

Master's thesis research : results

Implementation and testing of variable scale topological data structures

Experiences with the GAP-face tree and GAP-
edge forest

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Outline

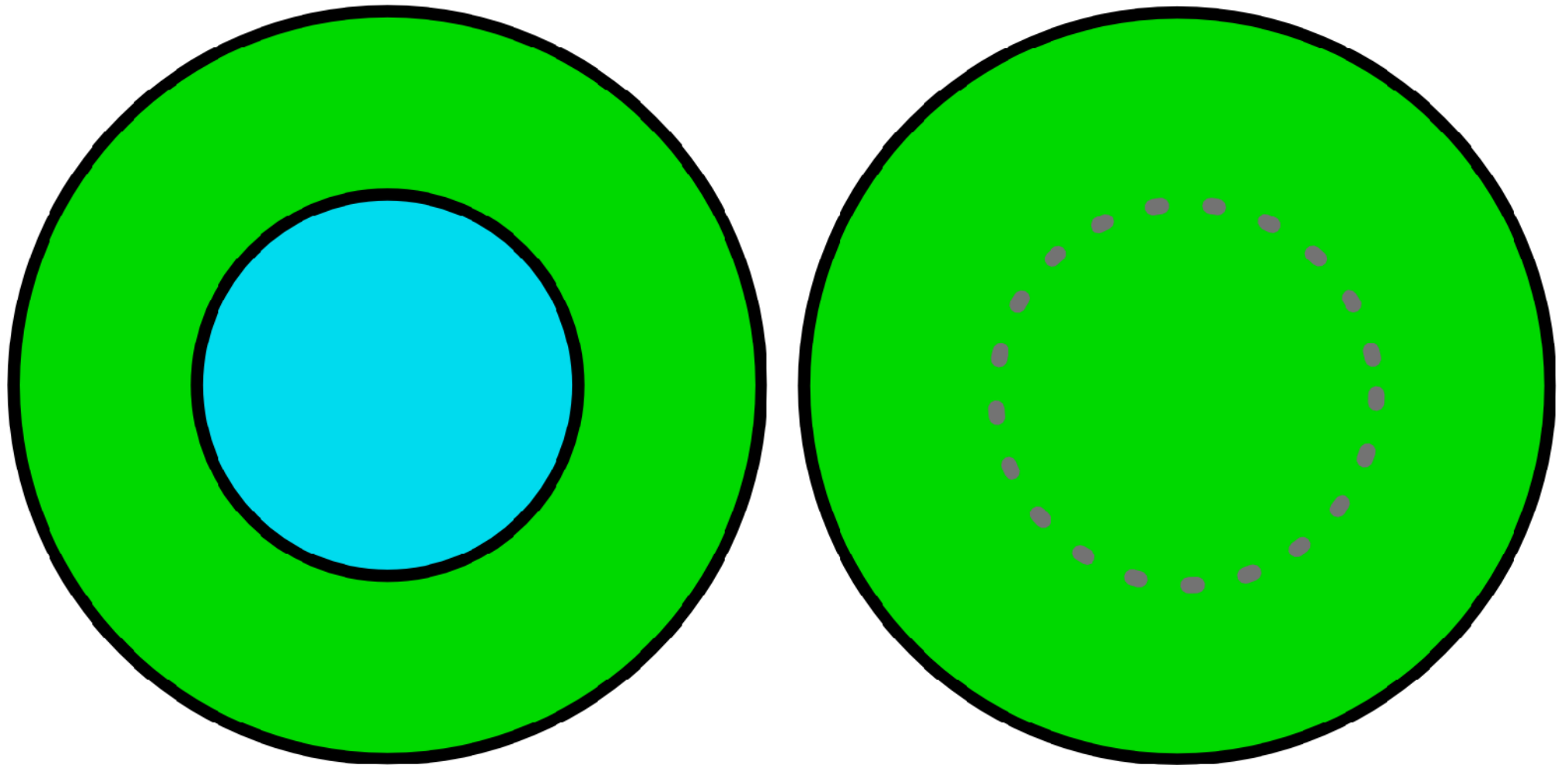
- Introduction to the problem
- Methodology: approach of research
- Relevant theories (background)
- Results
- Preliminary conclusions

Introduction

- Generalization: 'selection & simplification for appropriate detail and or purpose of maps' [ICA, 1973]
- Change in:
 - scale (paper) or level of detail (digital screen)
- Generalization by conceptual operator, implemented in GIS via algorithms [Galanda, 2003]:
 - Reclassification
 - Exaggeration
 - Simplification
 - Displacement
 - Collapse
 - Smoothing
 - Aggregation
 - Elimination
 - Typification
 - Enlargement

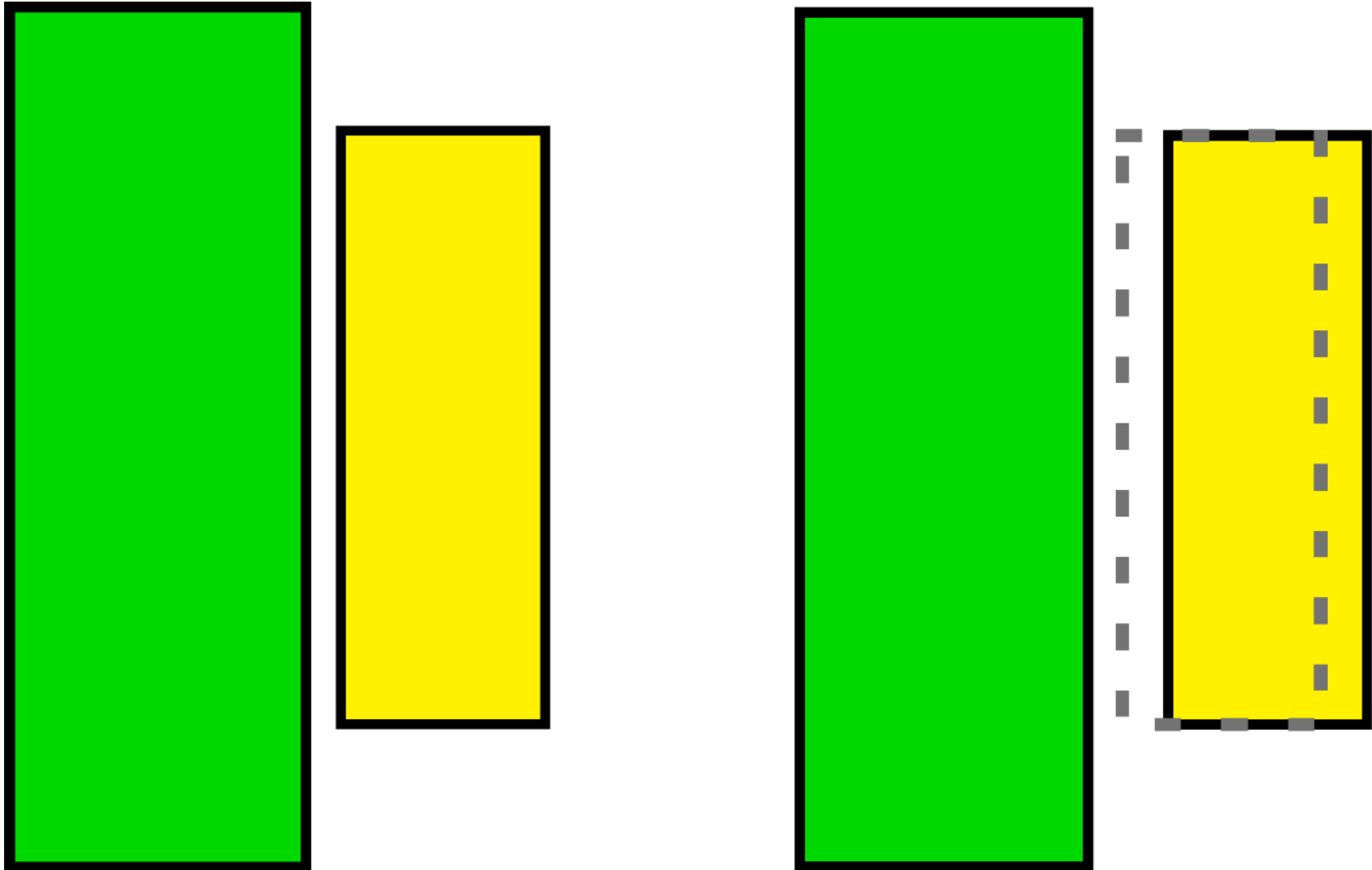
Example operator: reclassification

(taken from [Galanda, 2003])



Example operator: displacement

(taken from [Galanda, 2003])



Introduction

- Current approach (problematic, [Stoter, 2005]):
 - Problems with complexity of algorithms:
not in real time possible to calculate wanted level of detail
 - Multiple scale storage: waterfall like process
 - Problems with managing (updating) data:
redundancy
 - Not feasible in Spatial Data Infrastructure:
 - user interaction = real time
 - no pre-defined scale

Introduction

- New proposed approach [Van Oosterom, 2005 based on Van Oosterom, 1990 & Vermeij, 2003]:
 - Data structures (GAP-face tree & GAP-edge forest) store results of one-time calculation
 - No pre-defined scale: vario-scale
 - Topological data (references): no redundancy

Introduction

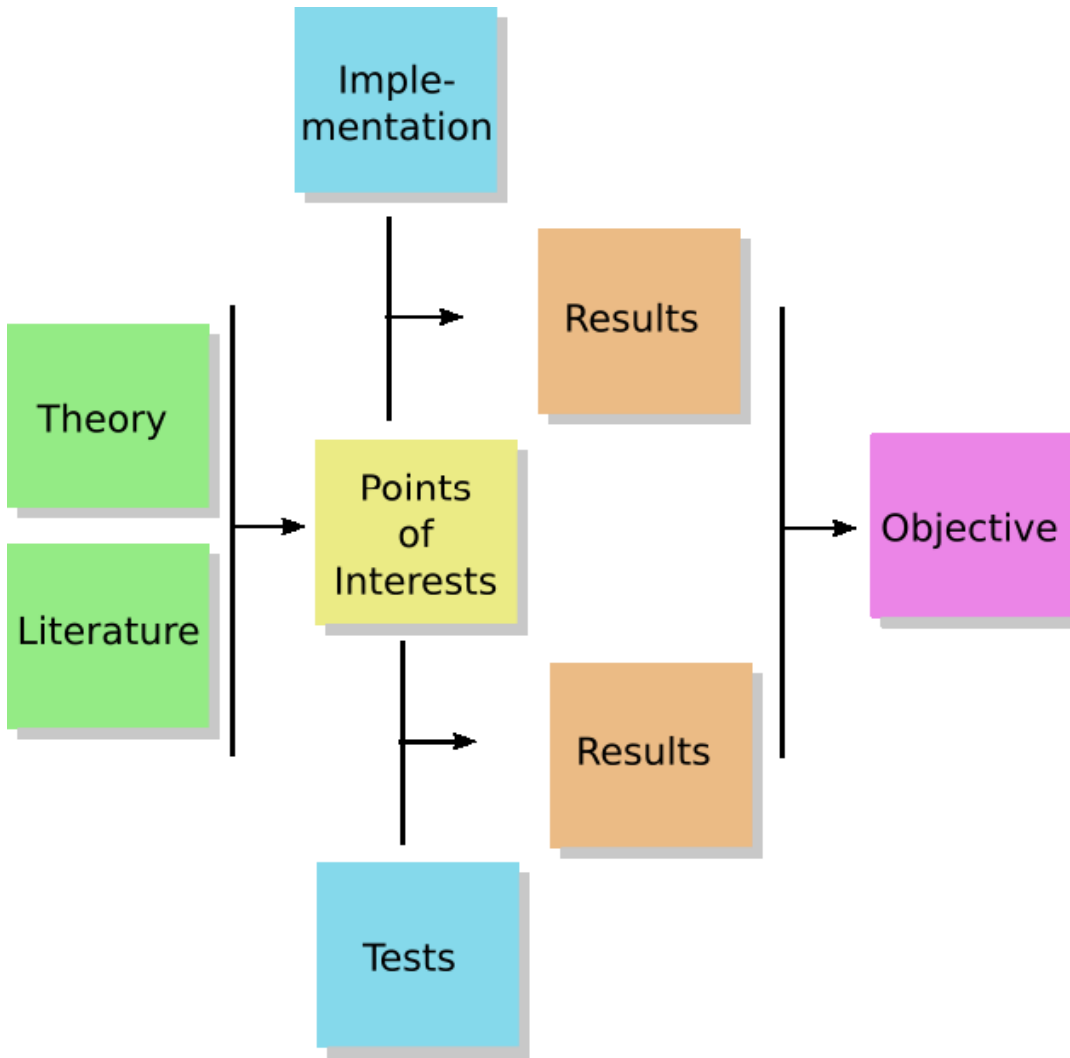
- Problem:
 - Only theory about new data structures
- Research objective:
 - Verification by:
 - literature study
 - Implementation experiment / test bed

Not: focus on generalization algorithms

But: focus on data structure:

- storing result of algorithms
- querying and visualization is possible on several levels of details (vario-scale)

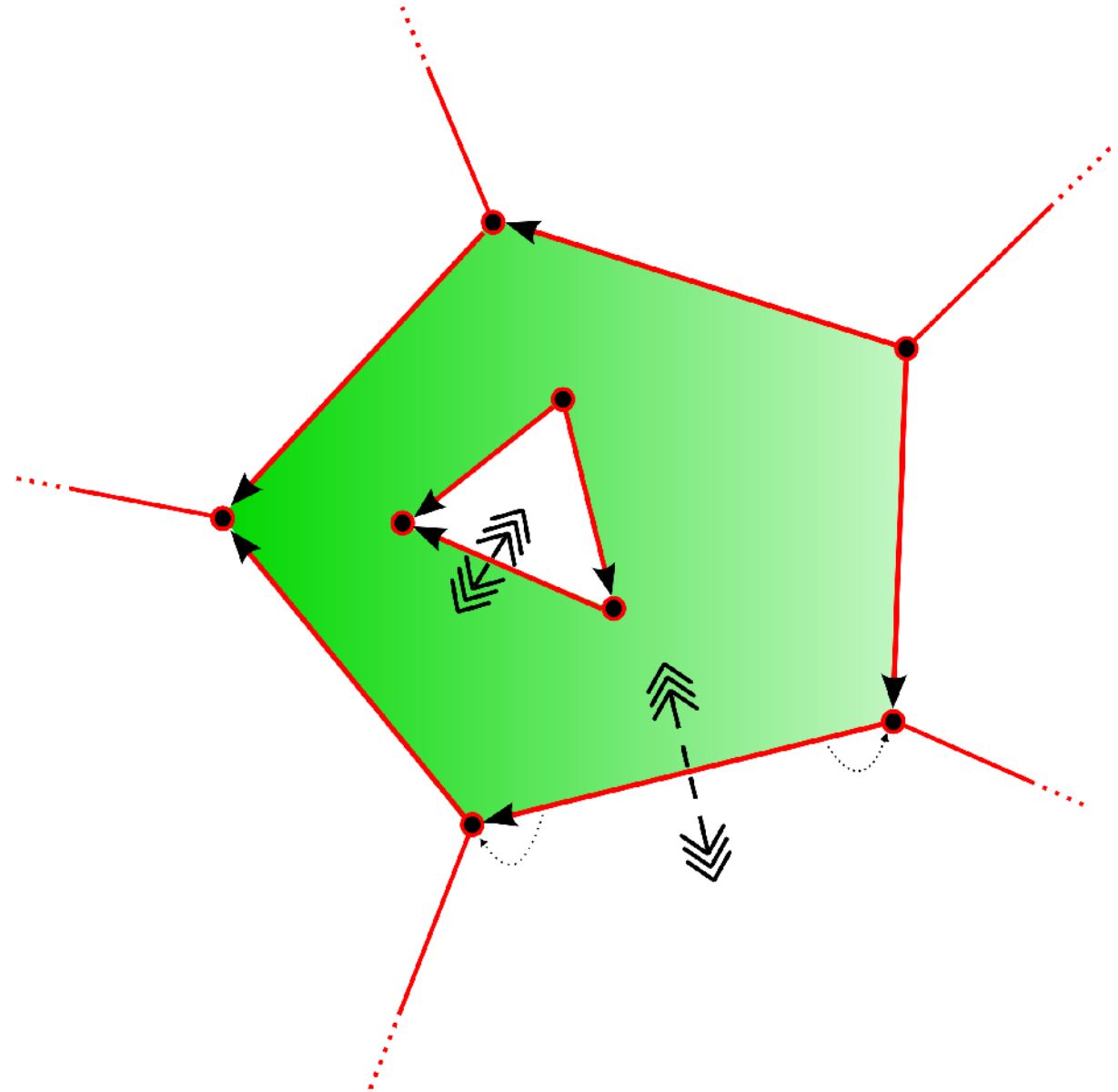
Methodology



- Research framework
 - Literature study
 - Experiment
 - Implementation: test bed
 - Tests
 - Results
 - Objective
 - Test performance (broadest sense) of data structures for generalization

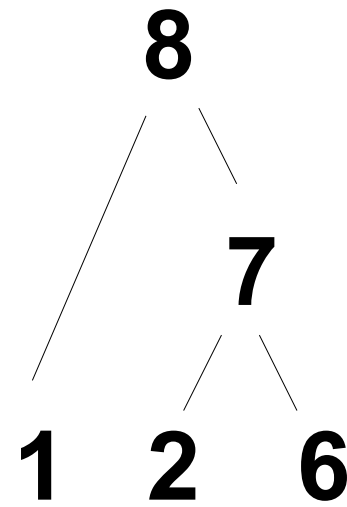
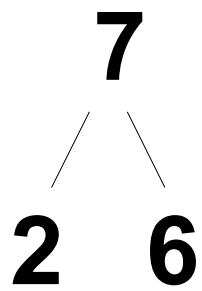
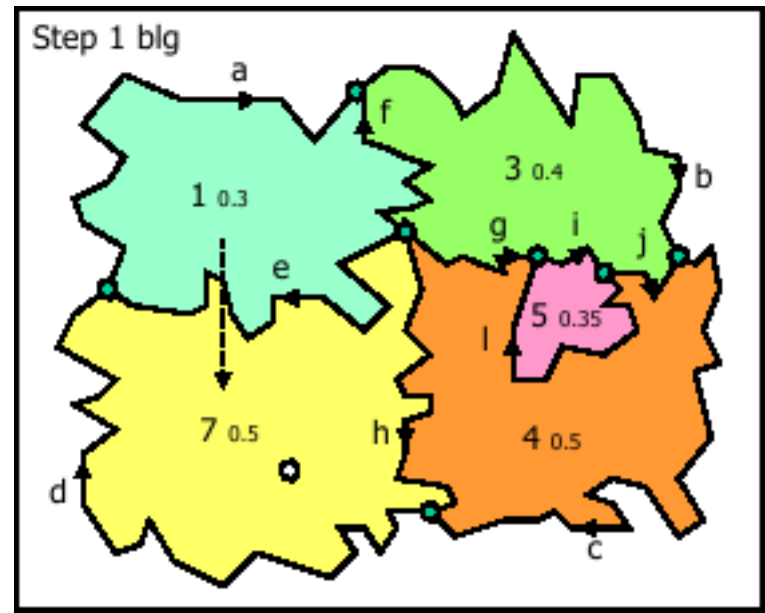
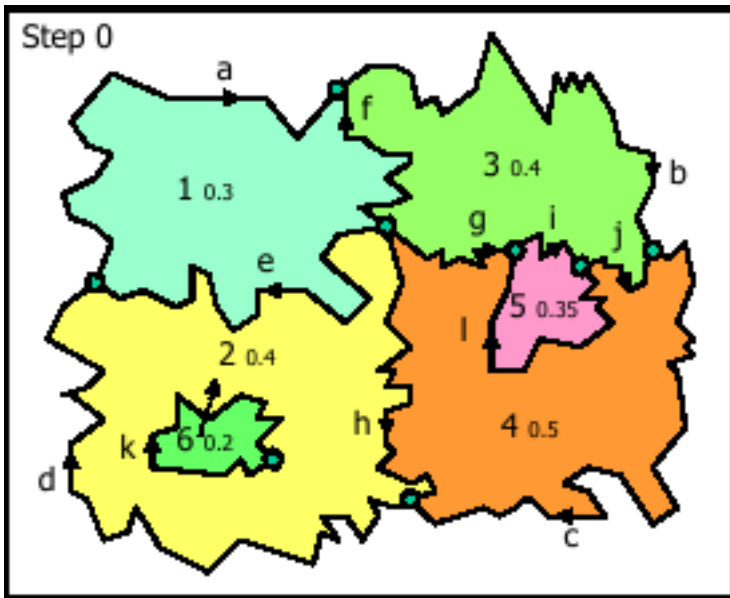
Background

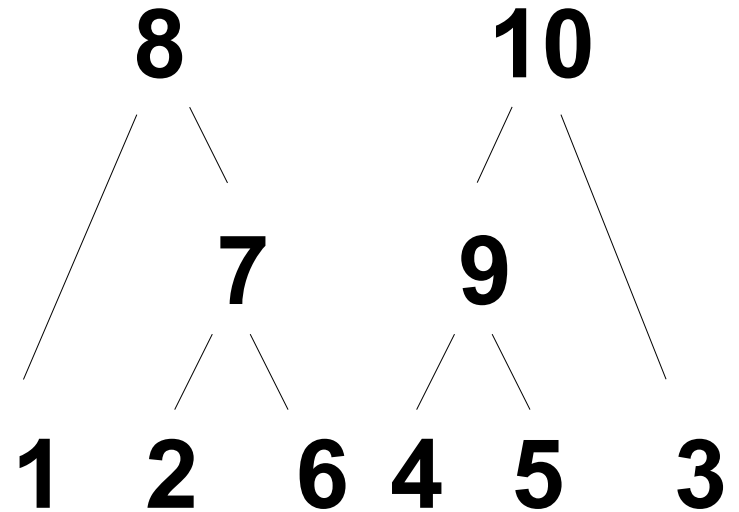
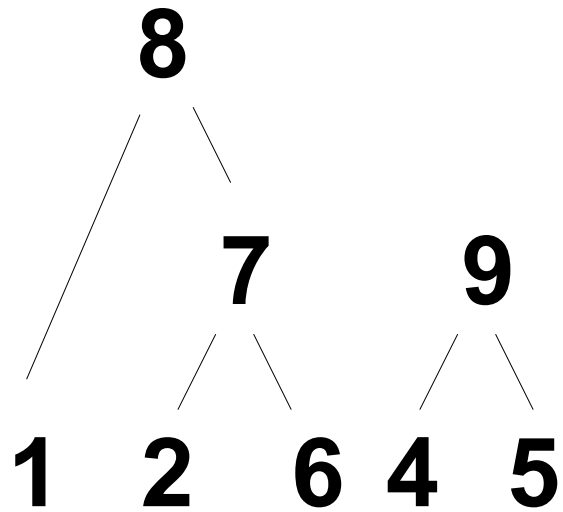
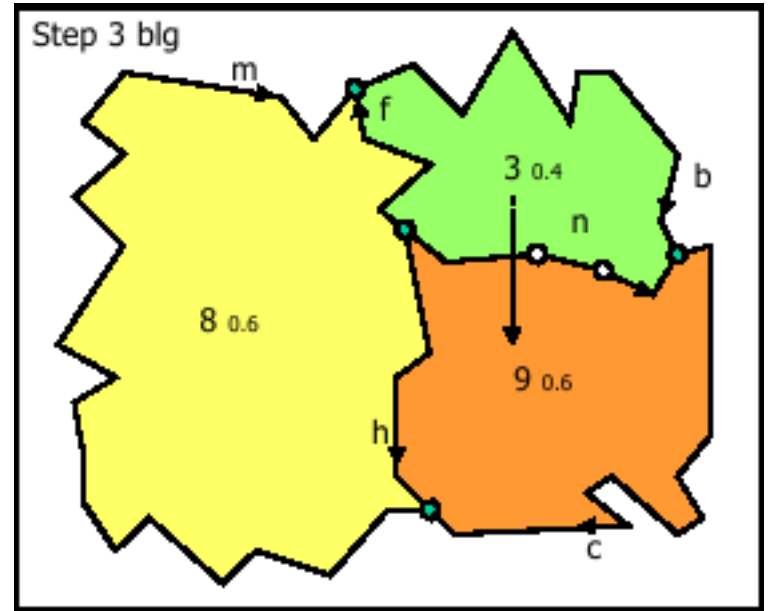
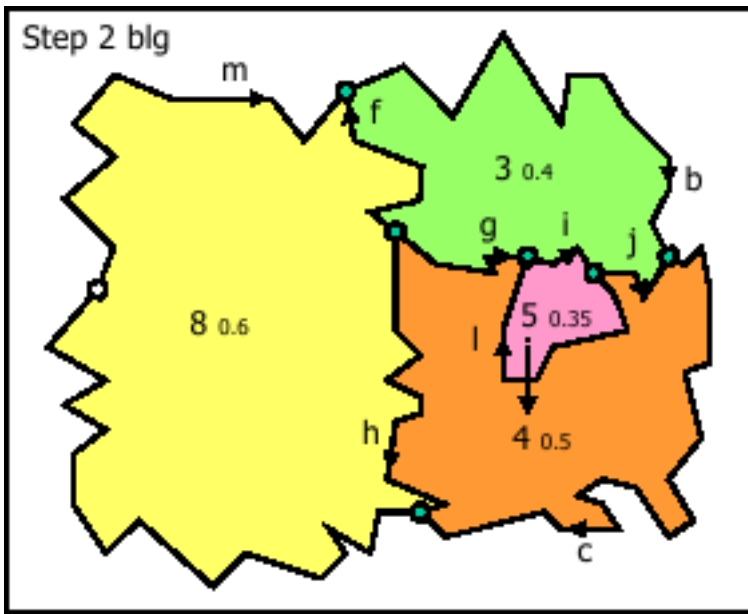
- Topology versus geometry
- Topological face:
 - {edges}
 - {nodes}
 - {references}

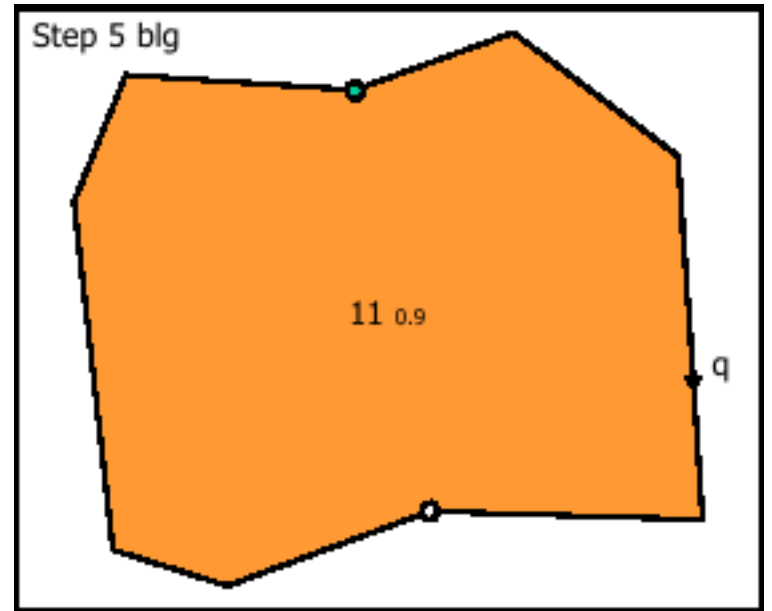
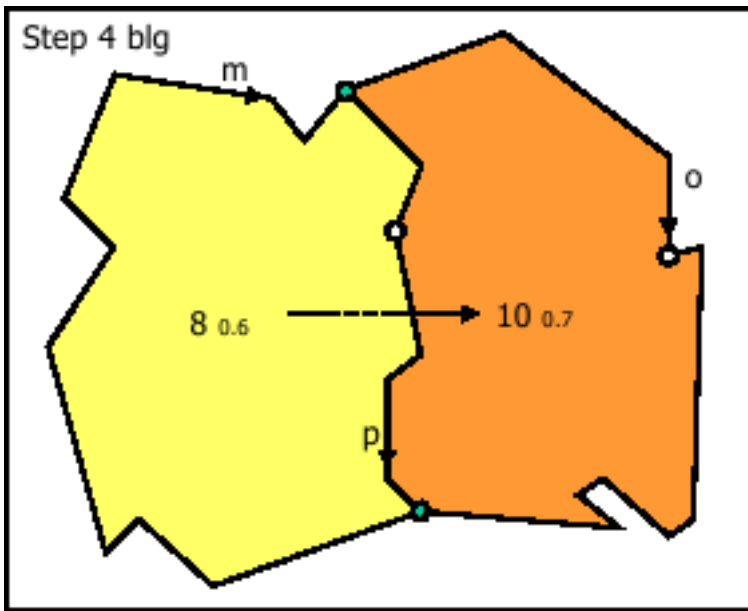


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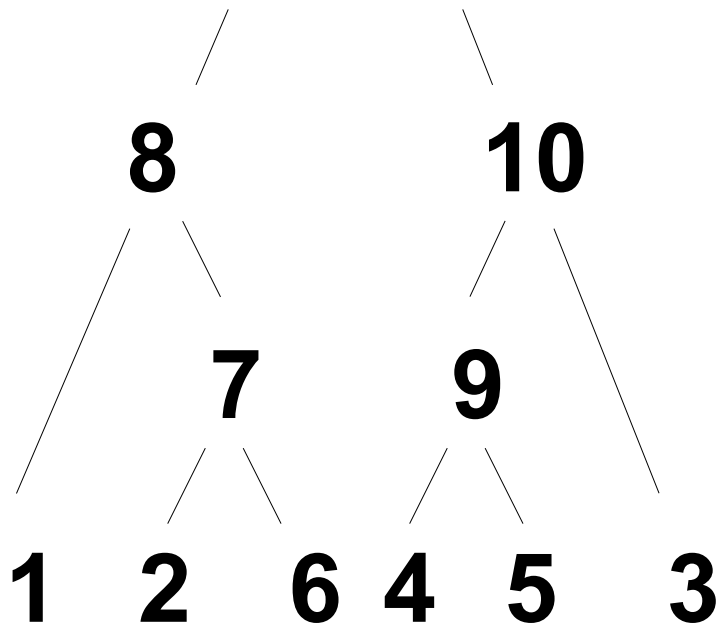
- GAP-face tree
 - Generalized Area Partition
 - Tree structure
 - Based on GAP-tree
- Store face information:
 - Which faces at which scale:
 - Selection on importance instead of scale
 - How faces are merged
- Example
 - Pictures taken from [Van Oosterom, 2005]

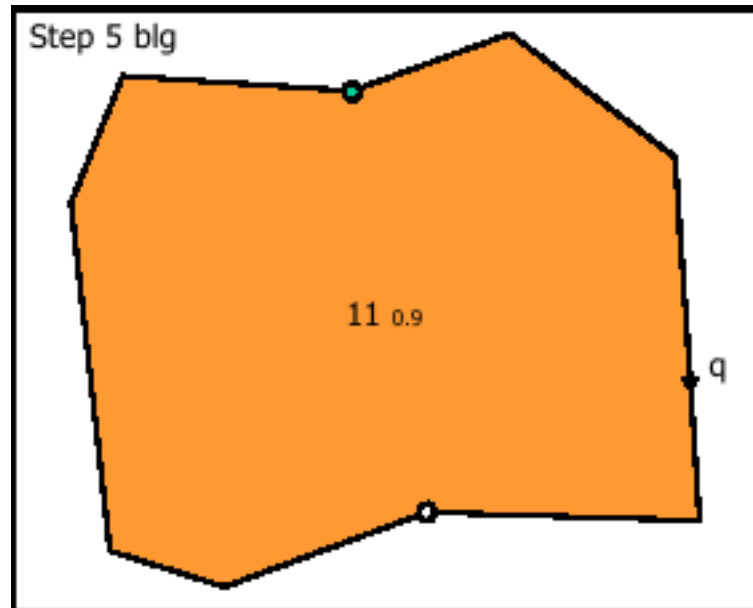
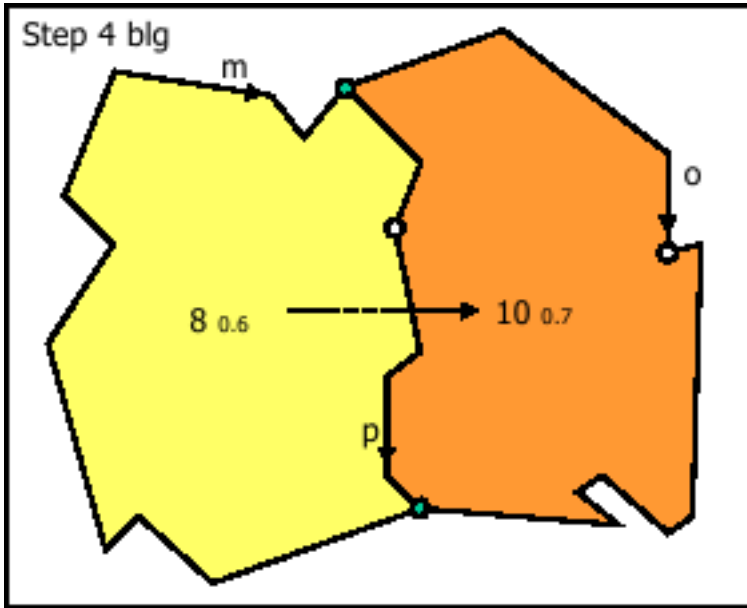




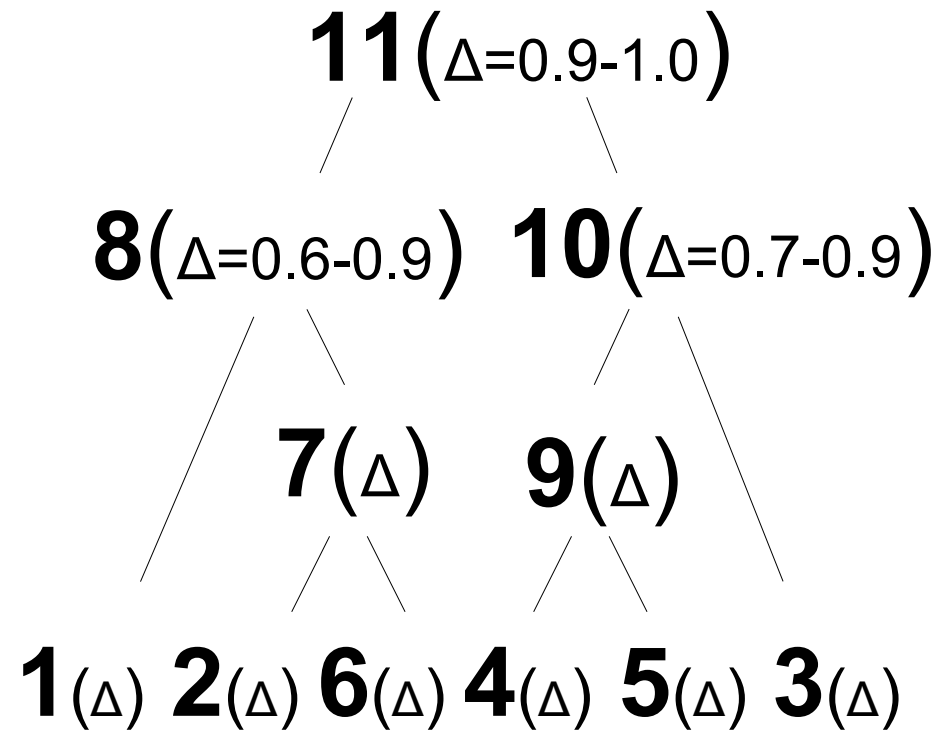


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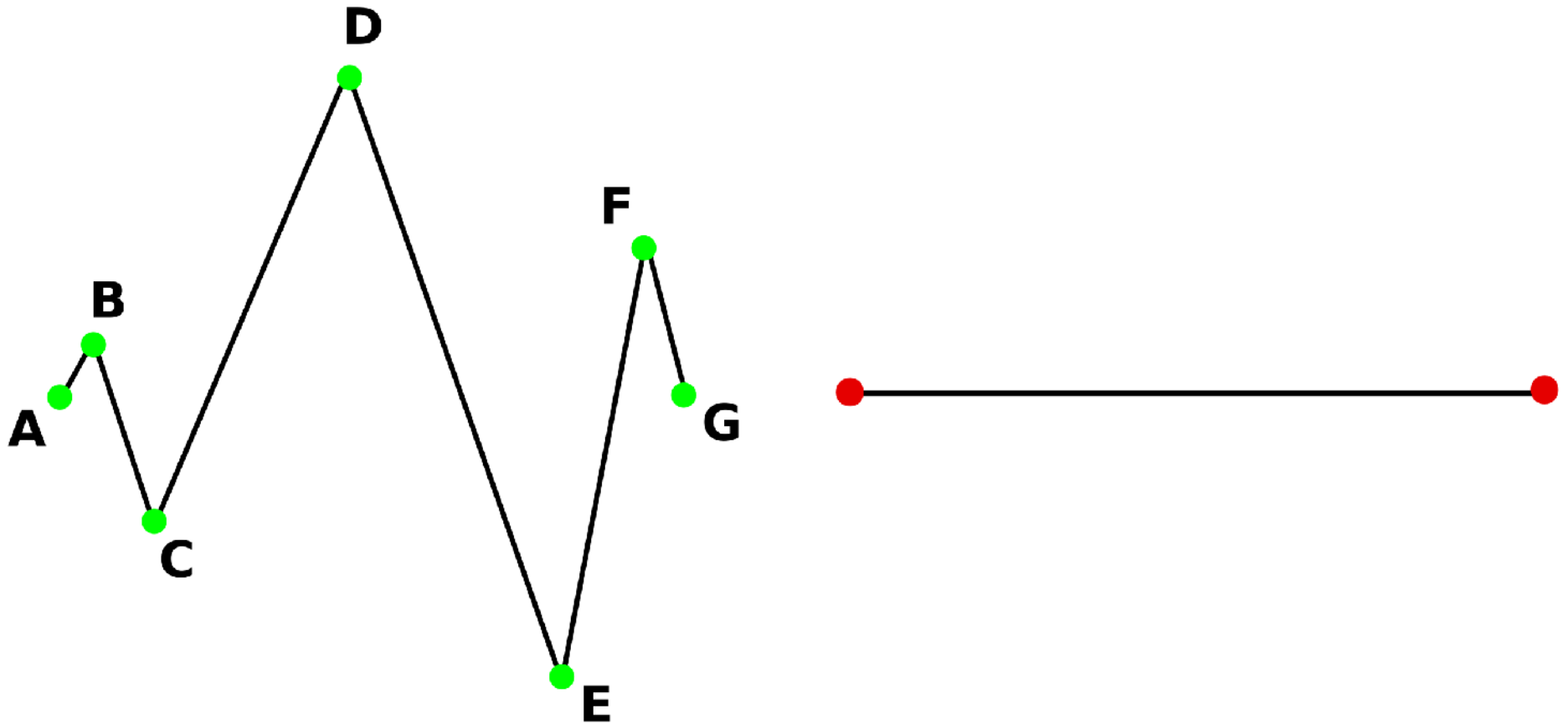
$$\Delta = [\text{imp_low}, \text{imp_high})$$

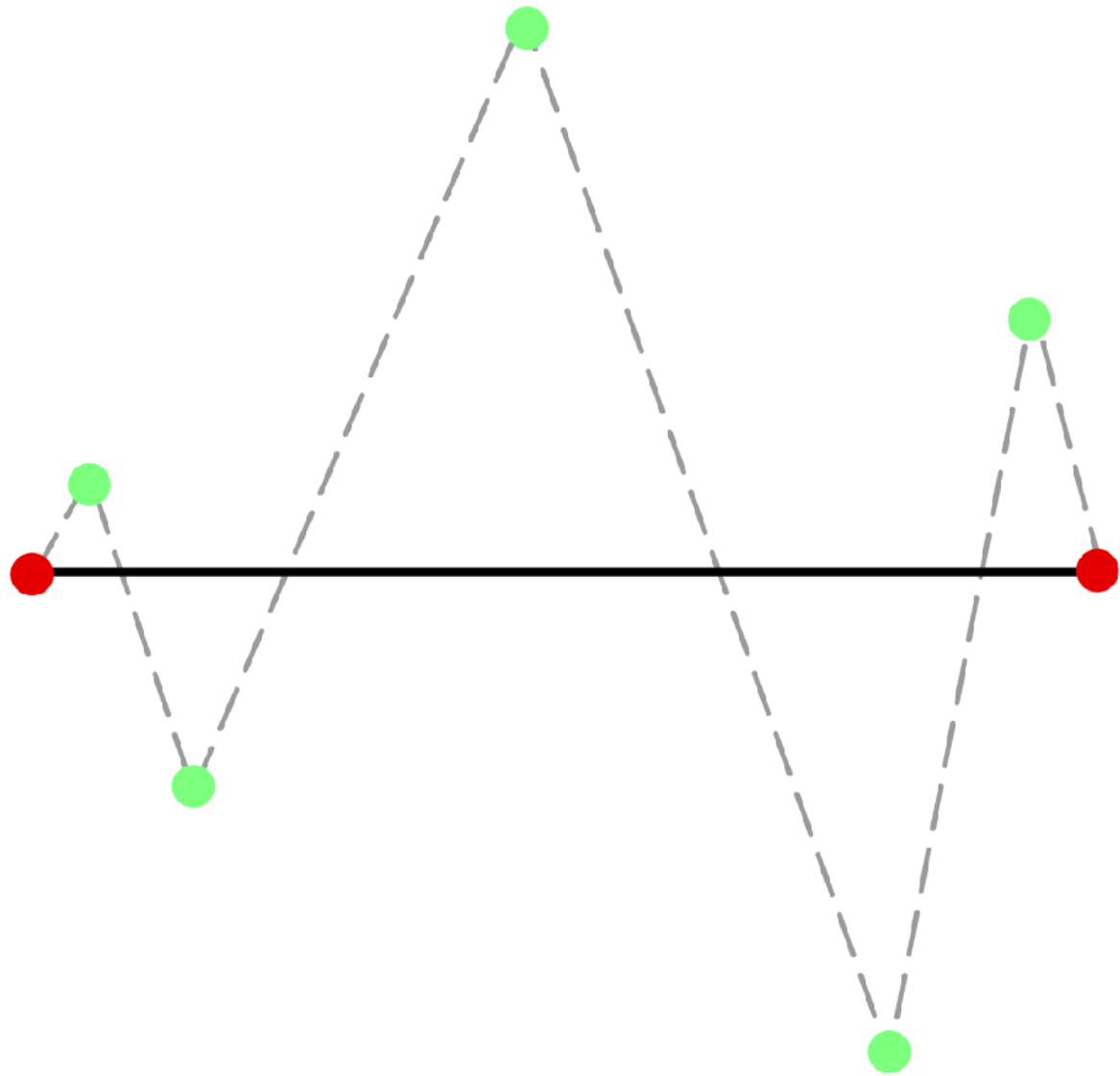


Background

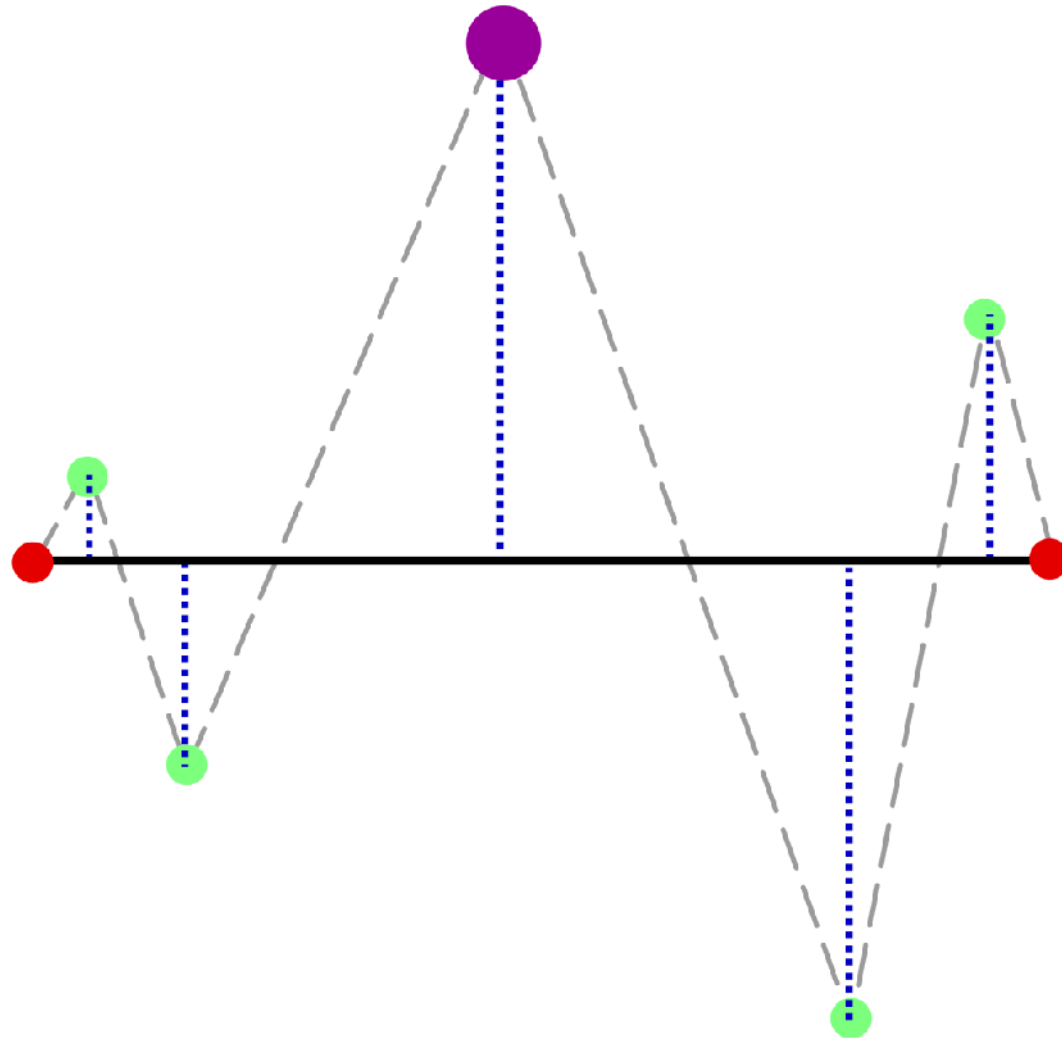
- GAP-edge forest (of trees)
 - Douglas Peucker algorithm [Douglas-Peucker, 1973]
 - BLG-tree data structure for storing result [Van Oosterom, 1990]
 - Binary Line Generalization
 - Tree structure
- Store edge information:
 - Generalized version & Non-generalized version in one tree
 - Merging of edges (with references) : forest

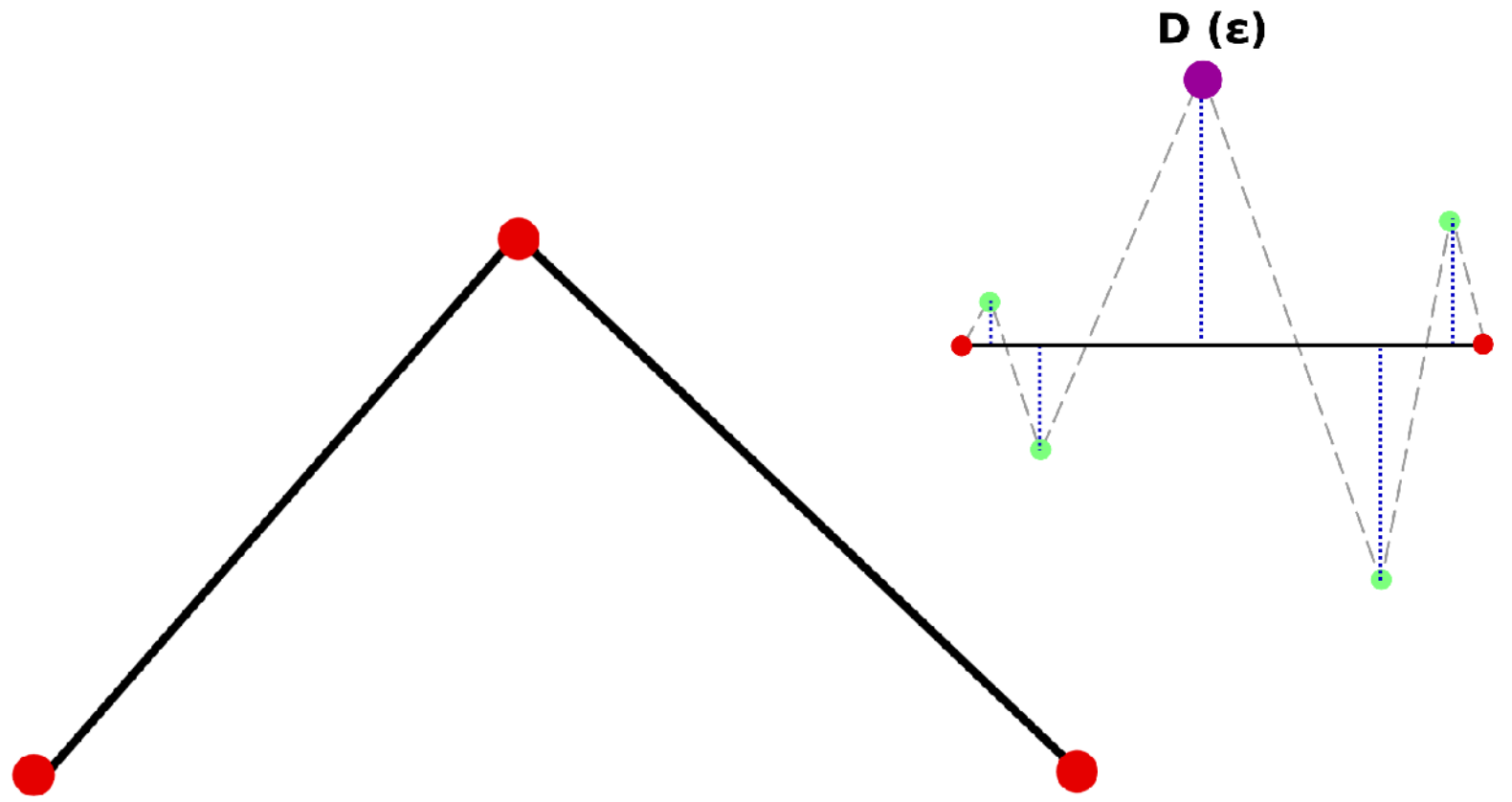
Douglas-Peucker Example

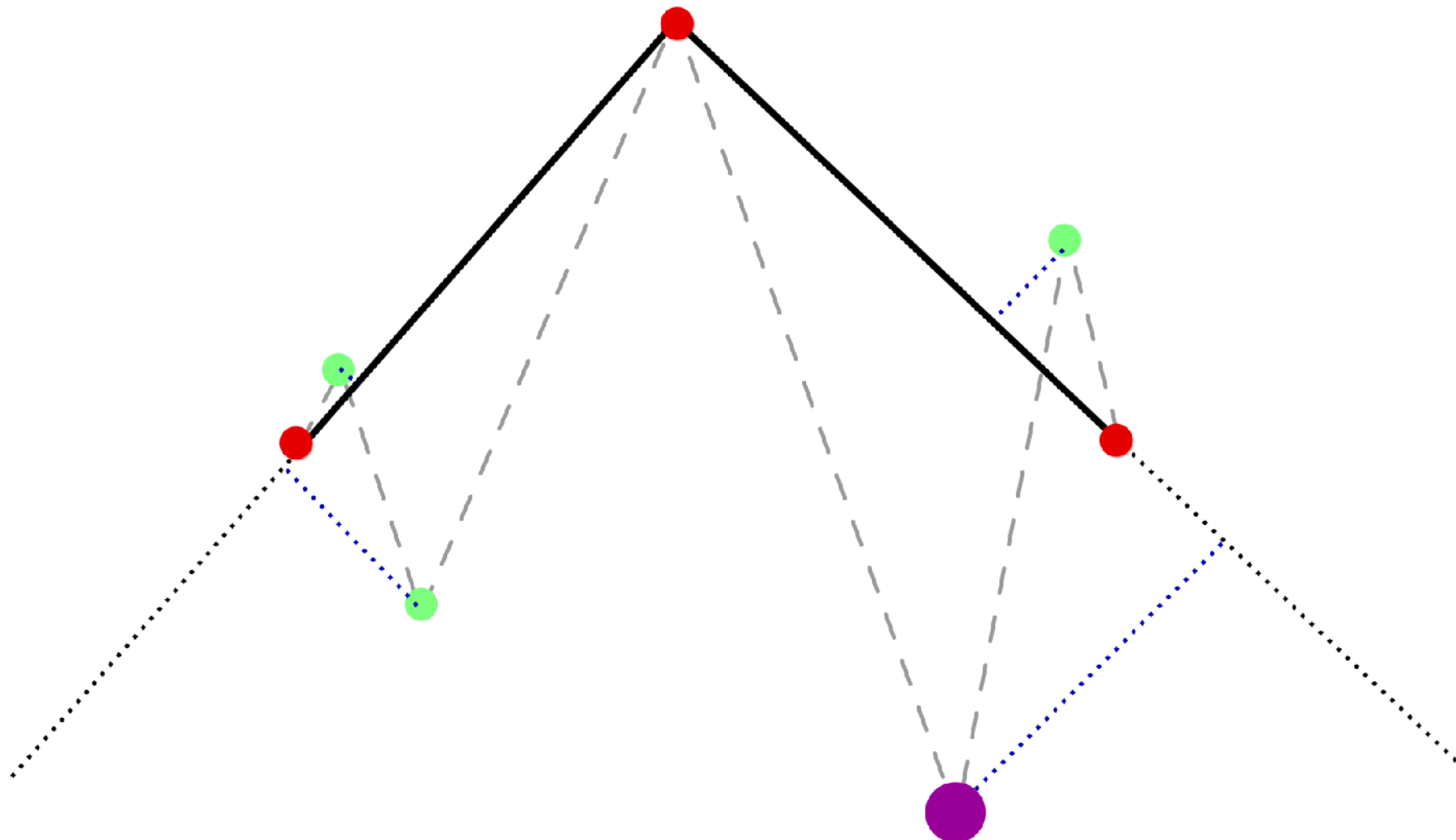




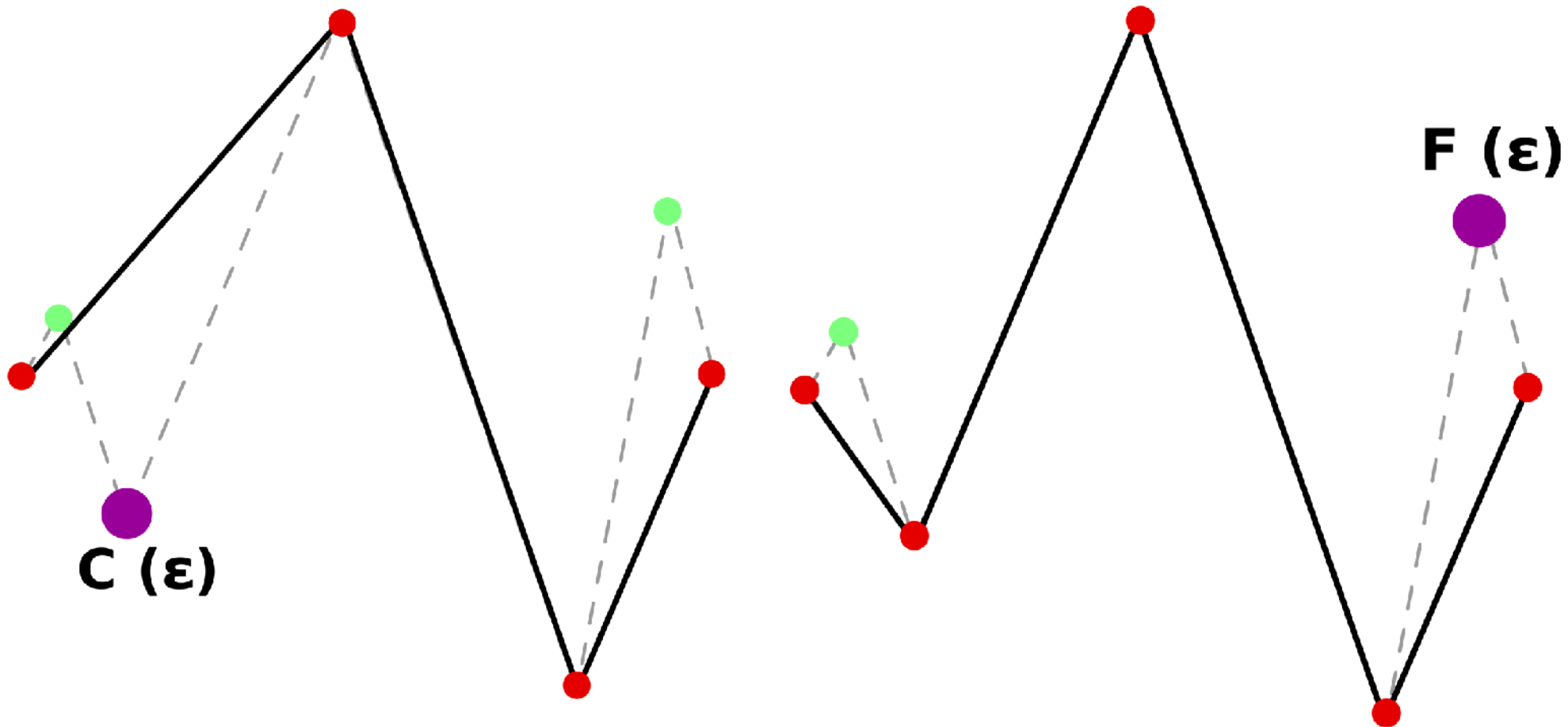
D (ϵ)







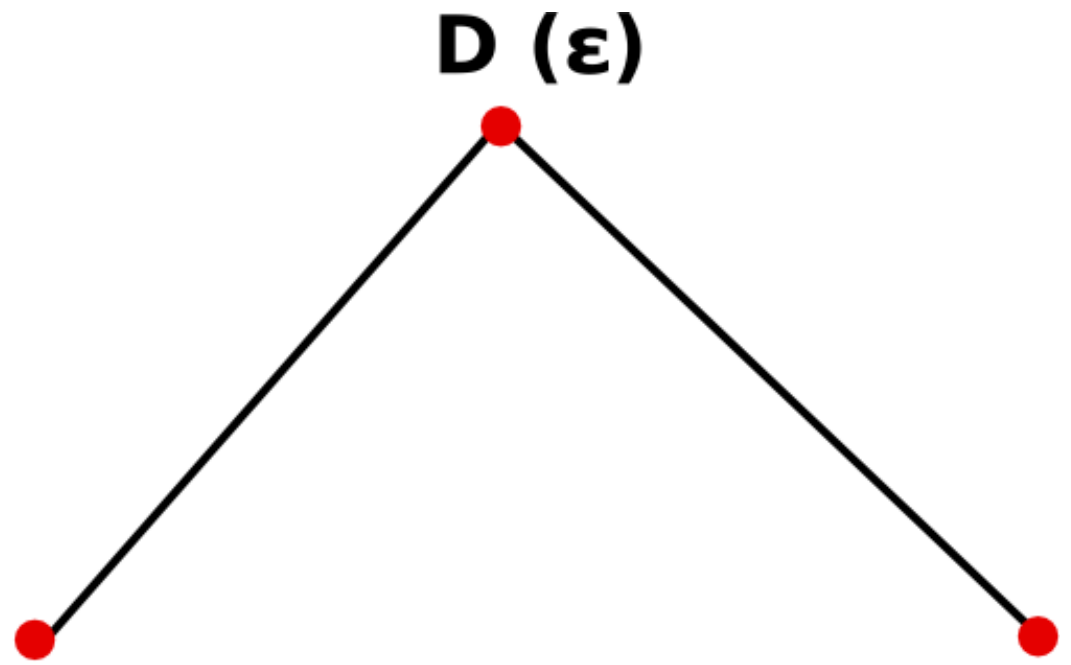
$E(\epsilon)$



Store D-P result in tree : BLG

- Calculation intensive algorithm
 - Each time calculate all distances to all remaining points
- Store result in tree
 - No need for computation
 - Get wanted level of detail of line from tree
- Binary Line Generalization tree
 - example with previous line

D (ε)

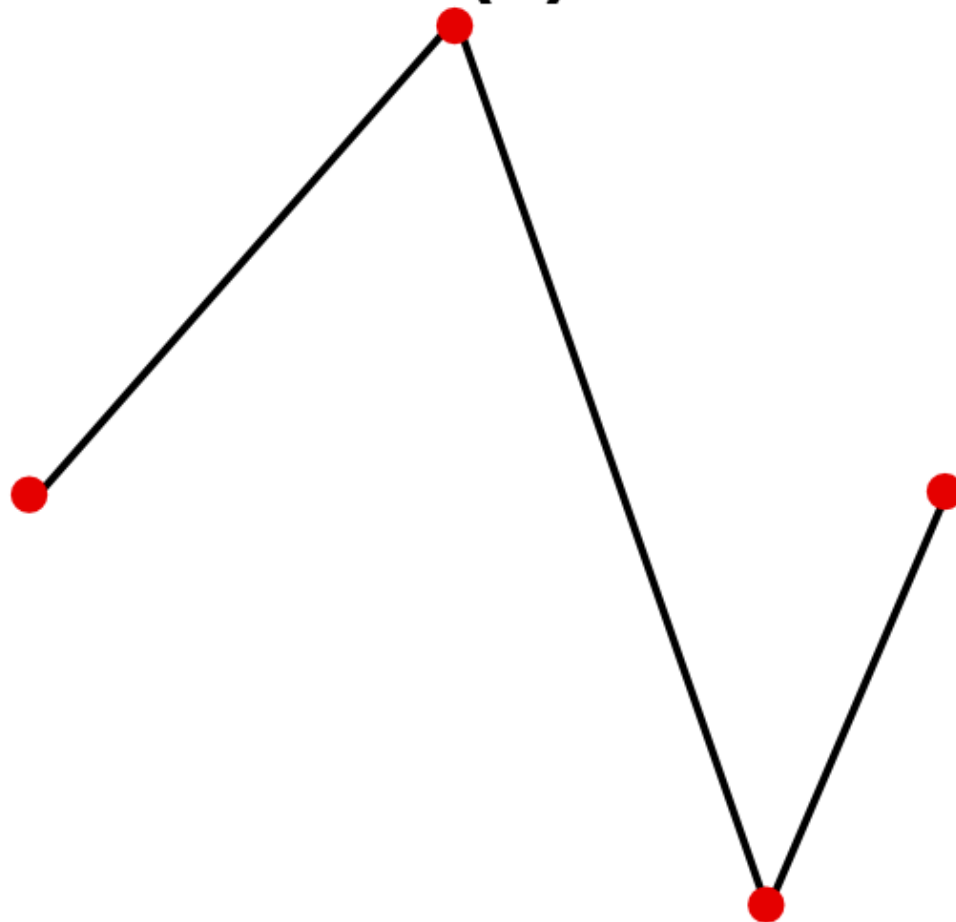


D (ϵ)

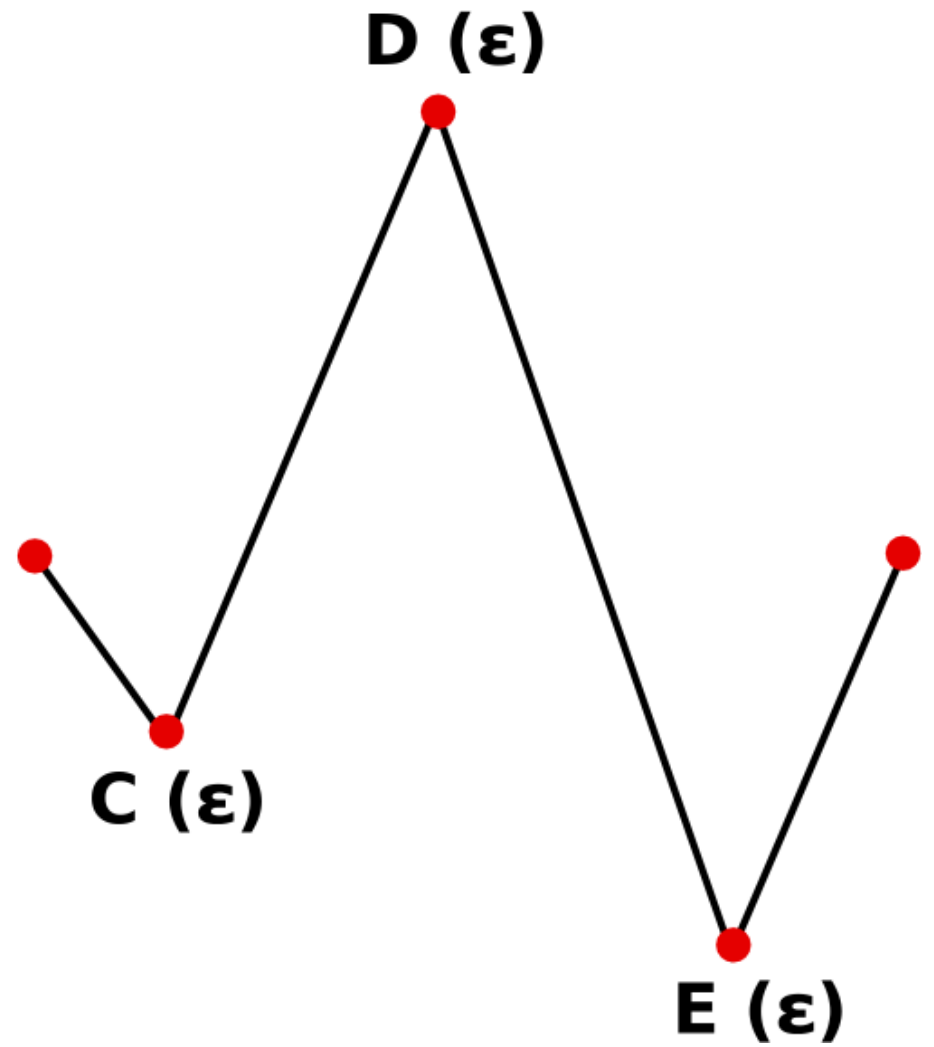
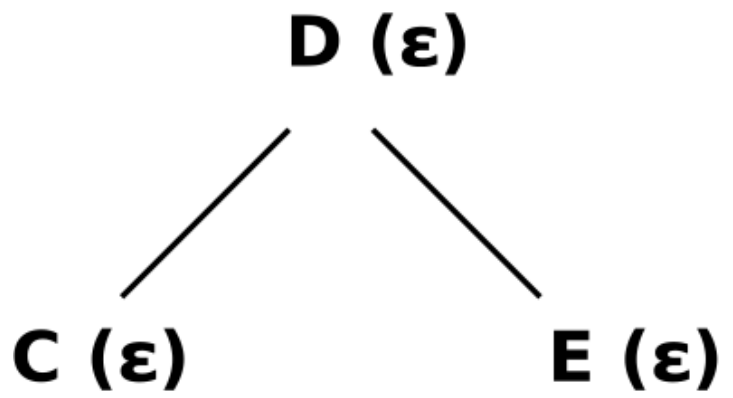


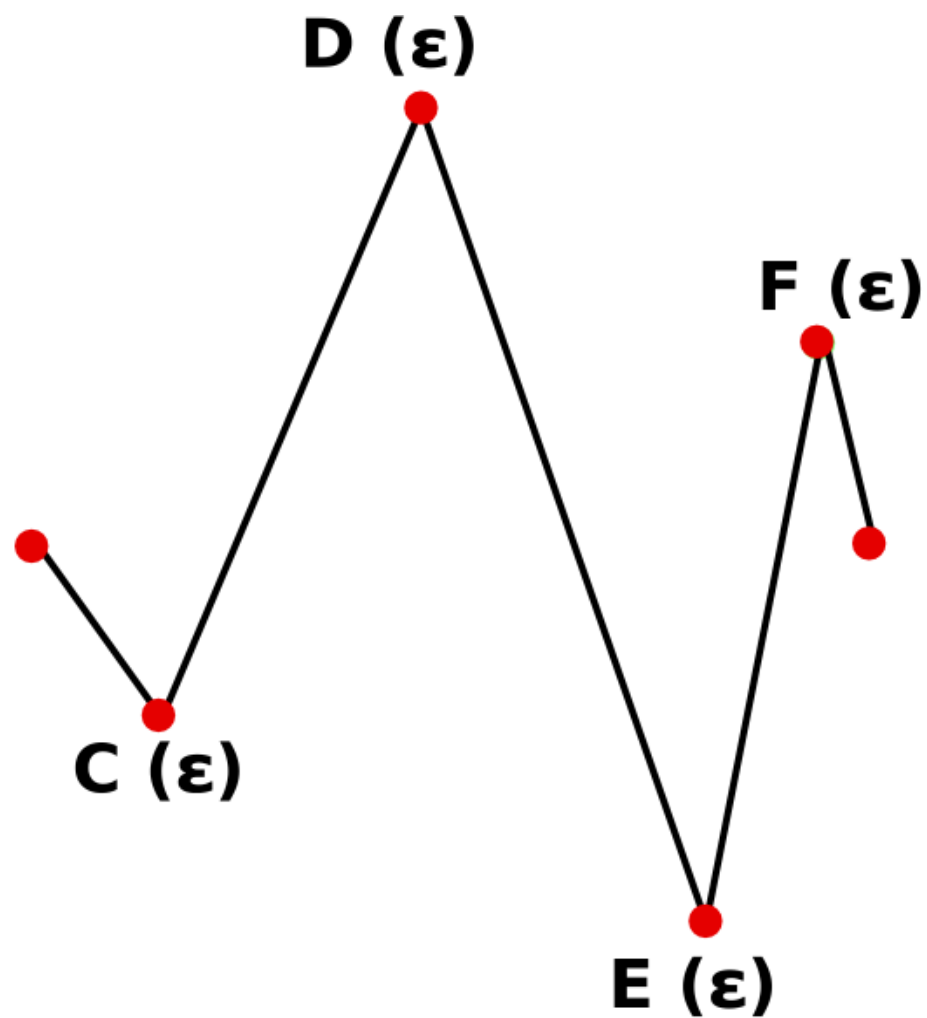
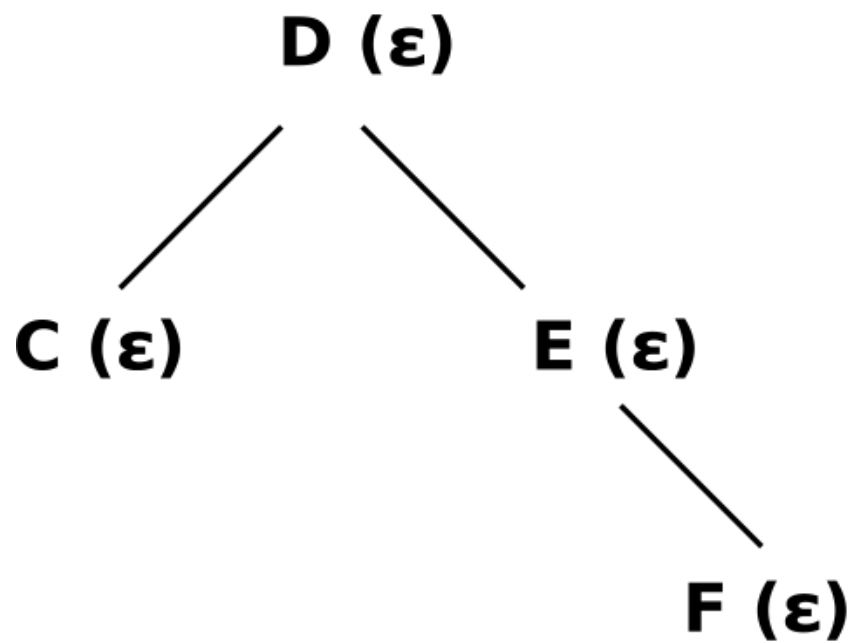
E (ϵ)

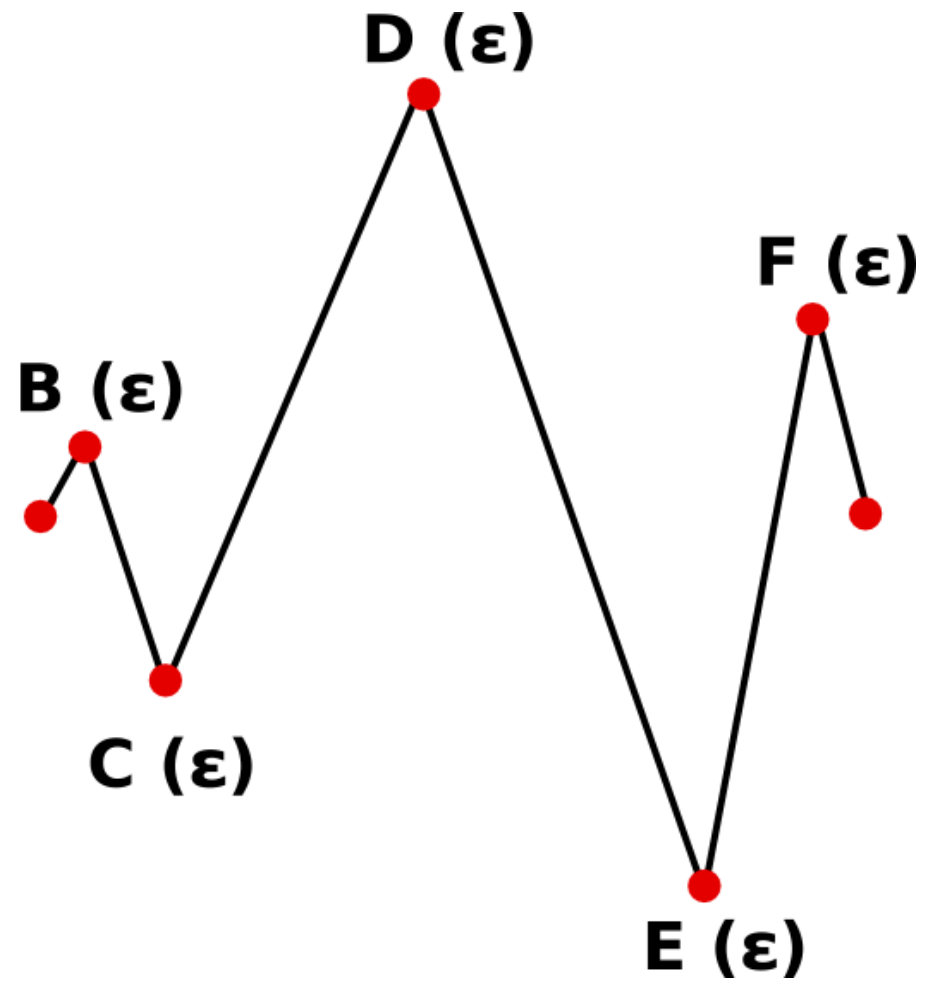
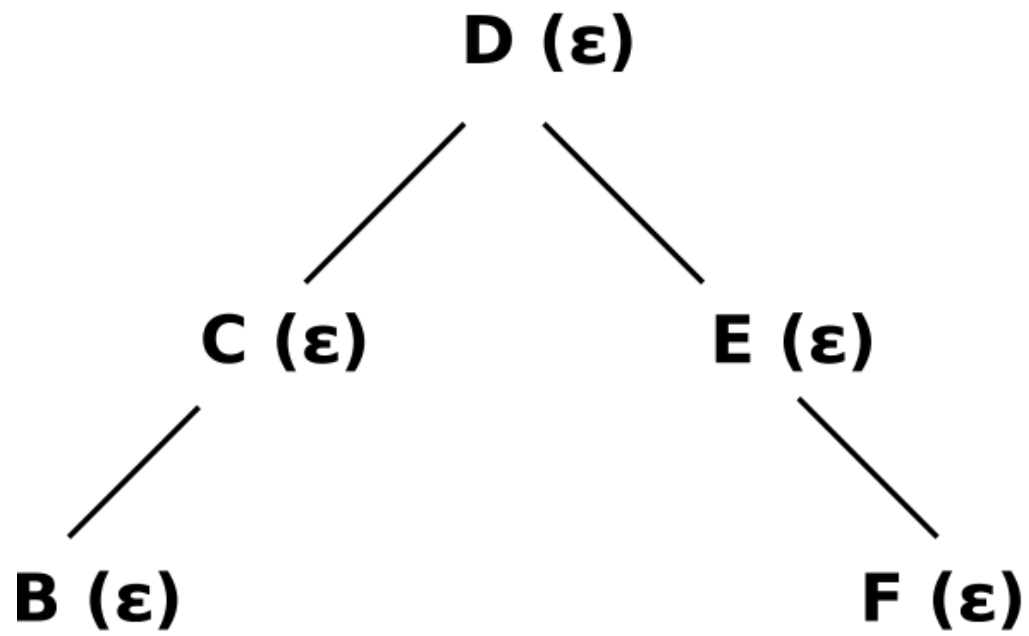
D (ϵ)



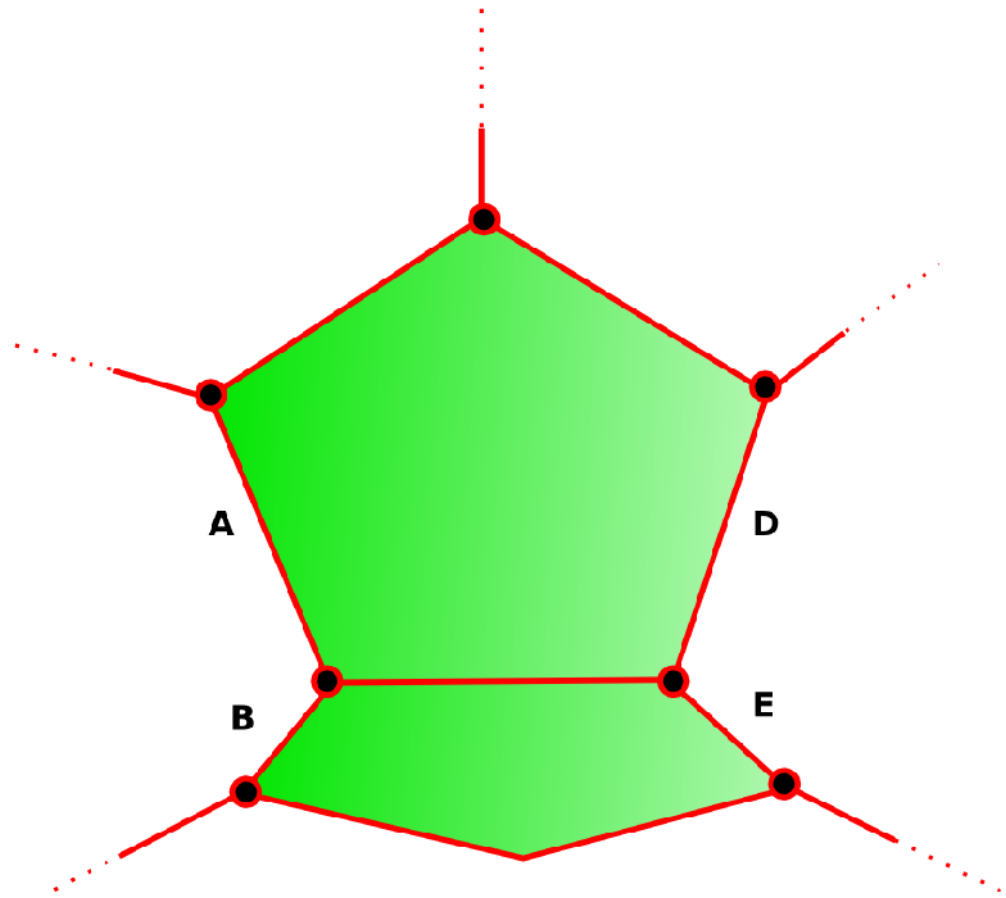
E (ϵ)



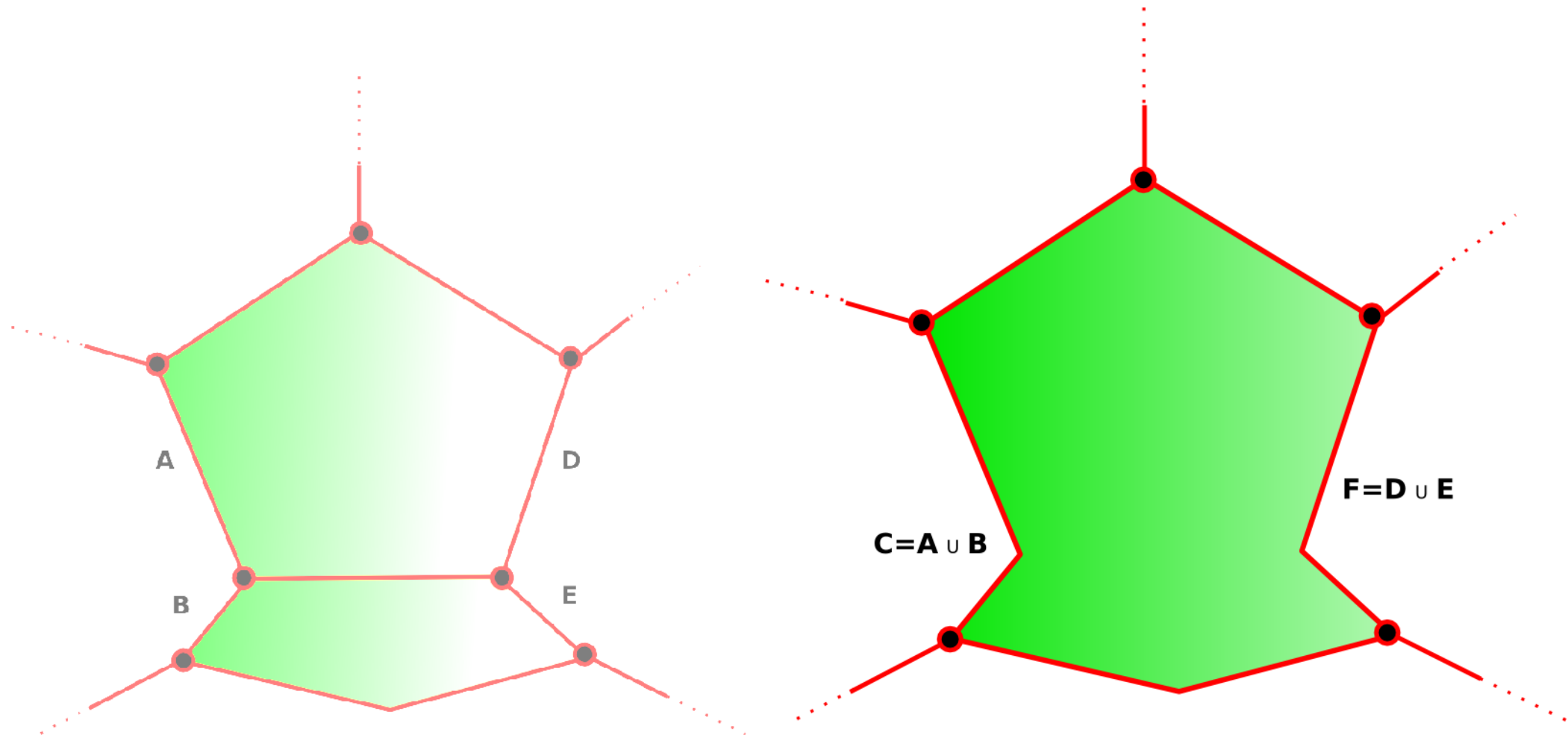




Combine into forest : Union edges



Combine into forest : Union edges



Background

- *What are the good things about having these data structures inside the database for generalization?*
 - Non-redundant storage
 - Makes it possible to use generalized data, avoiding need of real time computation:
 - Calculate once, store result, query, retrieve & visualize
 - Test bed for other research:
 - Suitable for progressive refinement (first send coarse data, then refine, until given criteria) & interface design [De Vries & Van Oosterom, 2006]

Results

- *How can the GAP-face tree and GAP-edge forest be implemented in an object-relational DBMS*
 - Spatial data types
 - Programming interface required
 - Extensible database : custom data type
 - Indexing: B-tree (numeric data) & R-tree (spatial data [in 2d and 3d!])

Results

- Implementation:
 - Tables & Indexes
 - Algorithm for filling tables (= building GAP-face tree)
 - Binary Line generalization:
 - Data type for holding BLG-trees + filling algorithm
 - Algorithm for recursively merging BLG-trees
 - Algorithm to get geometry from BLG-tree at certain depth
 - Reconstruction of geometry of topologically stored faces
 - Middle layer: database – Google Earth

Results

- *What problems occur when implementing the data structures inside the database?*
 - Minor changes needed in some algorithms
 - No indexing: no performance, due to huge amounts of data:
 - kadedge table (original): 178,815 entries
 - tgapedge table (GAP edge forest): 3,258,262 entries
 - Mapping 'importance' \leftrightarrow 'scale' \leftrightarrow 'BLG(ϵ)' is not linear: unknown relation, differ per dataset?
 - BLG might be self intersection: prohibit with constraints in calculation (known):
 - But, also with merging of BLG's!
- However, it works...



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Streaming ||||| 100%

Eye alt 54.37 mi



Hurwenensc

Zaltbommel

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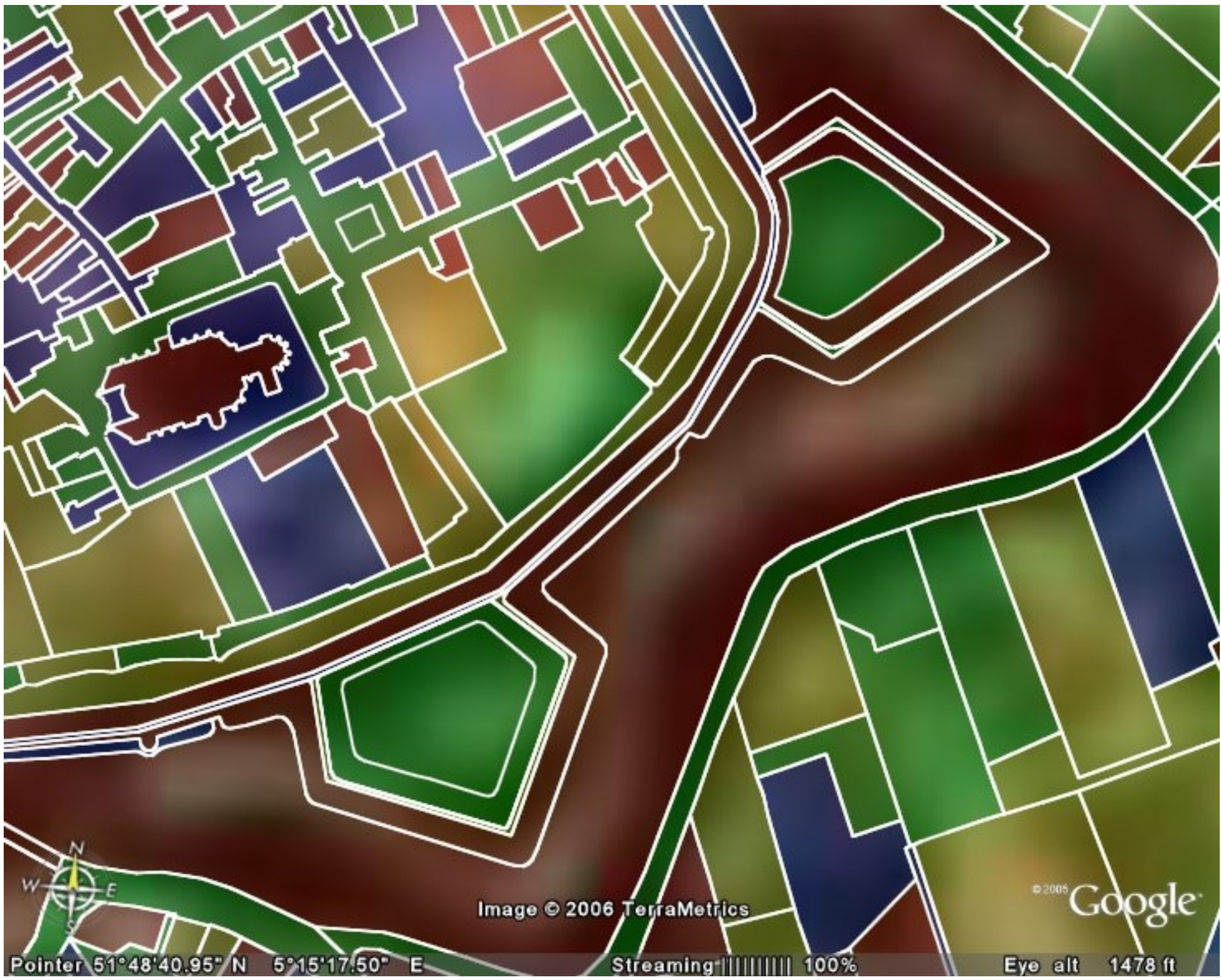


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To do

- *How can we assess the performance of the implemented structure?*
 - First solve how to use the data structure efficiently, especially mapping between:
 - Scale
 - Importance
 - BLG tree: ε
- Write thesis

Conclusions

- *What do we learn from an implementation of the GAP-face tree and GAP-edge forest in an object relational management system?*
 - Approach is feasible
 - Possible to implement – with some minor adjustments to the theory as described in [Van Oosterom, 2005]
 - Calculate once, visualize & query real time
 - No redundancy of geometry

Questions / Discussion

Now (or later...)

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