

Variable scale topological data structures for geo-information

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3rd Dutch Computational Geometry Day, TU Eindhoven

March 7, 2007

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Section GIS Technology



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1. Introduction

- Multi-scale databases: often multiple representation
drawbacks: redundancy, fixed levels of detail
- Scaleless data structures: single representation with additional structure to access at any level of detail
- Often also spatial organization (clustering/indexing)
- Progressive transfer: keep sending more details (compare to raster formats: data pyramids, wavelets)

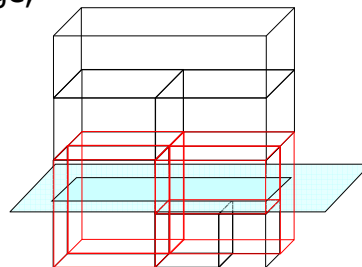
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1. Generalized Area Partitioning-tree (GAP-tree) history

- In normal GAP-tree (van Oosterom 1993) areas are stored as independent polygons, drawback (computed) redundancy
- Vermeij et al.'03 proposed topological GAP-tree: edges and faces (with importance range, consider as height), reduced redundancy between neighbors
- **Still some redundancy left: coordinates in higher level edge also present in lower (more detailed) level edges**



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1. tGAP structure (GAP-face tree + GAP-edge forest)

- Also coordinate redundancy between edges at different aggregation levels is removed
- Throughout remainder of presentation examples of the tGAP-structure (creation and use) will be shown
- Creation of the tGAP-tree is shown in pairs of steps
 1. removal of least important face (merge face)
 2. removal of edges, merge of edges (BLG-tree)

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1. Proposed solution: tGAP structure

- Variable scale: infinite amount of levels
- Base level with most detailed geometry/topology
- Create links/structure on top

- Only theory → validate
- Last year at Autocarto 2005, presentation was concluded with question: **What is the price of non-redundancy, that is, the many references?**

- Test and implement structure

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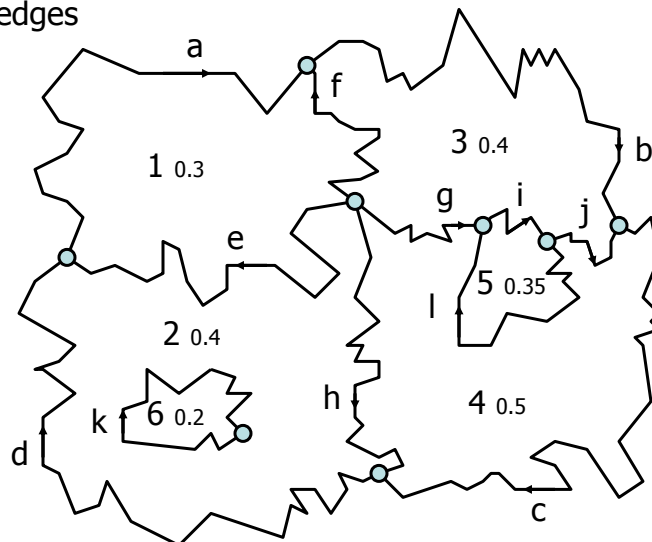
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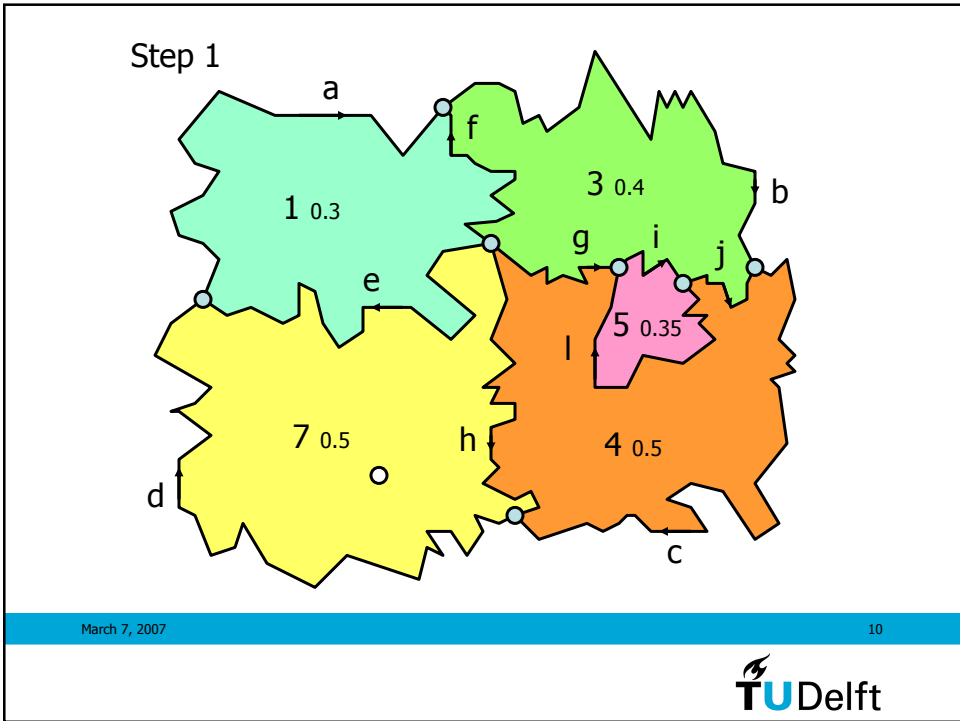
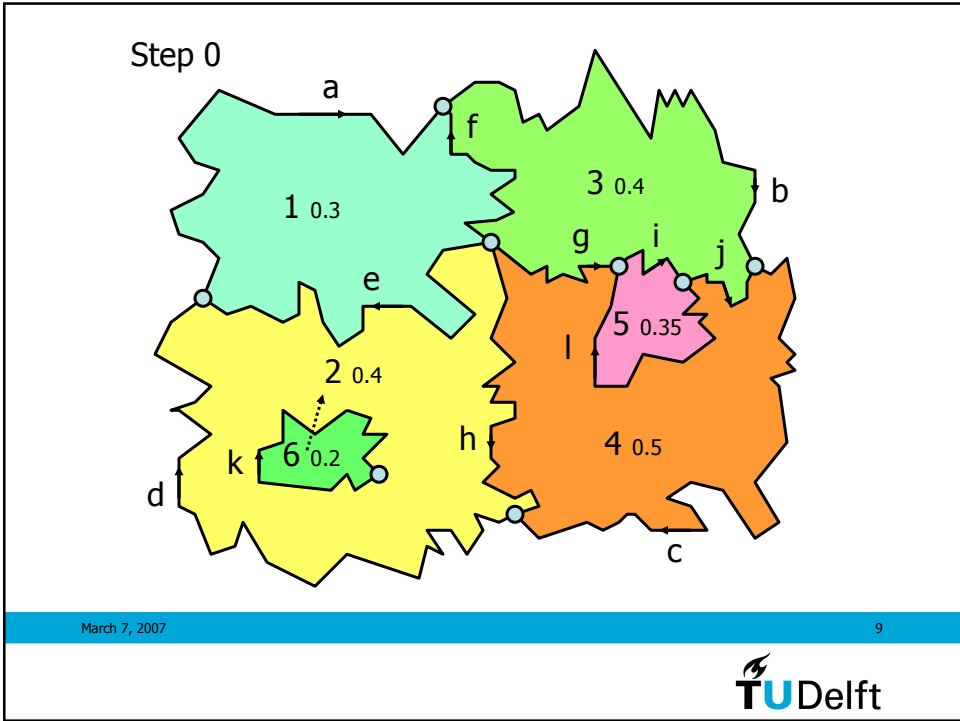
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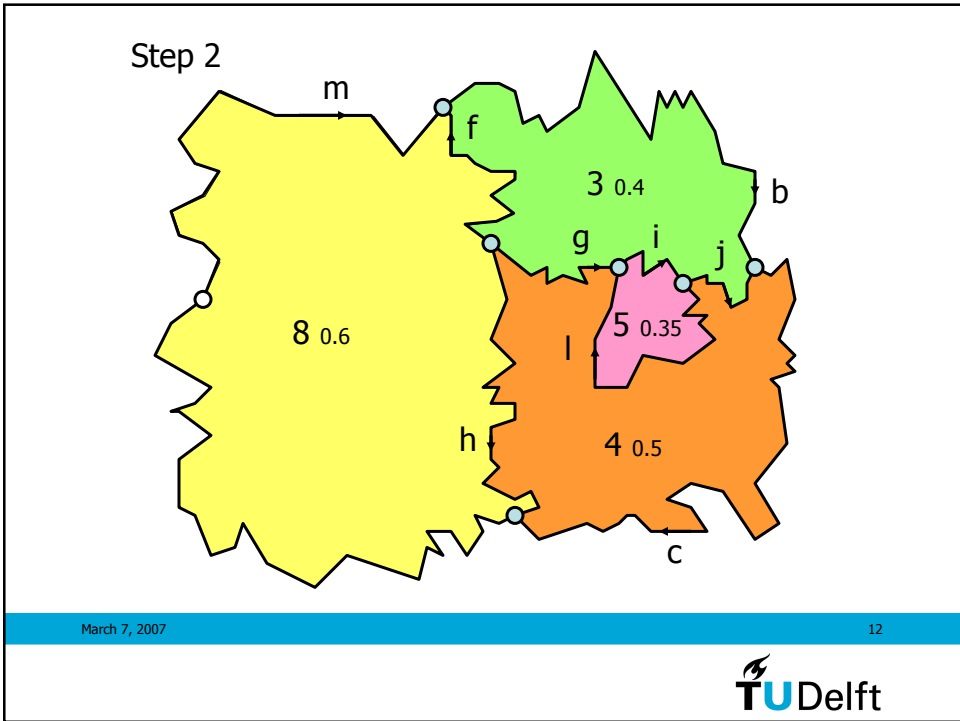
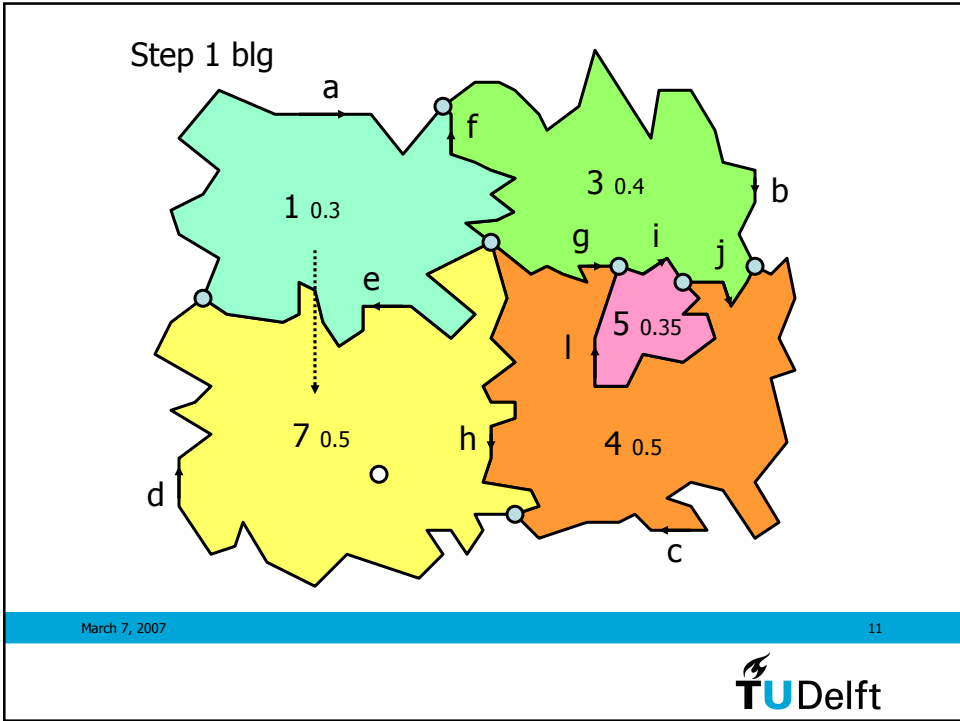
edges

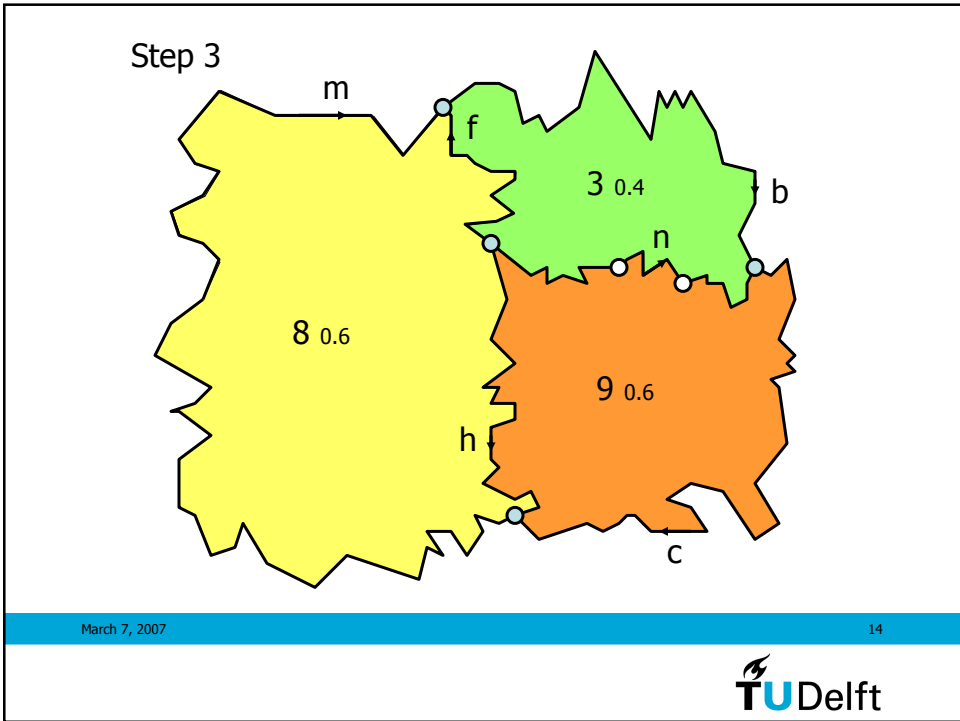
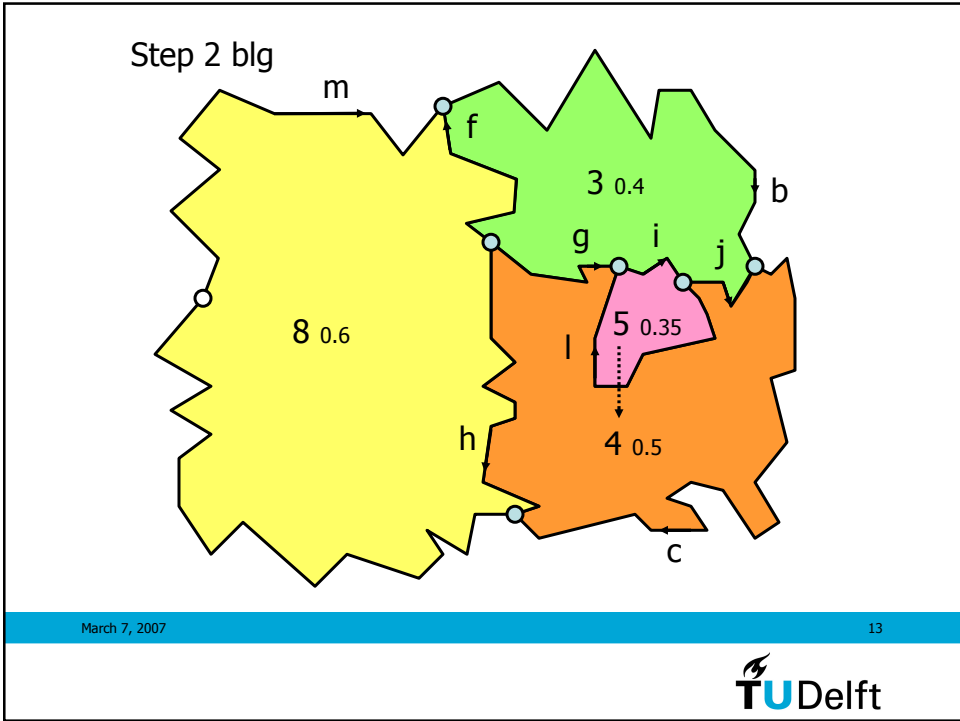


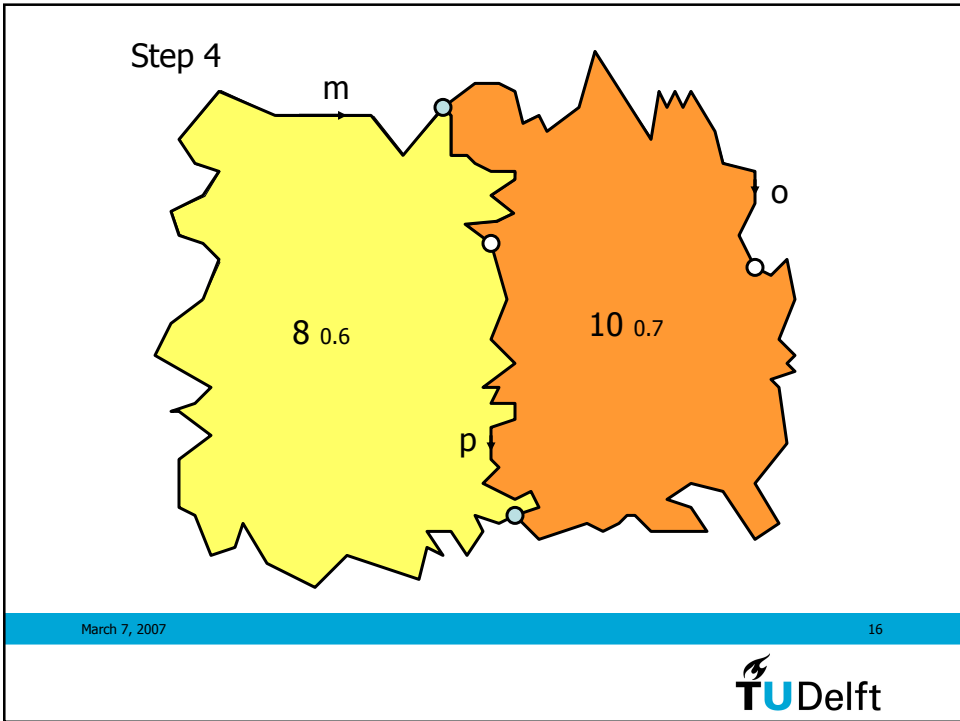
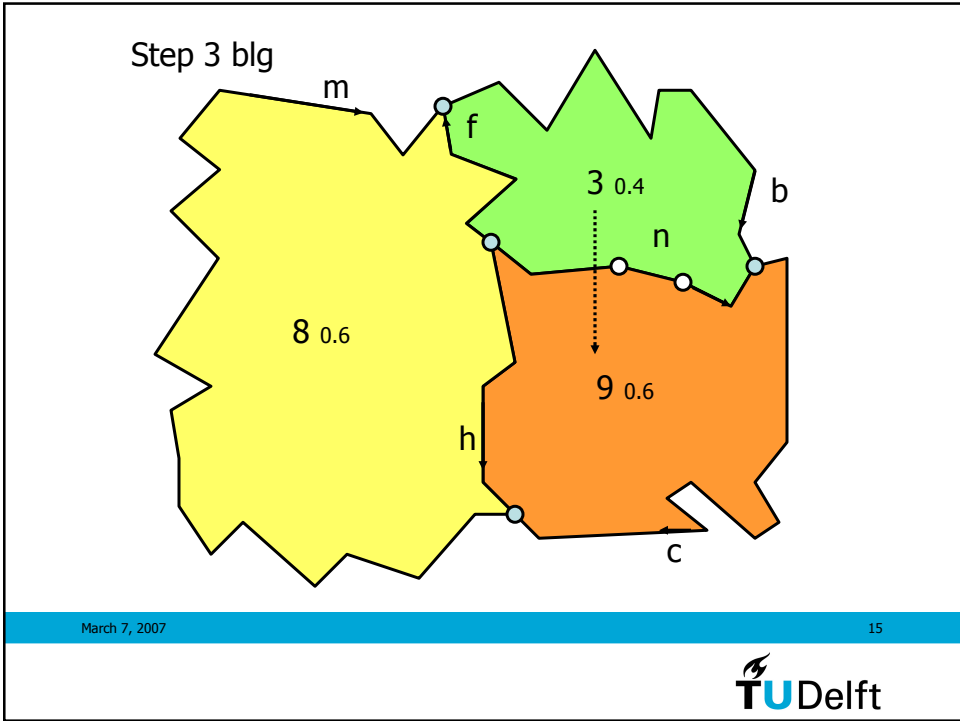
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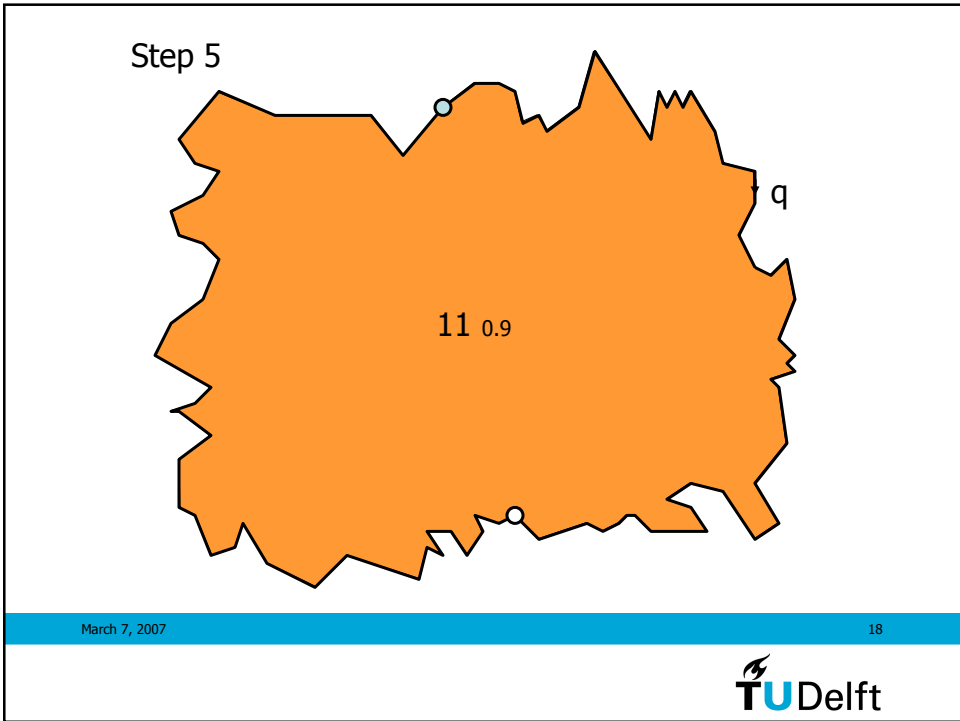
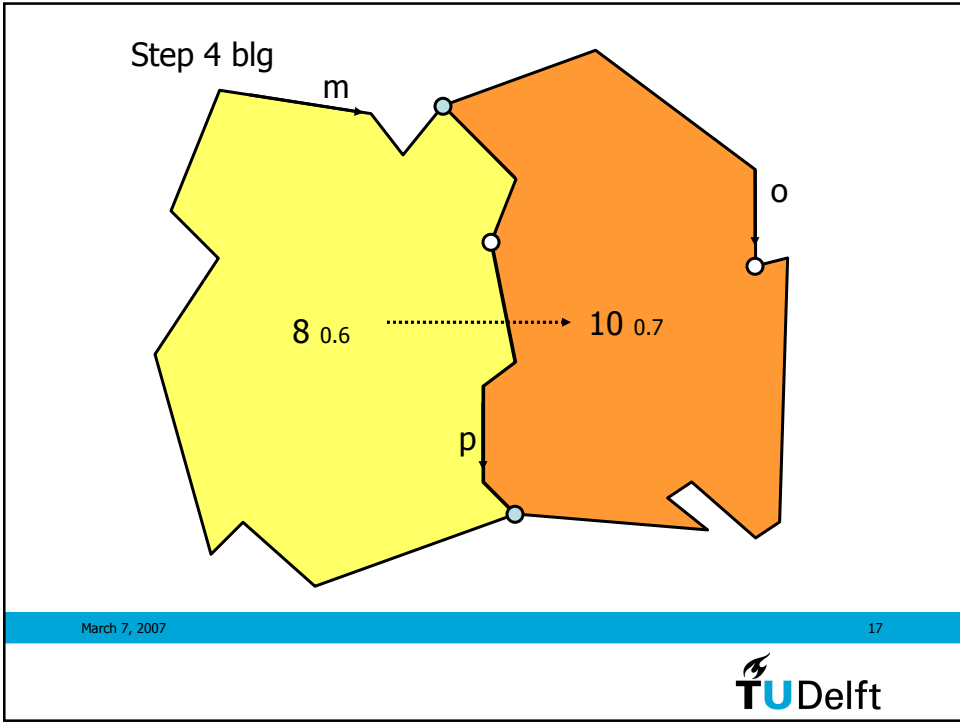
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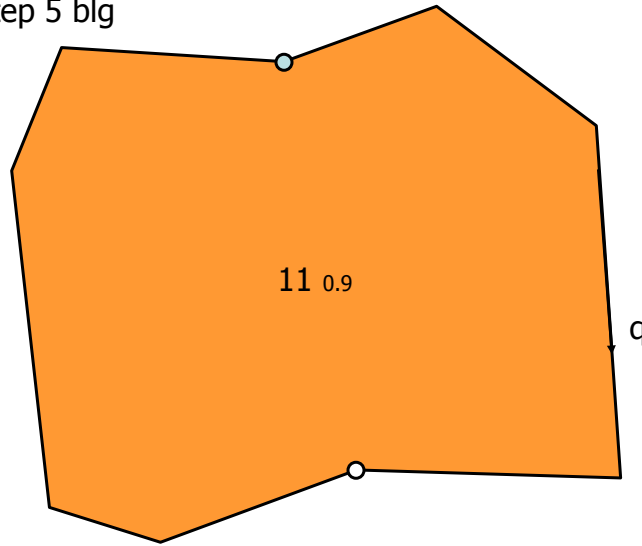








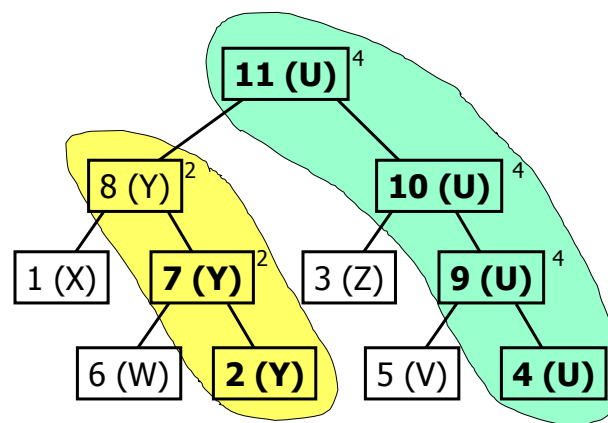
Step 5 blg



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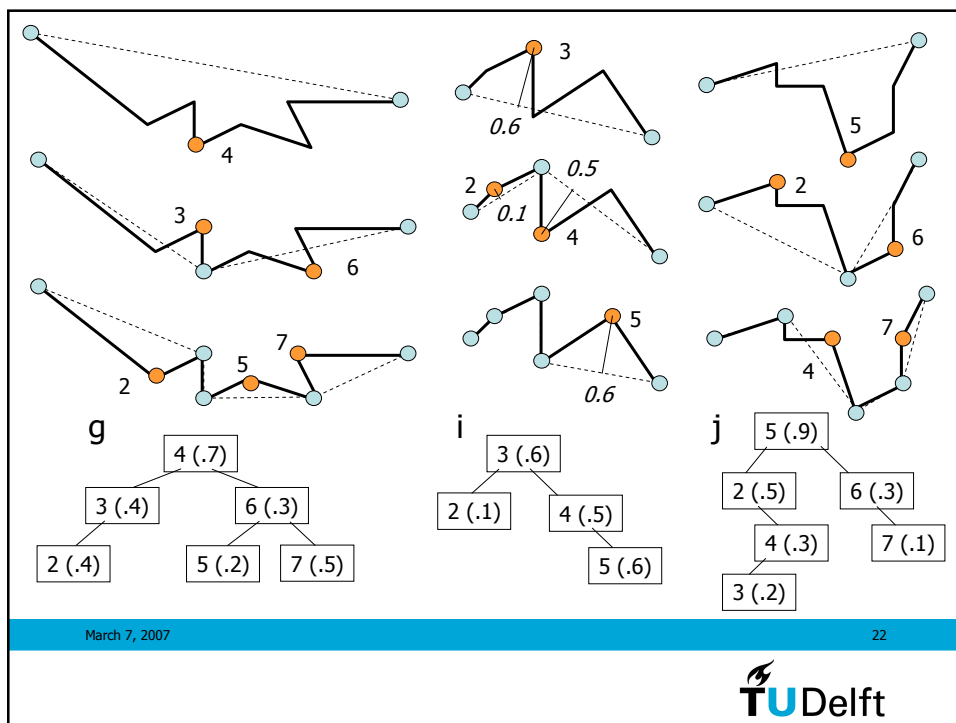
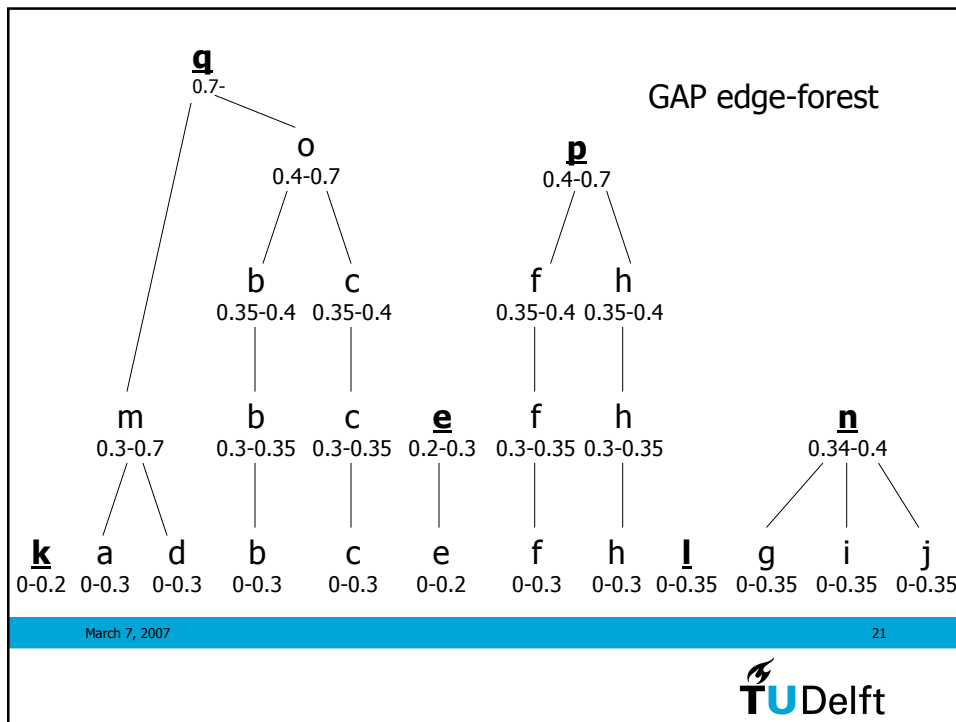
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GAP face-tree

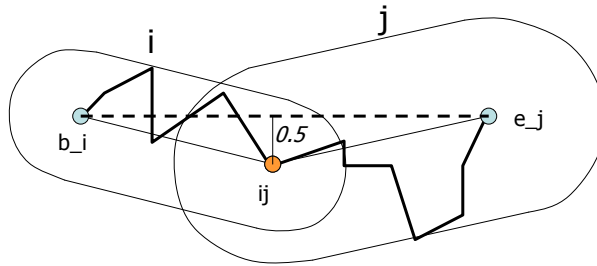


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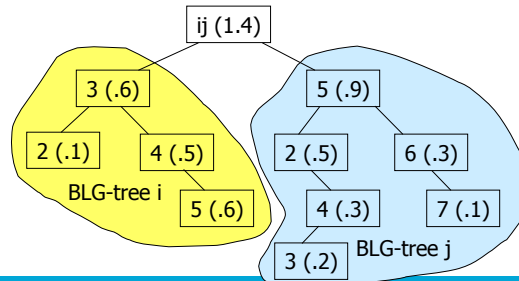


Join BLG-tree's
of edges i and j



$$\text{err}_{ij} = \text{dist}(\text{point}(ij), \text{line}(b_i, e_j)) \\ + \max(\text{err}_i, \text{err}_j) =$$

$$0.5 + 0.9 = 1.4$$



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3. First implementation

- Object-relational model
- Spatial data types available (incl. BLG-tree polyline)
- Tables for tgap_face, tgap_edge, and tgap_blg
- Heavy use of views (and functions) to avoid redundant storage, but to provide 'easy access'
- Functional index (3D R-tree: 2D box+imp range)

- Different from earlier 'theory'
 1. tgap_node table added (last redundancy+BLG-tree)
 2. No winged edge, only left/right refs (less storage)
 3. Signed references when merging BLG-trees

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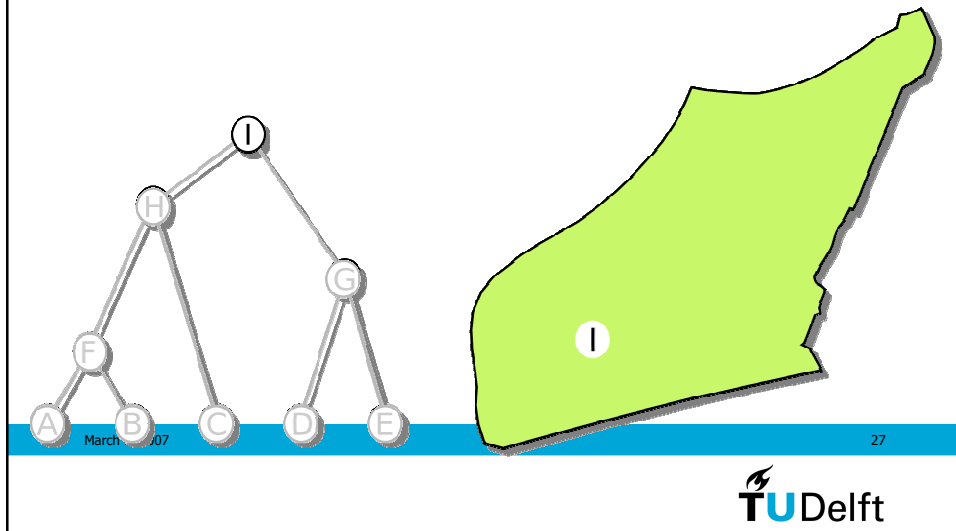
3: tGAP structure: combination of structures

- Uses topology
- Stores results of Generalization
- Suitable for Area Partitioning

GAP face tree	allow face selection
GAP edge forest	allow line selection
BLG tree	allow line simplification
3D R-tree	allow fast selection



3. Constructing GAP face tree



F 1

A+B A

ERROR: rangecheck
OFFENDING COMMAND: string

STACK:

66038
33018
32512
33019