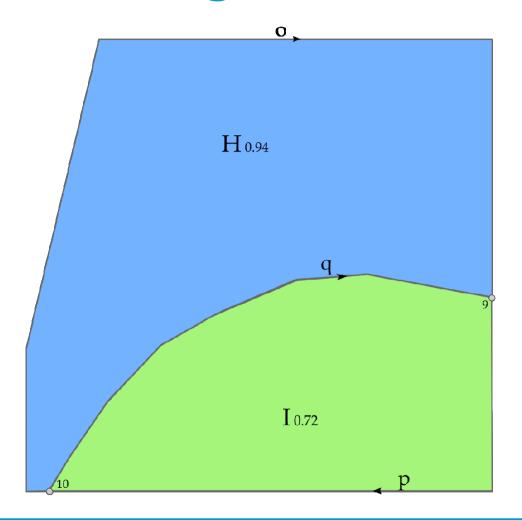




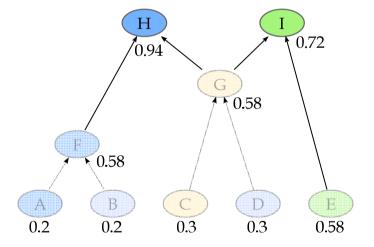
Split to an axis; Merge parts to neighbour faces



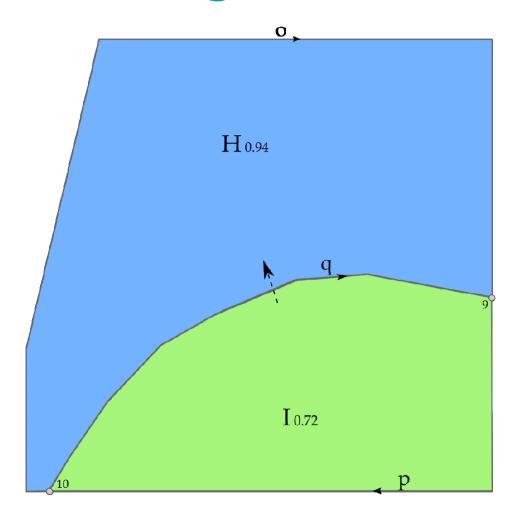




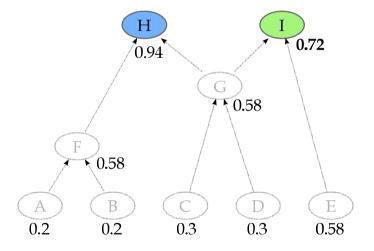
Calculate importance of the new faces



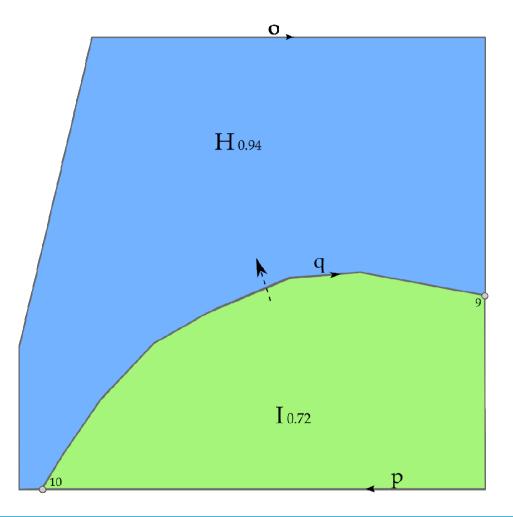


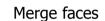


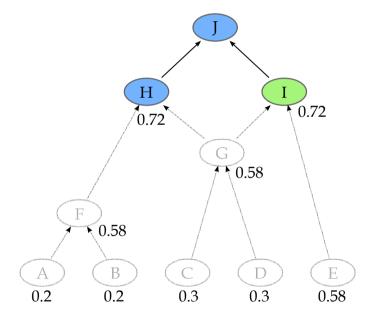
Find least important face; Find most compatible neighbour



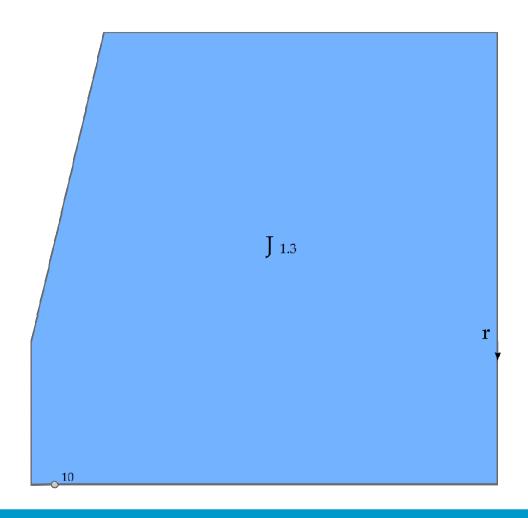




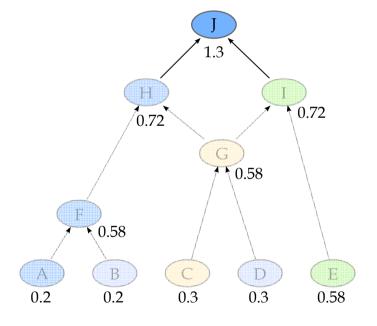






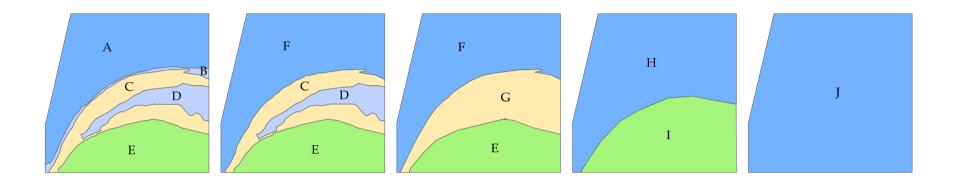


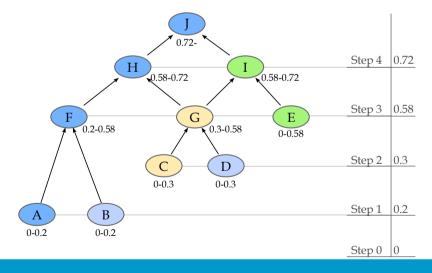
Calculate importance of the new face



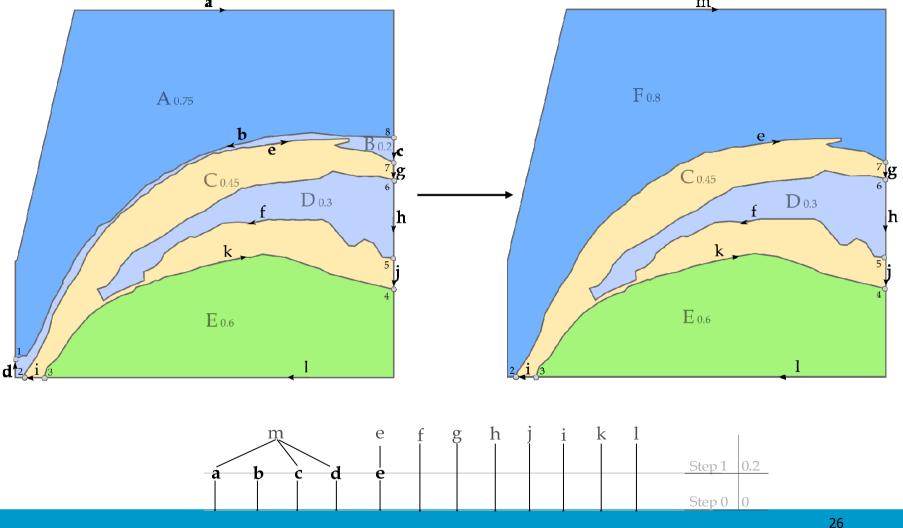


DAG hierarchy of faces

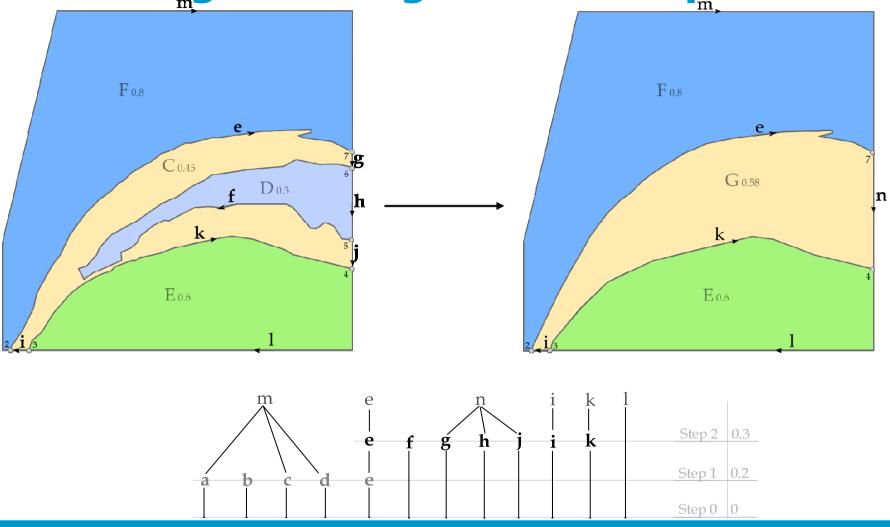




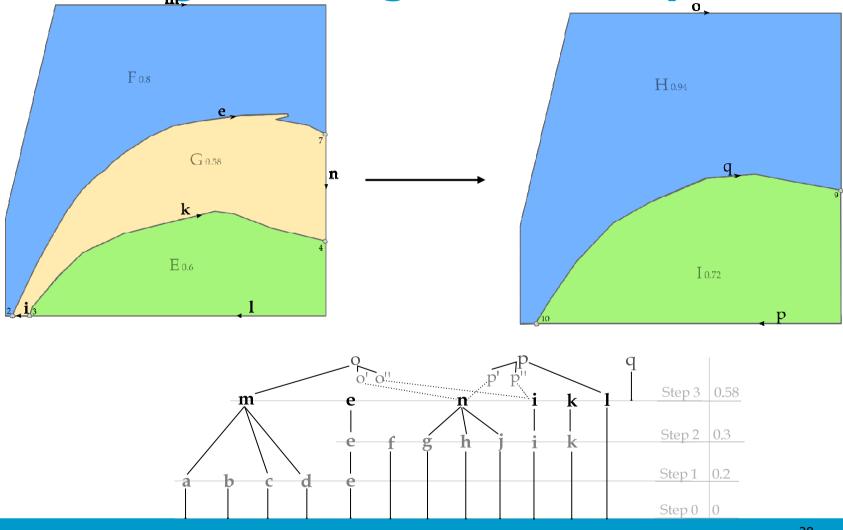




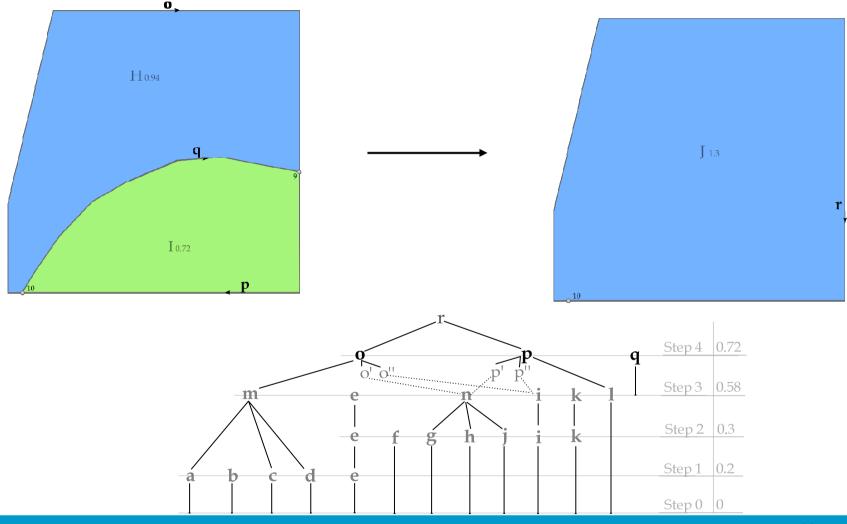






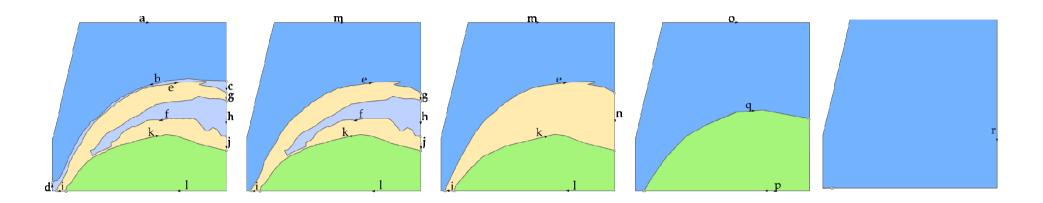


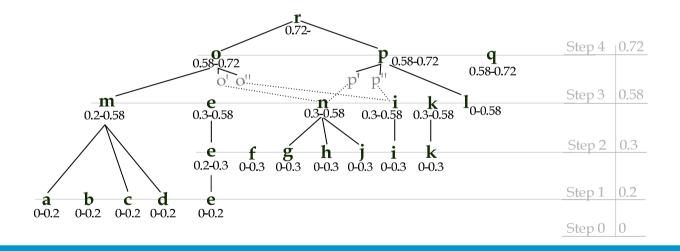






Complete tGAP edge forest

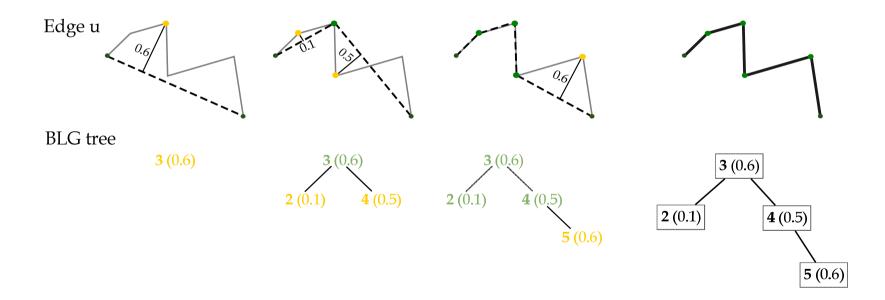






BLG edge trees

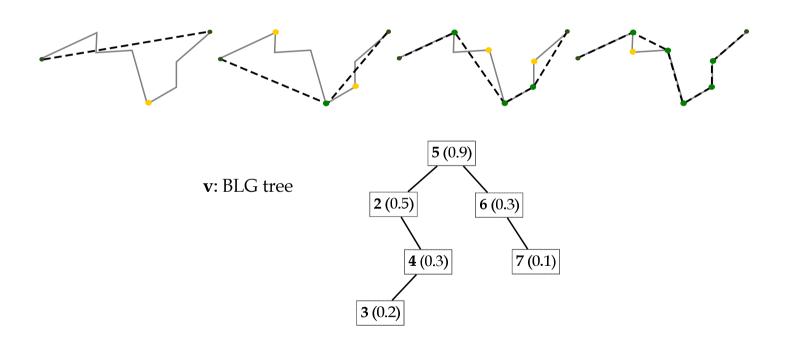
- Douglas-Peuker algorithm for edge simplification
- •Results stored in a BLG tree





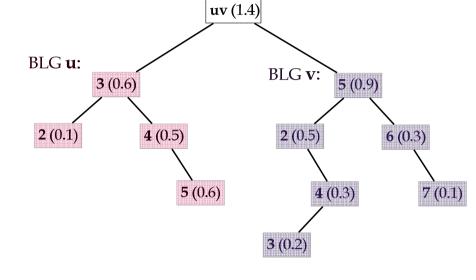
BLG edge trees

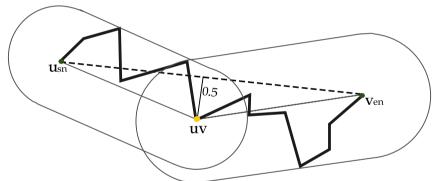
•BLG tree of another edge, **v**:





Joined BLG trees



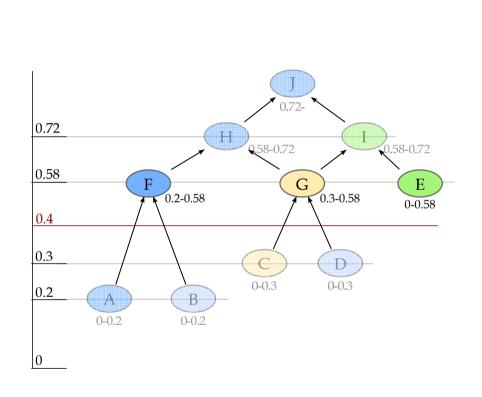


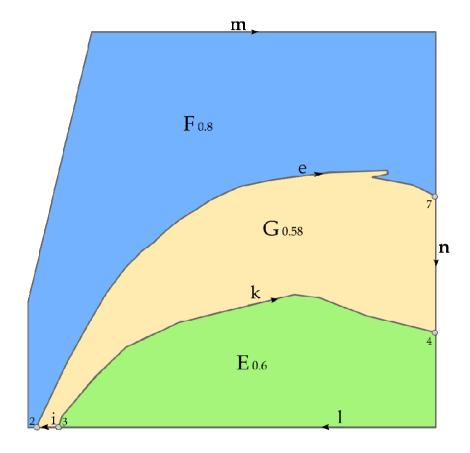
$$0.5+\max\{0.6,0.9\} = 0.5 + 0.9 = 1.4$$



Using DAG hierarchy for selection

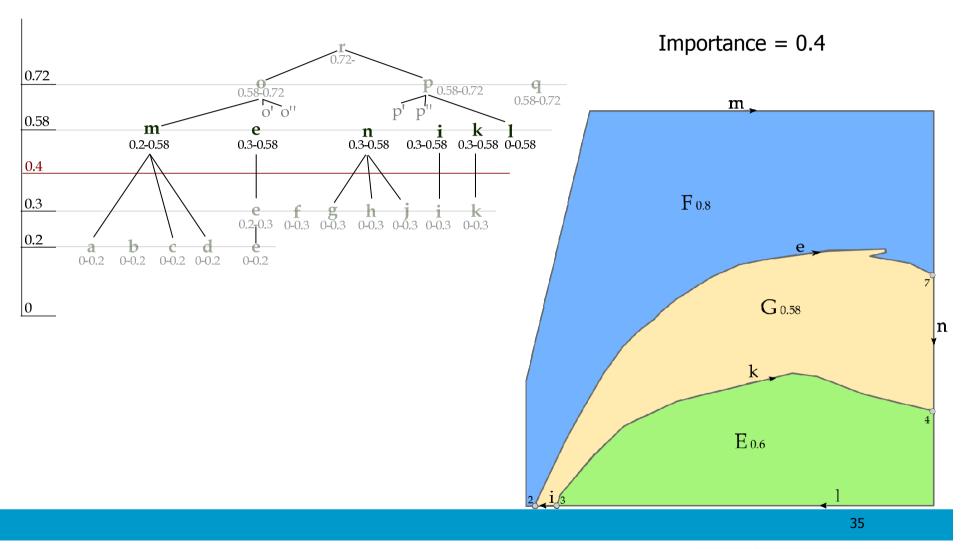
Importance = 0.4







Using edge forest for selection





Using BLG trees for edge simplification

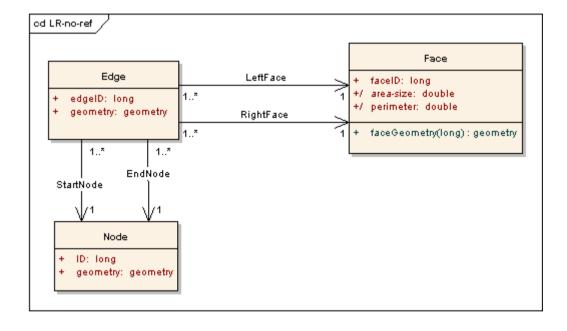
•Selecting vertices of BLG tree \mathbf{u} for tolerance = 0.52





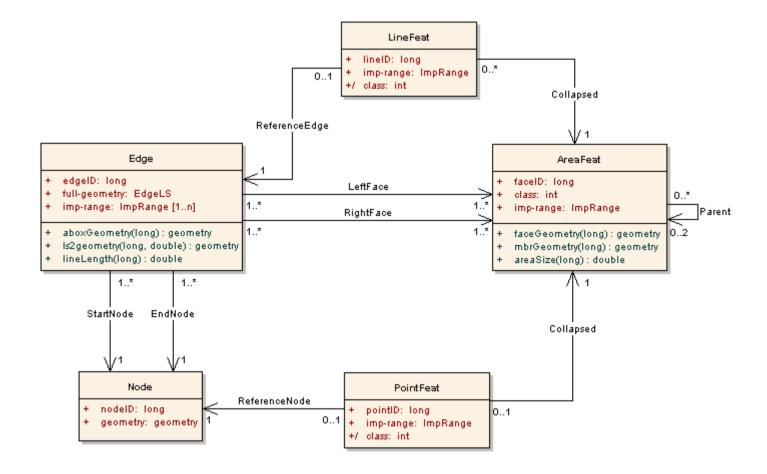
Implementation

Left-Right topology without edge references





Implementation: tGAP classes





Implementation: new data types

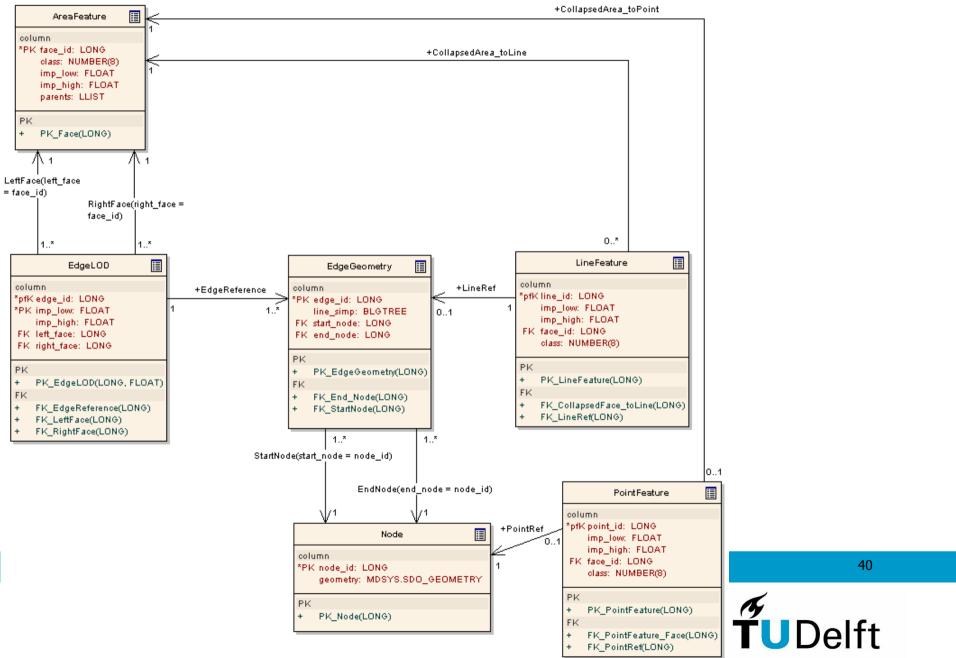
Data type for (variable detail) edge geometry

```
struct BLGTREE {
   double x_coord;
   double y_coord;
   float tolerance;
   struct BLGTREE *left_node;
   struct BLGTREE *right_node;
}
```

For joined BLG trees left & right_node refer to left & right BLG trees

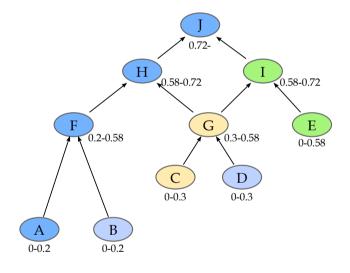


Implementation: tGAP tables



Implementation: AreaFeature table

AreaFeature							
face-id	class	imp-low	imp-high	parents			
A	1	0	0.2	F			
В	3	0	0.2	F			
С	2	0	0.3	G			
D	3	0	0.3	G			
E	4	0	0.58	I			
F	1	0.2	0.58	Н			
G	2	0.3	0.58	Н, І			
Н	1	0.58	0.72	J			
I	4	0.58	0.72	J			
J	1	0.72					

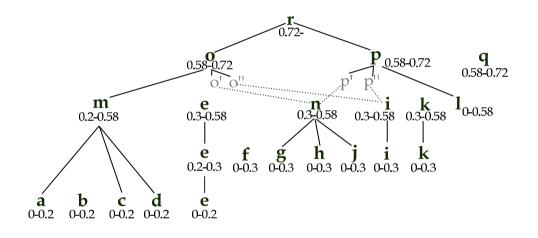


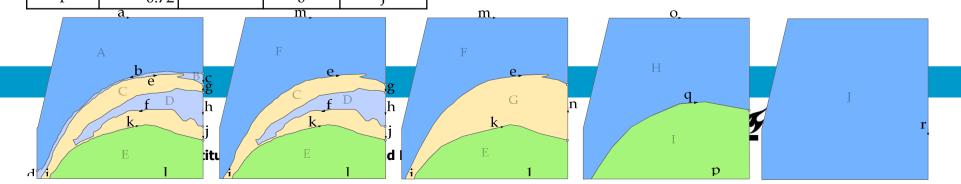




EdgeLOD							
edge-id	imp-low	imp-high	left-face	right-face			
a	0	0.2	0	A			
b	0	0.2	В	A			
С	0	0.2	0	В			
d	0	0.2	0	В			
e	0	0.2	В	С			
f	0	0.3	С	D			
g	0	0.3	0	С			
h	0	0.3	0	D			
i	0	0.3	0	С			
j	0	0.3	0	С			
k	0	0.3	С	Е			
e	0.2	0.3	F	С			
1	0	0.58	0	Е			
m	0.2	0.58	0	F			
e	0.3	0.58	F	G			
i	0.3	0.58	0	G			
k	0.3	0.58	G	E			
n	0.3	0.58	0	G			
0	0.58	0.72	0	Н			
p	0.58	0.72	0	I			
q	0.58	0.72	Н	I			
r	0.72		0	J			

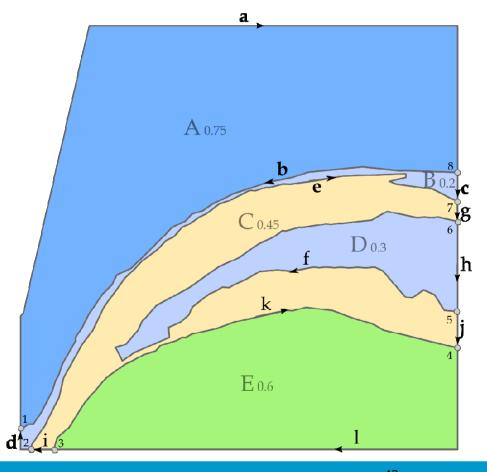
EdgeLOD table





Implementation: EdgeGeometry table

EdgeGeometry							
edge-id	line-simp	start-node	end-node				
a	 digtree>	1	8				
b	 digtree>	8	1				
С	 digtree>	8	7				
d	<bl></bl> digtree>	2	1				
e	 digtree>	2	7				
f	<bl></bl> digtree>	5	6				
g	<bl></bl> digtree>	7	6				
h	 digtree>	6	5				
i	<bl></bl> digtree>	3	2				
j	 digtree>	5	4				
k	 digtree>	3	4				
1	 digtree>	$oxed{4}$	3				
m	 digtree>	2	7				
n	 digtree>	7	4				
О	<bl></bl> digtree>	10	9				
p	 digtree>	9	10				
q	 	10	9				
r	 	10	10				







More tGAP issues & further research

- Algorithm performing the off-line generalisation
- Mobile (or web) application
 - Progressive transfer
 - Visualisation on client
- Include other operators in generalisation process
- Updating tGAP structure
- ...



References

- 1. Peter van Oosterom. Variable-scale topological data structures suitable for progressive data transfer: the gap-face tree and gap-edge forest. *Cartography and geographic information science*, 32:331–346, 2005.
- 2. Peter van Oosterom. *Reactive Data Structures for Geographic Information Systems*. PhD thesis, Department of Computer Science, Leiden University, December 1990.
- 3. Martijn Meijers. Implementation and testing of variable scale topological data structures. Master's thesis, TU Delft, June 2006.
- 4. Tinghua Ai and Peter van Oosterom. Gap-tree extensions based on skeletons. In Dianne Richardson and Peter van Oosterom, editors, *10th International Symposium on Spatial Data Handling*, pages 501–513, 2002.
- 5. Martin Galanda. *Automated Polygon Generalization in a Multi Agent System*. PhD thesis, University of Zürich, 2003.

